



**DLP-IO20** 

**LEAD-FREE** 

# **USB-Based 20-Channel Data-Acquisition Module**

## **FEATURES:**

- 20 Channels: 14 Analog Inputs 0-5V, Up to 20Ksps Sample Rate, 2 Latching Relays, Digital I/O
- Two Relay Driver Outputs (5V Coil)
- Digital Temperature Sensor Feature Supported on All Digital I/O's
- Two 32-Bit Interrupt-Driven Event Counters
- USB Port Powered
- USB 1.1- and 2.0-Compatible Interface
- Small Footprint; Easily Fits On a Desktop
- Easy-To-Use Programming Interface

## **APPLICATIONS:**

- Robotics Control
- Motion Control/Presentation
- Data Acquisition
- Industrial/Process Control
- Process Monitoring
- Relay Control
- Audio Analysis

#### 1.0 INTRODUCTION

The DLP-IO20 Data-Acquisition Module is a low-cost, easy-to-use data-acquisition system for analyzing AC voltages, driving 5-volt relays, controlling and monitoring processes and measuring DC voltages in the range of 0-5 volts. This module provides topside wire terminal blocks for the wiring connections.

The 20 channels on the DLP-IO20 are broken down as follows: 3 outputs with high current relay/LED drivers and 17 digital I/O; 14 of which can be set to analog input mode. The DLP-IO20 also provides two latching relay contacts. Each of the channels and relay contacts can be controlled via simple, multi-byte commands. All operational power is taken from the host PC via the USB port.

The mode of each I/O is automatically changed with each command sent. For example, if an I/O is set to Digital Output-High and then the Digital Input Mode is selected, the I/O is first changed to Input Mode and then the high/low state is read and returned to the host.

#### 2.0 SPECIFICATIONS

The DLP-IO20 is an all 5-volt system that derives its power from the host USB port. Channels have the following capabilities:

<u>Relay Contacts</u>: There are two sets of relay contacts on the board. These contacts are latching and have the following characteristics:

Contact Ratings: 60W, 125VA

Max Switching Voltage: 220VDC, 250 VAC

Max Switching Current: 2A Max Carrying Current: 2A

Each of the two on-board relays has two sets of SPDT contacts that have been connected in parallel to increase the current carrying capability. (These are detailed in Section 6 under the table describing K1 and K2.)

<u>Relay Drivers</u>: There are three relay driver outputs on the board. These outputs connect to one side of a 5V relay coil, and the side of the coil is connected to the +5V terminal.

<u>Analog In</u>: Fourteen inputs can read and return the voltage on the analog inputs using a 10-bit ADC. The maximum sample rate is 20Ksps. The input voltage range is 0-5 Volts. (Refer to Section 7 of this document for more details.)

<u>Digital Output</u>: Set high, or clear low; configurable as digital outputs (5V). (The actual high/low voltage depends upon sink/source current.)

Digital Input: Read the input's high/low state.

#### 3.0 ABSOLUTE MAXIMUM RATINGS

Stresses beyond the ranges listed below may cause permanent damage to the DLP-IO20:

Operating Temperature: 0-70°C

Voltage on Digital Inputs with Respect to Ground: -0.3V to +5.3V

Voltage on Analog Inputs with Respect to Ground: -0.3V to +5.3V

Voltage on Relay Contacts with Respect to Ground/Return: 110VDC, 125VAC

Sink/Source Current on Any I/O: 25mA

Sink/Source Current on All I/O Combined: 90mA

#### 4.0 WARNINGS

- Unplug from the host PC before connecting to the I/O terminals on the DLP-IO20.
- Isolate the bottom of the board from all conductive surfaces.
- Observe static precautions to prevent damage to the DLP-IO20 module.

#### 5.0 USB DRIVERS

USB drivers for the following operating systems are available for download from the DLP Design website:

Windows XP x64	Mac OSX
Windows Server 2003	Mac OS9
Windows 2000	Mac OS8
Windows 98, ME	Linux

These drivers are available for download from the following page: <a href="http://www.dlpdesign.com/DNLD8/">http://www.dlpdesign.com/DNLD8/</a>.

Note: If you are utilizing the dual-mode drivers from FTDI (CDM2.x.x) and you want to use the Virtual COM Port (VCP) drivers, then it may be necessary to disable the D2XX drivers first via Device Manager. To do so, right click on the entry under USB Controllers that appears when the DLP-IO20 is connected, select Properties, select the Advanced tab, put a check in the option for "Load VCP" and click OK. Then unplug and replug the DLP-IO20, and a COM port should appear in Device Manager under Ports (COM & LPT).

#### 6.0 TERMINAL BLOCK PIN DEFINITIONS

The wiring terminals on the DLP-IO20 are explained in the following table:

TABLE 1					
J1 Prototyping Terminal Block Pin Definitions					
PIN NAME	DESCRIPTION				
R1	Latching Relay 1 Reset Contact (see Note 3)				
C1	Latching Relay 1 Common Contact (see Note 3)				
S1	Latching Relay 1 Set Contact (see Note 3)				
GND	Ground				
P7	Relay Driver Output P7. Driven by Darlington pair transistors powered by 5V from the USB port (see Note 4).				
P6	Relay Driver Output P6. Driven by Darlington pair transistors powered by 5V from the USB port (see Note 4).				
P5	Relay Driver Output P5. Driven by Darlington pair transistors powered by 5V from the USB port (see Note 4).				
+5V	VCC Output +5.0V. Limit current drawn from this pin to 100mA to avoid exceeding the available current from the host USB port.				
AN7	Analog Input AN7. Input voltage range is 0 to +5V (see Note 1). Digital I/O AN7; configurable as a digital input, a digital output (5V) or an open-drain output (5V max pullup) (see Note 2).				
AN6	Analog Input AN6. Input voltage range is 0 to +5V (see Note 1). Digital I/O AN6; configurable as a digital input, a digital output (5V) or an open-drain output (5V max pullup) (see Note 2).				

AN5	Analog Input AN5. Input voltage range is 0 to +5V (see Note 1). Digital I/O AN5; configurable as a digital input, a digital output (5V) or an open-drain output (5V max pullup) (see Note 2).
AN4	Analog Input AN4. Input voltage range is 0 to +5V (see Note 1). Digital I/O AN4; configurable as a digital input, a digital output (5V) or an open-drain output (5V max pullup) (see Note 2).
RA4	Digital I/O RA4; configurable as a digital input, a digital output (5V) or an open-drain output (5V max pullup) (see Note 2).

AN3	Analog Input AN3. Input voltage range is 0 to +5V (see Note 1). Digital I/O AN3;
	configurable as a digital input, a digital output (5V) or an open-drain output (5V max
	pullup) (see Note 2).
GND	Ground
AN12	Analog Input AN12. Input voltage range is 0 to +5V (see Note 1). Digital I/O AN12;
	configurable as a digital input, a digital output (5V) or an open-drain output (5V max
	pullup) (see Note 2).
AN10	Analog Input AN10. Input voltage range is 0 to +5V (see Note 1). Digital I/O AN10;
	configurable as a digital input, a digital output (5V) or an open-drain output (5V max
	pullup) (see Note 2).
AN8	Analog Input AN8. Input voltage range is 0 to +5V (see Note 1). Digital I/O AN8;
	configurable as a digital input, a digital output (5V) or an open-drain output (5V max
	pullup) (see Note 2).
AN9	Analog Input AN9. Input voltage range is 0 to +5V (see Note 1). Digital I/O AN9;
	configurable as a digital input, a digital output (5V) or an open-drain output (5V max
A N 14 4	pullup) (see Note 2).
AN11	Analog Input AN11. Input voltage range is 0 to +5V (see Note 1). Digital I/O AN11;
	configurable as a digital input, a digital output (5V) or an open-drain output (5V max
AN13	pullup) (see Note 2).  Analog Input AN13. Input voltage range is 0 to +5V (see Note 1). Digital I/O AN13;
ANIS	configurable as a digital input, a digital output (5V) or an open-drain output (5V max
	pullup) (see Note 2).
RB6	Digital I/O RB6; configurable as a digital input, a digital output (5V) or an open-drain
INDO	output (5V max pullup) (see Note 2).
RB7	Digital I/O RB7; configurable as a digital input, a digital output (5V) or an open-drain
	output (5V max pullup) (see Note 2).
AN0	Analog Input AN0. Input voltage range is 0 to +5V (see Note 1). Digital I/O AN0;
	configurable as a digital input, a digital output (5V) or an open-drain output (5V max
	pullup) (see Note 2).
AN1	Analog Input AN1. Input voltage range is 0 to +5V (see Note 1). Digital I/O AN1;
	configurable as a digital input, a digital output (5V) or an open-drain output (5V max
	pullup) (see Note 2).
AN2	Analog Input AN2. Input voltage range is 0 to +5V (see Note 1). Digital I/O AN2;
	configurable as a digital input, a digital output (5V) or an open-drain output (5V max
	pullup) (see Note 2).
GND	Ground
S2	Latching Relay 2 Set Contact (see Note 3)
C2	Latching Relay 2 Common Contact (see Note 3)
R2	Latching Relay 2 Reset Contact (see Note 3)

#### Notes:

- 1. The Analog Input Range is 0-5V. The maximum sample rate is 20Ksps. Refer to Section 7 for more details.
- 2. Digital outputs can sink or source 25mA; 90mA for all combined. Open-drain outputs are implemented by making the I/O pin an input. The maximum pullup voltage is 5.3 volts.
- Relay contacts can support resistive loads of up 60 watts (125VA). If this value is exceeded, the DLP-IO20 can be damaged. The relay is set and reset under software control. For a functional schematic of the relay connections, refer to Figure 8.

4. The DLP-IO20 uses a single-package multi-device driver (ULN2003APW). If only one of the driver channels is being used, it can provide a peak current of 300mA at a 100% duty cycle; but if all three channels are being used, they can only provide a peak current of 100mA each at a 100% duty cycle. The 5V power source provided by the host USB interface has limited power. For this reason the amount of current drawn by the relay drivers MUST be limited to 300mA or there may not be enough current available to power the board, and the PC's USB port could be damaged.

#### 7.0 RELAY FUNCTIONAL SCHEMATIC

The DLP-IO20 contains two latching relays. These are controlled by host software. The relay contacts R1, S1, C1, R2, S2 and C2 are described in Table 1. A functional view of how one of the relays works is shown here:

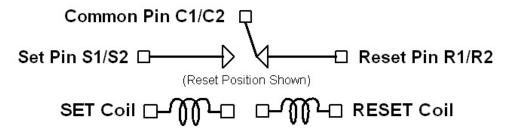


Figure 1: Relay Functional Schematic

<u>Note</u>: On power-up of the DLP-IO20, the relay states will be unknown. Each can power up in either the set or reset state. If a known initial state is required, the user will need to issue either a set or reset command upon power-up.

#### 8.0 USING THE DLP-IO20

Simply connect the DLP-IO20 to the PC to initiate the loading of USB drivers. Once the USB drivers are loaded, the DLP-IO20 is ready for use. All commands are issued as multi-byte command packets consisting of at least two bytes.

# **Packet Structure**

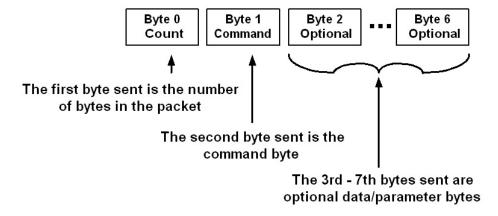


Figure 2: Multi-Byte Command Packets

You can either utilize the TestApp program provided with the DLP-IO20 (as described in Section 8), or you can write your own program in your language of choice. Begin by opening the COM port, and send multi-byte commands as shown in Table 2 below. There is no need to set the baud rate because the DLP-IO20 uses a parallel interface between the USB IC and the microcontroller. (The Ping command can be used to locate the correct COM port used for communicating with the DLP-IO20, or you can look in Device Manager to see which port was assigned by Windows.)

TABLE 2					
	Command Packets				
Command			Hex		
Packet	Description	Byte	Value	Return/Comments	
Ping	Issue Ping	0	0x02	2-Byte Packet	
		1	0x27	Y (0x59) will be returned if the DLP-IO20 is found on the	
				selected port	
Flash LED	Flashes the	0	0x02	2-Byte Packet	
	D1 LED	1	0x28	Nothing Returned	
LED	Turn the D1	0	0x03	3-Byte Packet	
Control	Control LED On/Off	1	0x29	LED Control Command	
		2	0x00	LED D1 port pin set Low (0) turns LED on	
			0x01	LED D1 port pin set High (1) turns LED off	
				Nothing Returned	
Relay	Set/Reset	0	0x04	4-Byte Packet	
Control	Relays	1	0x30	Relay Control Command	
		2	0x01	Select Relay 1	
			0x02	Select Relay 2	
		3	0x00	Set Relay	
			0x01	Reset Relay	
				Nothing Returned	

Digital I/O	Control	0	0x05	5-Byte Packet
Command	Direction	1	0x35	Digital I/O Command
Command	and Output	2	0x00	Select Channel AN0
	Value on		0x00	Select Channel AN1
	Digital I/O		0x01	Select Channel AN2
	Digital 1/0		0x02	Select Channel AN3
			0x04	Select Channel AN4
			0x04 0x05	Select Channel AN5
			0x05	Select Channel AN6
			0x07	Select Channel AN7
			0x07	Select Channel AN8
			0x09	Select Channel AN9
			0x0A	Select Channel AN10
			0x0B	Select Channel AN11
			0x0C	Select Channel AN12
			0x0D	Select Channel AN13
			0x0E	Select Channel RA4
			0x0F	Select Channel P5
			0x10	Select Channel P6
			0x10	Select Channel P7
			0x11	Select Channel RB7
			0x12	Select Channel RB6
		3	0x10	Channel Configured as Digital Output
		3	0x00	Channel Configured as Digital Output  Channel Configured as Digital Input
		4	0x00	Digital Output Set Low (0)
		4	0x00	Digital Output Set Low (0) Digital Output Set High (1)
			UXUI	Digital Output Set Flight (1)
				Note: Byte 4 is only used in output mode but must be
				included in all Digital IO Command Packets. When
				Byte 3 is set for input (0x01), a single byte is returned.
Enable/	Enable and	0	0x04	4-Byte Packet
Clear Event	Clear Event	1	0x36	Enable and Clear Event Counter Command
Counter	Counter on	2	0x06	Channel RB6
Command	Channels		0x00	Channel RB7
Command	RB6 and	3	0x00	Trigger Event Count on Falling Edge
	RB7	3	0x00	
	ND7		UXUT	Trigger Event Count on Rising Edge
				Nothing Returned
Read Event	Read Event	0	0x03	3-Byte Packet
Counter	Counter on	1	0x37	Read Event Counter Command
Command	Channels	2	0x06	Channel D6
	RB6 and		0x07	Channel D7
	RB7			
				32-bit count value returned as 4 bytes with the LS byte
				first.
	KB/			1

Detect	Determine if	0	0x03	3-Byte Packet
Sensor	Temperature	1	0x39	Detect Sensor Command (see Note 3)
Command	Sensor is	2	0x00	Select Channel AN0
	Present and		0x01	Select Channel AN1
	Retrieve the		0x02	Select Channel AN2
	Serial		0x03	Select Channel AN3
	Number		0x04	Select Channel AN4
	/D '   ( -		0x05	Select Channel AN5
	(Designed to		0x06	Select Channel AN6
	work with		0x07	Select Channel AN7
	the		0x08	Select Channel AN8
	DS18B20+		0x09	Select Channel AN9
	sensor)		A0x0	Select Channel AN10
			0x0B	Select Channel AN11
			0x0C	Select Channel AN12
			0x0D	Select Channel AN13
			0x0E	Select Channel RA4
			0x12	Select Channel RB7
			0x13	Select Channel RB6
				8 Bytes are Returned by the Detect Command:
				0 : LS Byte (0) of Sensor Serial Number, or the following:
				1 = Error: Short Circuit; Data Always Low
				2 = Error: No DS18B20+ Sensor Detected
				1 : Byte (1) of Sensor Serial Number; 0x00 on Error
				2 : Byte (2) of Sensor Serial Number; 0x00 on Error
				3 : Byte (3) of Sensor Serial Number; 0x00 on Error
				4 : Byte (4) of Sensor Serial Number; 0x00 on Error
				5 : Byte (5) of Sensor Serial Number; 0x00 on Error
				6 : Byte (6) of Sensor Serial Number; 0x00 on Error
	1. 141. 4		0.00	7 : MS Byte (7) of Sensor Serial Number; 0x00 on Error
Convert	Initiate	0	0x03	3-Byte Packet
Sensor	Sensor	1	0x40	Convert Sensor Command (see Notes 1 & 2)
Command	Conversion	2	0x01- 0x13	Select Channel 0x00-0x13 (see Command 0x39 above)
			UXIO	The host software must wait for conversion to complete
				before valid data can be read.
				Soloto valia data oan so road.
				Nothing Returned
Read		0	0x03	3-Byte Packet
Sensor		1	0x41	Read Sensor Command (see Note 3)
Command		2	0x01-	Select Channel 0x00-0x13 (see Command 0x39 above)
			0x13	
				2 bytes are returned:
				0 : LS Puto Tomporaturo Valua (aca Nata 2)
				0 : LS Byte Temperature Value (see Note 3)
				1: MS Byte of Temperature Value (see Note 3)
				0x00 returned for both bytes indicates conversion not
				complete.
				A <u>successful</u> read initiates another conversion.

Sensor	Configure the	0	0x04	4-Byte Packet
Resolution	Sensor's	1	0x42	Set Resolution Command (see Note 3)
Command	Resolution	2	0x01-	Select Channel 0x00-0x13 (See Command 0x39
		_	0x13	above)
		3	0x09	9-Bit Resolution (0.5 °C); 94mS Max Convert Time
			0x0A	10-Bit Resolution (0.25 °C); 188mS Max Convert Time
			0x0B	11-Bit Resolution (0.125 °C); 375mS Max Convert
				Time
			0x0C	12-Bit Resolution (default) (0.0625 °C; 750mS Max
				Convert Time
				Nothing Returned
Single	Convert and	0	0x03	3-Byte Packet
Channel	Read the	1	0x50	Single-Channel A/D Convert/Read Command
A/D	Analog Voltage	2	0x00	Select Channel AN0
Conversion	on Selected		0x01	Select Channel AN1
Command	Channel		0x02	Select Channel AN2
			0x03	Select Channel AN3
			0x04	Select Channel AN4
			0x05	Select Channel AN5
			0x06	Select Channel AN6
			0x07	Select Channel AN7
			0x08	Select Channel AN8
			0x09	Select Channel AN9
			A0x0	Select Channel AN10
			0x0B	Select Channel AN11
			0x0C	Select Channel AN12
			0x0D	Select Channel AN13
				2 Bytes are Returned by the A/D Command:
				0 : Least Significant Byte of Voltage Value
				1 : Most Significant Byte of Voltage Value
Single-	Perform	0	0x05	5-Byte Packet
Channel	Multiple A/D	1	0x51	Single-Channel A/D Multiple Conversion Command
A/D	Conversions	2	0x01-	Select Channel 0x00-0x0D (see Command 0x50)
Multiple	on the		0x0D	
Conversion	Selected	3	0x00	Rate = 1K Samples per Second
Command	Channel, and		0x01	Rate = 2K Samples per Second
	Return the		0x02	Rate = 4K Samples per Second
	Data after		0x03	Rate = 10K Samples per Second
	Each		0x04	Rate = 20K Samples per Second
	Conversion	4	0x00	Number of Samples = 128 Returns data in real time
			0x01	Number of Samples = 256 as each A/D conversion
			0x02	Number of Samples = 512 completes; 2 bytes are
			0x03	Number of Samples = 1024 returned for each
			0x04	Number of Samples = 2048 conversion.
			0x05	Number of Samples = 4096
			0x06	Number of Samples = 8192

Continuous	Stream	0	0x04	4-Byte Packet
Read	Voltage Data	1	0x52	Single-Channel A/D Multiple Conversion Command
Command	Collected from	2	0x01-	Select Channel 0x00-0x0D (see Command 0x50)
	Selected		0x0D	
	Channel Until	3	0x000x	Rate = 1K Samples per Second
	Commanded to		01	Rate = 2K Samples per Second
	Stop		0x02	Rate = 4K Samples per Second
			0x03	Rate = 10K Samples per Second
			0x04	Rate = 20K Samples per Second
				Data will be streamed to the host until any byte is sent,
				at which point this command will be terminated.
Set		0	0x02	2-Byte Packet
External		1	0x53	Select the A/D reference voltage connected to the AN3
A/D				pin. (The valid range is 2.7-5.0V.) This voltage sets
Reference				the maximum voltage that can be measured by the
				A/D.
Set Internal		0	0x02	2-Byte Packet
A/D		1	0x54	Use the USB host 5V power source as the reference
Reference				voltage (default).

#### Notes:

- 1. Requires DS18B20+ digital temperature sensor (purchased separately). See Section 9.0 of this document for connection details.
- 2. Before issuing a Convert Sensor Command, make sure that a digital temperature sensor is present on the selected digital I/O channel with a 1.5K-ohm pull-up resistor.
- 3. The temperature value returned is in °C and is assigned a 16-bit value. When the MS bit is high, this indicates a negative temperature. The user will need to handle the sign and convert the negative number before translating the binary representation into a decimal temperature value. One example of how to do this is shown in the DLP-IO20 demo code provided. Other examples are available from <a href="https://www.maxim-ic.com">www.maxim-ic.com</a> in Application Note AN162.pdf.

#### 9.0 CONNECTING THE DIGITAL TEMPERATURE SENSOR

Up to 17 DS18B20+ digital temperature sensors can be connected to the DLP-IO20. For best performance, use Category 5/6 type computer cable to connect the sensors to the DLP-IO20. Two twisted-pair wires in the Cat 5/Cat 6 cable are required for the connection. The first pair are for Power (5V) and Ground, and the second pair are designated as Data and Ground. In addition, a 1.5K-ohm pull-up resistor is required for the data line. Figure 3 shows an example of this connection using Channel AN7:

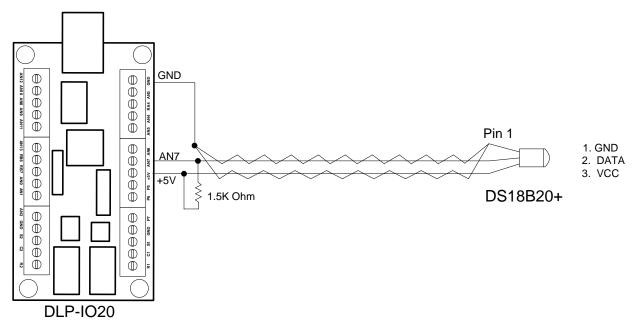


Figure 3: Digital Temperature Sensor Connection Example

To detect a sensor, send the DLP-IO20 the Detect Sensor Command (0x39) packet for the appropriate channel. Eight bytes will be returned from this command packet. If the channel is stuck Low, a "1" will be returned in the first byte. If no sensor is present, then a "2" will be returned in the first byte. In these two cases, the remaining seven bytes will be all zeroes. If a sensor is present and functional, its 8-byte serial number will be returned.

Next, send a Convert Sensor Command (0x40) to initiate the temperature-conversion process. At this point, a Read Sensor Command (0x41) packet can be issued to obtain the temperature value. The conversion can take up to 750mS to complete depending upon the resolution setting.

All commands are detailed in Table 2 under Section 8 of this datasheet.

#### 10.0 DEMO APPLICATION PROGRAM

A test application program called IO20Demo is provided with the purchase of the DLP-IO20 that runs on Windows XP/Vista and can be used to interface with and control the DLP-IO20. (Note that the Visual C++ source is also available with the purchase of the DLP-IO20.) This application is designed to demonstrate all available features:

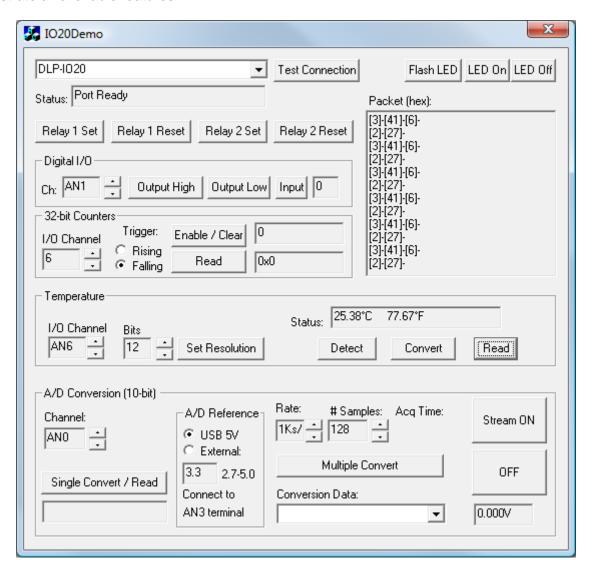
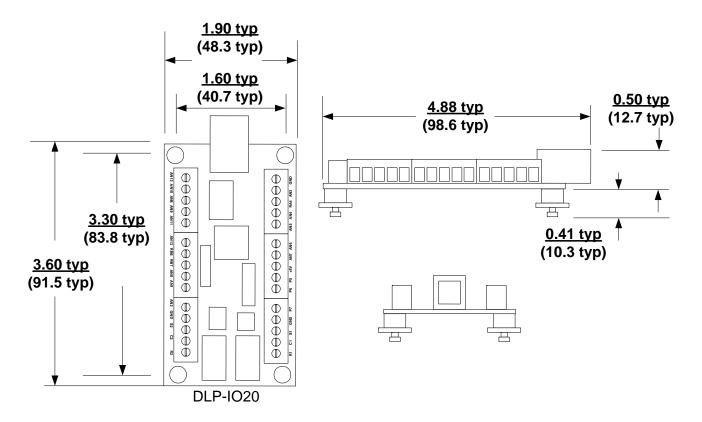


Figure 4: Test Application GUI

The version of the application provided for download with the DLP-IO20 targets Windows XP and Vista, but the Visual C++ 6.0 source code is available (upon purchase of the DLP-IO20) so that the application can be retargeted for different operating systems.

## 11.0 MECHANICAL DIMENSIONS IN INCHES (MM)



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