

Part Number*	Relay Description
KD00CK	5A Solid-State Relay (SSR)
KD02CK	5A SSR with Switch Status
KD20CK	5A SSR with Short-Circuit Protection
KD22CK	5A SSR with Short-Circuit Protection and Switch Status
LD00CM	10A Solid-State Relay
LD02CM	10A SSR with Switch Status
LD20CM	10A SSR with Short-Circuit Protection
LD22CM	10A SSR with Short-Circuit Protection and Switch Status

\* The Y suffix denotes parameters tested to MIL-PRF-28750 specifications. The W suffix denotes parameters tested to Teledyne specifications.

### ELECTRICAL SPECIFICATIONS

(-55°C TO +105°C UNLESS OTHERWISE NOTED)

#### INPUT (CONTROL) SPECIFICATION

When used in 2 terminal configuration

(TTL or direct control) (See Fig. 1)	Min	Typ	Max	Units
Input Current @ $V_{BIAS} = 5$ Vdc (See Fig. 2)			15	mAdc
Turn-Off Voltage (Guaranteed Off)			1.5	Vdc
Turn-On Voltage (Guaranteed On)	3.8			Vdc
Reverse Voltage Protection			-32	Vdc
Input Supply Range (See Note 1)	3.8		32	Vdc

#### INPUT (CONTROL) SPECIFICATION

When used in 3 terminal configuration

(CMOS or open collector TTL) (See Fig. 1)	Min	Typ	Max	Units
Control Current				
$V_{CONTROL} = 5$ Vdc			250	$\mu$ Adc
$V_{CONTROL} = 18$ Vdc			1	mAdc
Control Voltage Range	0		18	Vdc
Bias Supply Voltage (See Note 1)	3.8		32	Vdc
Bias Supply Current			16	mAdc
Turn-Off Voltage (Guaranteed Off)	3.2			Vdc
Turn-On Voltage (Guaranteed On)			0.3	Vdc



### FEATURES

- Available with short-circuit/current overload protection
- Available with switch status output
- TTL and CMOS compatible control
- Low ON resistance power FET output
- Fast switching speed
- Meets 28 Vdc system requirements of MIL-STD-704
- Optical isolation
- Low profile hermetic package
- Built and tested to the requirements of MIL-PRF-28750

### DESCRIPTION

The Series KD and LD solid-state relays are screened utilizing MIL-PRF-28750 test methods and are packaged in low profile hermetically sealed cases. These relays are constructed with state-of-the-art solid state techniques and feature fully floating power FET output technology. This allows the load to be connected to either output terminal and provides a low ON resistance. The input (control) and output are optically isolated to protect input logic circuits from output transients. Available options include short circuit and current overload protection, which provides complete protection for both the relay and system wiring. This feature not only provides protection should a short or overload occur while the relay is on, but will also provide protection should the relay be switched into a short. The second option is a status output line. Switch status returns the true status of the output switch and is optically isolated from the load. It provides status indication independent of the control circuit of the relay. The status line provides a logic 0 (low) when the relay output is off with load voltage and continuity present, and a logic 1 (high) when the output is on.



**ENVIRONMENTAL SPECIFICATIONS**

	Min	Typ	Max	Units
Temperature Range				
Operating	-55		+105	°C
Storage	-55		+125	°C
Vibration 100 g	10		3000	Hz
Constant Acceleration			5000	g
Shock 0.5 ms pulse			1500	g

**STATUS OUTPUT TRUTH TABLE  
(KD02CK, LD02CM, KD22CK, LD22CM)**

Control Voltage	Relay Output	State Status Output Level
High	Off	Low ( $V_{SO} \leq 0.4 \text{ Vdc}$ )
Low	On	High ( $V_{SO} = V_{STATUS}$ )

**STATUS OUTPUT SPECIFICATIONS  
(KD02CK, LD02CM, KD22CK, LD22CM)**

	Min	Typ	Max	Units
Status Supply Voltage			30	Vdc
Status Leakage Current				
@16Vdc			10	µAdc
@30Vdc			100	µAdc
Status (sink) Current ( $V_{SO} < 0.4 \text{ Vdc}$ )			600	µAdc
Status Turn-On Time (See Fig. 6)			3.5	ms
Status Turn-Off Time (See Fig. 6)			8.0	ms



**BIAS (INPUT) CURRENT VS BIAS (INPUT) VOLTAGE  
FIGURE 2 (See Note 1)**



**(A) 3 TERMINAL INPUT WITH STATUS (See Note 5)**



**(B) 2 TERMINAL INPUT (OPEN COLLECTOR TTL DRIVE)**



**(C) 2 TERMINAL INPUT (DIRECT DRIVE) WITH STATUS**



**(D) 2 TERMINAL INPUT (DIRECT DRIVE)**



1/ KD02CK, KD22CK, LD02CM and LD22CM may be wired without the status line as shown in (B), (D) and (E) above.

**(E) 3 TERMINAL INPUT WITHOUT STATUS**

**WIRING CONFIGURATIONS  
FIGURE 1 (See Note 1)**



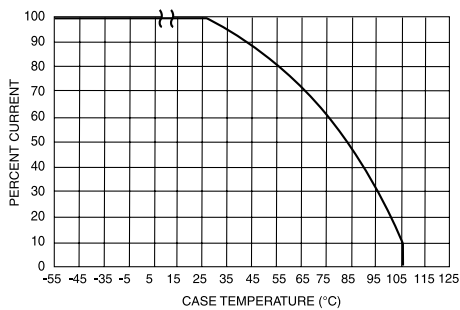
**LOAD CURRENT DERATING CURVE FOR KD/LD SERIES WITHOUT A HEAT SINK**  
**(A)**



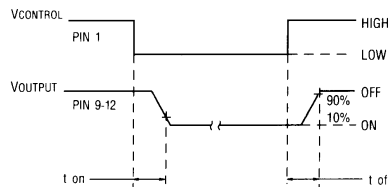
**NORMALIZED ON RESISTANCE VS JUNCTION TEMPERATURE**  
**FIGURE 4 (See Note 3)**



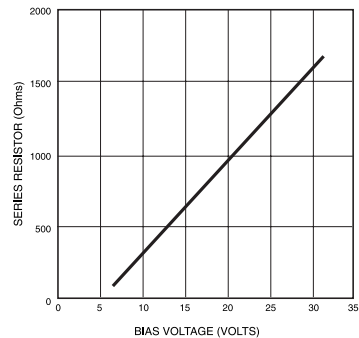
**OVERLOAD CURRENT VS TIME TO TRIP (TYPICAL)**  
**KD20CK, KD22CK, LD20CM, LD22CM**  
**FIGURE 7**



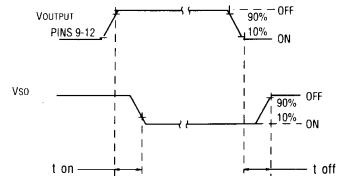
**LOAD CURRENT DERATING CURVE FOR LD SERIES**  
**(B)**



**OUTPUT TURN-ON AND TURN-OFF TIMING**  
**FIGURE 5**



**SERIES LIMIT BIAS RESISTOR VS BIAS VOLTAGE**  
**FIGURE 8 (See Note 1)**



**STATUS TURN-ON AND TURN-OFF TIMING**  
**FIGURE 6**

**NOTES:**

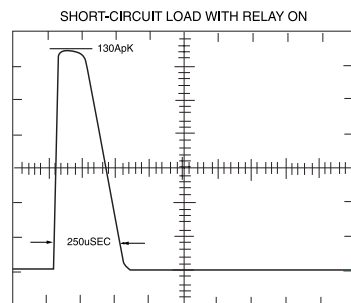
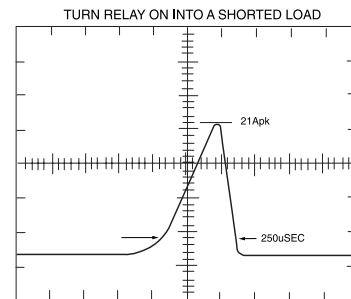
- Control input is compatible with CMOS or open collector TTL (with pull up resistor). For bias voltages above 6V, a series resistor is required. Use the standard resistor value equal to or less than the value found in Figure 8.
- The rated input voltage is 5V for all tests unless otherwise specified.
- To calculate the maximum ON resistance for a given junction temperature, find the normalized ON resistance factor (NR) from Figure 4. Calculate the new ON resistance as follows:  

$$R_{(ON)} = NR \cdot R_{ON} @ 25^{\circ}C$$
 (KD00CK, LD00CM, KD02CK, LD02CM)  

$$R_{(ON)} = NR(R_{ON} @ +25^{\circ}C) + .025 \text{ ohm}$$
 (KD20CK, LD20CM, KD22CK, LD22CM)
- Overload testing to the requirements of MIL-PRF-28750 is constrained to the limits imposed by the short circuit protection characteristics as defined in this specification. System series inductance for "shorted-load" mode of operation should be 50 μH. Maximum repetition rate into a shorted load should not exceed 10 Hz.
- A status pull up resistor is required for proper operation of the status output. Determine the current (I<sub>so</sub>) required by the status interface. Calculate the current (I<sub>s</sub>) through the status resistor such that the sink current through the status output is 0.6 mA. Select the status resistor such that it does not allow more than 0.6 mA to flow through the status output.

$$R_{STATUS} = \frac{V_{STATUS} - 0.4V}{I_{so}}$$

- Inductive loads should be diode suppressed. Input transitions should be ≤1 ms duration and the input drive should be a bounceless contact type.



**TYPICAL TRIP CURRENT CHARACTERISTICS FOR SHORT CIRCUIT CONDITIONS**  
**FIGURE 9**