

Released

K-Band Doppler Sensor Module

RF Frequency: 24.05 to 24.25 GHz

Model No. NJR4265R series

Frequency Line-up:

F1: 24.05 to 24.25 GHz / EU F2: 24.15 to 24.25 GHz / EU F3: 24.075 to 24.175 GHz / US J1: 24.05 to 24.25 GHz / JAPAN C1: Original Release

Software Version:

Specifications Rev.05e July 11, 2017

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24GHz Microwave Intelligent Motion Sensor for Short Distance, Low Speed Applications

NJR4265R is intelligent motion sensor that is designed for the sensing of short distance low speed movement object of pedestrian etc. The steady sensing of moving object is realized by embedded software. It is suitable for the built-in use of the sensing function to various equipment as all functions are integrated in a small package and it can easily control from PC/MCU by UART interface. Further, stand-alone operation is also possible.

Features:

- Motion sensor using the 24GHz Microwave Doppler
- Antenna, RF circuit, IF amp, MCU and voltage regulator are integrated in a small package (14 x 20.4 x 8.8mm)
- Communication with PC/MCU is available by UART interface and stand-alone operation is also possible
- Signal processing software for the steady sensing
 - Enhancing the signal from movement object and decreasing random noises
 - Decreasing the mutual interference between sensors
 - Identification of direction for movement object (approaching and leaving).
- Low voltage operation and low power consumption
- Sleep mode for reducing power when unnecessary

Applications:

- Various equipment control by human sensing
 - Energy saving management
 - Entrance and exit management
 - Safety and Security





Rev.05e July 11, 2017 NJR4265R

Products Line-up:

Model Numbering System



Model Number List

Model No.	RF Frequency	Software Version	Region	Certification	
NJR4265RF1C1	24.05 to 24.25 GHz (F1 type)		EU except specific regions (UK, Frence, etc)	EU/EC Radio Equipment Directive (RED)	
NJR4265RF2C1	24.15 to 24.25 GHz (F2 type)	Original	All of EU regions	2014/53/EU (CE Marking)	
NJR4265RF3C1 ^{*Note}	24.075 to 24.175 GHz (F3 type)	Release	US	FCC Part 15.245	
NJR4265RJ1C1	24.075 to 24.175 GHz (J1 type)		JAPAN	MIC Technical Conformity ARIB STD-T73	

*Note: The Model of FCC certification (Model No. NJR4265RF3C1) must refer to Appendix of "FCC Statement of NJR4265RF3".

• Evaluation Kit

The evaluation kit is available for NJR4265R series. The contents of the evaluation kit are as follows.

> Evaluation Kit P/N.: NJR4265J1K

Contents

- 1. Sensor Module
- 2. Evaluation Board (Functions are UART-to-USB convertor and analog threshold setting)
- 3. GUI Software
- 4. USB Cable



NJR4265R series

1. Absolute Maximum Rating

ITEM	MIN.	TYP.	MAX.	UNITS	REMARKS
Supply Voltage	0	—	6.5	V	
Operating Temperature	-40	—	+85	°C	
Storage Temperature	-40	—	+85	°C	

2. Electrical Characteristics

Common measure condition Ta= +25 °C

ITEM	MIN.	TYP.	MAX.	UNITS	REMARKS
Power Supply					
Operating Voltage	3.0	3.3/5.0	5.25	V	
Operating Current					
Sensing mode	-	60	_	mA	
Sleep mode		4	_	mA	
Sensor RF					
Conformity Standard	EU C	Certificatio	n: Radio E	quipment	Directive 2014/53/EU
	• FCC	Certificati	on: Part 1	5.245	
	• MIC	Technical	Conformit	y (Japan)	: ARIB STD-T73
Operating Frequency					
F1 type	24.05	_	24.25	GHz	EU Certification
F2 type	24.15	—	24.25	GHz	
F3 type	24.075	_	24.175	GHz	FCC Certification
J1 type	24.05	_	24.25	GHz	Japan Certification
Frequency Stability (Temp.)		+/-0.2	_	MHz/°C	Ta=-20 to +60 °C
Output Power (E.I.R.P.)	8.2	_	13	dBm	
2 nd Harmonics (E.I.R.P.)		_	-30	dBm	
Antenna					
-3dB beam width (Horizontal)	-	70	—	deg.	
-3dB beam width (Vertical)	-	54	—	deg.	
Side lobe suppression	-	—	—	dB	No Side lobe
(Horizontal)					
Side lobe suppression	_	_	_	dB	No Side lobe
(Vertical)					

Typical Radiation Pattern





3. Environmental characteristics

ITEM	SPECIFICATION
Operation Temperature	-20 to +60 °C
Storage Temperature	-40 to +80 °C
Humidity	0 to 95 % @+30 °C
Vibration	49.03 m/s ² (5 G), 30 to 50 Hz, 10 minutes, XYZ direction
Shock	196.13 m/s ² (20 G), Half sine, 11 ms, XYZ direction, 3 times

4. Sensing Performance

Common measure condition Ta= +25 °C

ITEM	PERFORMANCE	UNITS	REMARKS
Speed Range of Target	0.25 to 1.0	m/s	
Maximum Distance in Front	10	m	
Detectable Angle	+/-35	deg.	

*Note) This is not the specification to guarantee the performance of this product. As for the specification of the product, the electric characteristic standard is applied. Sensing performance shown here is an example of the result of being likely to obtain it when this product is used on the following conditions. Actual sensing performance would be greatly different in each environment used. Please do enough confirmation in the environment actually used.

Definition of Sensing Performance

* Speed Range of Target: The range of the speed that the detection distance become 70% of the detection distance of 0.5 m/s
* Maximum Distance in Front: Detectable distance that can be detected in front of sensor when a threshold value set to [999] or when VDD is added to a threshold setting terminal
* Detectable Angle: Angle where detection distance becomes 70% of the front

Measurement condition of detection performance

* Temperature:	Ta = +25 °C
* Target of Measurement:	An adult of 170cm/70kg approaching at the rate of 0.5m/s from the front of sensor
* Installation of the Sensor:	The sensor is installed as the antennas horizontal horizontally in a height of 1 m from the ground.





5. Signal processing for the steady sensing of moving object

This product is embedding software for the steady sensing of moving object. It is enhance the signal from movement object of pedestrian etc. and is reduce random noise and sudden signal which caused an incorrect detection by using the signal from IQ mixer, namely **Environmental Noise Reduction**.

The following effects are expectable.

- Reduction of false detection by random movement such as the shakes of plant by wind or the noise of rain etc.
- Reduction of the false detection by sudden movement such as the insect etc. which cross just before a sensor
- Steady detection of movement objects such as pedestrian under the environment where the above-mentioned noise exists.
- Reduction of the mutual interference of sensors
- Identification of direction of movement (approach and leaving)

*Note) This signal processing function assumes the following noises are reduced, and pedestrian's movement is emphasized. However, it is likely to become a counter productivity for a signal outside assumption.

6. Interface

6.1. Pin Assignment



Pin diagram (Bottom View)

#	NAME	I/O	DESCRIPTION
1	Option	_	Option Pin
			Option pin is not assigned at NJR4265R.
			Keep it in electrically open state
2	TxD (UART)	0	UART TxD
3	RxD (UART)	Ι	UART RxD
4	Threshold Setting	Ι	Analog threshold voltage (V_{TH})
			Available to set by the voltage applied to this pin.
			Threshold of detection distance = $V_{TH} / V_{DD} \times 10 \text{ m *Note1}$
5	Detect	0	Output for approaching detection *Note2
	(approaching)		H: Detect / L: No detect
6	Detect	0	Output for leaving detection *Note2
	(leaving)		H: Detect / L: No detect
7	VDD	Ι	Power Supply Input (V_{DD}): 3.0 to 5.25 V
8	—	_	Internal connection *Note3
9	—	_	DO NOT connect any signal lines including GND.
10	—	_	
11	GND	—	GND Pin

*Note1) Detection distance assumes the case that an adult of 170cm/70kg approaches at the rate of 0.5m/s from the front.

*Note2) Pin 5 or 6 is changed to H level respectively when the movements of approaching or leaving is detected. (Output current < 5mA)

*Note3) Pin 8, 9 and 10 are used for internal connection. Those must be electrically open independently. These pins must use the via holes of an independent pad when the sensor install on a PCB. Do not connect also between these terminals too.

6.2. Asynchronous Serial Data Bus (UART) Interface

NJR4265R is able to control of sensor mode, set of threshold level, acquisition of detection result and acquisition of various information of sensor states from PC or MCU, etc. by using UART Interface.

ITEM	FORMAT	UNITS	REMARKS
Signal Level	CMOS	—	Internally pulled-up by 10 Kohms
Communication Parameters			
Baud Rates	9600	bps	
Data Bits	8	bits	
Stop Bits	1	bits	
Parity	odd	—	
Handshake	non	—	
Byte Order	LSB	_	

7. Operational mode

MODE	DESCRIPTION				
Power ON / Reset	CPU Reset.				
Initialization Mode	Initialize and wait until sensor is stabilized.				
	Notice command is sent out after the completion of initialization.				
Detection Mode	Detection command is sent when following changes arise in the state of the				
	sensor detection.				
	1. detect approaching object				
	2. detect leaving object				
	3. state change from detection to no-detection				
Sleep Mode	Shutdown of all analog circuit for reducing the current.				
	When returning to detection mode, about one second needs for				
	stabilization of the sensor.				

*Note) When the watch dog timer overflows, it is reset from any mode



State Transition Diagram

State Transition Table

- The default detection mode at the Power-on or CPU reset is analog threshold mode. It is possible to change to the command threshold mode by sending parameter setting commands. (@SP, @SM and @SC)
- The @SA command is effective when changing from the command threshold to an analog threshold mode.
- When mode is changed to sleep mode or is resumed from sleep mode, the threshold mode is preserved. Moreover, the change of the threshold mode in sleep mode is also possible.

8. Communication command

8.1. Outline

COMMAND TYPE	DIRECTION	DESCRIPTION	EFFECTIVE MODE
Detection	Sensor to Host	Sending from sensor when movement	Detection mode
Mada Change	Heat to Canada	Change the senser mode	Data ati any manda
Mode Change	Host to Sensor	Change the sensor mode	Detection mode
Parameter Setting	Host to Sensor	Setting and change of threshold	Sleep mode
		parameters	
Query	Sensor to Host	Reading of state of sensor (mode ,	
	Host to Sensor	parameters)	
Reset	Host to Sensor	Reset of sensor	
Start Notification	Sensor to Host	Sending from sensor when initialization	Initialization
		is completed	mode
Error Response	Sensor to Host	Sending from sensor when error occurs	All mode

8.2. Communication Command List

Both Sensor-to-Host (S-to-H) and Host-to-sensor (H-to-S) use the following formats.

@ XXX xx <CR><LF>

@:	Command header
XXX :	Command characters, alphabet 1-3 characters. (Capital letter and small letter are Distinguished.)
xx :	Command/configuration parameters (numerical value or alphabet one character or "?".)
<cr><lf>:</lf></cr>	Delimiter (CR+LF)

CONTENTS/EFFECTS	XXX	DIRECTION	FORMAT	REMARKS	
Detection Commands					
Detected Approaching movement	С	S-to-H	@C <cr><lf></lf></cr>		
Detected Leaving movement	L	S-to-H	@L <cr><lf></lf></cr>		
Becomes undetected from detected	N	S-to-H	@N <cr><lf></lf></cr>		
Mode Change Commands					
Change to Detection mode	Т	H-to-S	@T <cr><lf></lf></cr>		
Change to Sleep mode	U	H-to-S	@U <cr><lf></lf></cr>		
Parameter Setting Commands					
Setting an Approaching threshold	SP	H-to-S	@SPxxx <cr><lf></lf></cr>		
Setting a Leaving threshold	SM	H-to-S	@SMxxx <cr><lf></lf></cr>		
Change to Analog threshold mode	SA	H-to-S	@SA <cr><lf></lf></cr>		
Change to Command threshold mode	SC	H-to-S	@SC <cr><lf></lf></cr>		
Query Commands					
Acquire the present detection	Q1	H-to-S	@Q1? <cr><lf></lf></cr>		
Response of present detection		S-to-H	@C <cr><lf></lf></cr>	Approaching	
			@L <cr><lf></lf></cr>	Leaving	
			@N <cr><lf></lf></cr>	No detection	
Acquire the present mode	Q2	H-to-S	@Q2? <cr><lf></lf></cr>		
Response of present mode		S-to-H	@T <cr><lf></lf></cr>	Detection mode	
			@U <cr><lf></lf></cr>	Sleep mode	

CONTENTS/EFFECTS	XXX	DIRECTION	FORMAT	REMARKS	
Acquire the present threshold mode	Q6	H-to-S	@Q6? <cr><lf></lf></cr>		
Response of present threshold mode		S-to-H	@SA <cr><lf></lf></cr>	Analog threshold	
			@SC <cr><lf></lf></cr>	Command threshold	
Acquire the Approaching threshold	SP	H-to-S	@SP? <cr><lf></lf></cr>		
Response of Approaching threshold		S-to-H	@SPxxx <cr><lf></lf></cr>	*Note1	
Acquire the Leaving threshold	SM	H-to-S	@SM? <cr><lf></lf></cr>		
Response of Leaving threshold		S-to-H	@SMxxx <cr><lf></lf></cr>	*Note1	
Acquire the Analog threshold	SV	H-to-S	@SV? <cr><lf></lf></cr>		
Response Analog threshold		S-to-H	@SVxxxx <cr><lf></lf></cr>	Value of ADC	
Acquire the software version	V	H-to-S	@V? <cr><lf></lf></cr>		
Response of software version		S-to-H	@Vx.xx <cr><lf></lf></cr>	x.xx: Version	
Reset Command, Start Notification Command					
Reset Command	R	H-to-S	@R <cr><lf></lf></cr>		
Start Notification	W	S-to-H	@W <cr><lf></lf></cr>		
Error Response Commands					
Notification of UART framing error	EF	S-to-H	@EF <cr><lf></lf></cr>		
Notification of UART parity error	EP	S-to-H	@EP <cr><lf></lf></cr>		
Notification of Communication error	ER	S-to-H	@EP <cr><lf></lf></cr>		
Notification of Self-test	ES	S-to-H	@ER <cr><lf></lf></cr>		
Notification of watch dog timer error	EW	S-to-H	@EW <cr><lf></lf></cr>		
*Note1) Capable threshold setting range is Integer 1-999.					

The relation between the threshold value and the detection distance (*Note2) can be shown by the following expressions:

Da =SP/100, [Da] is approaching detection distance (units: m)

DI = SM/100, [DI] is leaving detection distance (units: m)

*Note2) Detection distance assumes the case that an adult of 170cm/70kg approaches at the rate of 0.5m/s from the front.

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9. Drawing

9.1. Outline



Recommended diameter of via hole: φ 0.75

9.2. Label

NJR4265RF1C1	NJR4265RF2C1	NJR4265RF3C1	NJR4265RJ1C1
NJ R4265RF1C1 A00001A New Japan Radio Co., Ltd.	NJR4265RF2C1 A00001A New Japan Radio Co., Ltd.	Image: Constraint of the second sec	NJR4265R_J1 A000001A 见001- A06676 区 ROHS 新日本無線株式会社

unit: mm tolerance: +/-0.5

10. Package

Standard Package

Packing Quantity: 500 pieces per shipping box



⑦Package label.

11. Reference Circuit

11.1. Example of connecting with MCU



11.2. Example of using it by stand-alone



12. Recommendation Mounting Conditions

12.1. Footprint dimensions



*Note) In actual design, please optimize in accordance with the situation of your board design and soldering condition.

12.2. Soldering conditions

- Soldering way: Solder iron *Note
- Solder iron temperature: 350 °C or less
- Mounting time: 3 second or less per pin

*Note) The soldering iron to be used must be grounded via a resistance of about 1 $\mbox{M}\Omega.$



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FCC Statement of NJR4265RF3

Responsible party:

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Tel: +81-49-278-1271, Fax: +81-49-278-1234

This device complies with Part 15 of the FCC rules. Operation is a subject to the following two conditions:

- (1) This device may not cause harmful interference.
- (2) This device must accept any interference received, including interference that may cause undesired operation.

Caution

DC power supply for each module should be conformed to the electrical specifications as described in this section. A host in which a module is integrated should provide stable DC power through suitable regulator circuit to the module.

NOTE :

Changes or modifications to the device not expressly approved by the party responsible for compliance could void the user's authority to operate the equipment(s).

This equipment has been tested and found to comply with the limits for a Class B digitaldevice, pursuant to part 15 of the FCC Rules. These limits are designed to provide reasonable protection against harmful interference in a residential installation. This equipment generates, uses and can radiateradio frequency energy and, if not installed and used in accordance with the instructions, may cause harmful interference to radio communications. However, there is no guarantee that interference will not occur in a particular installation. If this equipment does cause harmful interference to radio or television reception, which can be determined by turning the equipment off and on, the user is encouraged to try to correct the interference by one or more of the following measures:

- Reorient or relocate the receiving antenna.

- Increase the separation between the equipment and receiver.

- Connect the equipment into an outlet on a circuit different from that to which the receiver is connected.

- Consult the dealer or an experienced radio/TV technician for help. The equipment complies with radio frequency exposure limits set forth by the FCC for an uncontrolled environment.

The device must not be co-located or operating in conjunction with any other antenna or transmitter.

Appendix)

WARNING:

The FCC regulations provide that changes or modifications not expressly approved by the party responsible for compliance could void the user's authority to operate the equipment.

Limitation for use of the modules:

When the module is installed in a host product, the module shall be connected directly to a PCB of the host product. It shall NOT be extended by any cable. DC power supply for each module must strictly be conformed to each electrical specification as described in the section 1 of this document.

Manual and Product Labeling information to the End User:

End user manual must include all required regulatory information and/or warning as show in this manual.

OEM Integrator must indicate "<u>Contain FCC ID: 2ACUJR4265</u>" at the outside of a host product such as label when the module is installed in the host product.

This device complies with Part 15 of the FCC Rules. Operation is subject to the following two conditions:

- (1) this device may not cause harmful interference, and
- (2) this device must accept any interference received, including interference that may cause undesired operation.

OEM Integrator may be sure that the End user manual may not contain any information about the way to install or remove the modules from the host product.

APPLICABLE MODEL:

This FCC Statement is valid only for the following model number: NJR4265RF3C1

FCC Statement of NJR4265RF3 rev1.0

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