

## Smart "Compact" range without display CB12 Smart Part number 88974021



- "Modular" versions designed for application-specific functions
- No display or parameter-setting buttons to avoid tampering by unauthorised users

#### Part numbers

	Type	Input	Output	Supply
88974021	CB12 Smart	8 digital (including 4 analogue)		24 V DC

### Specifications

General environment characteristics for CB, CD, X Certifications	CE, UL, CSA, GL
Conformity to standards (with the low voltage directive and EMC directive)	IEC/EN 61131-2 (Open equipment) IEC/EN 61131-2 (Zone B) IEC/EN 61000-6-2, IEC/EN 61000-6-3 (*) IEC/EN 61000-6-4 (*) Except configuration (88 970 1.1 or 88 970 1.2) + (88 970 250 or 88 970 270) + 88 970 241 class A (class B in a metal enclosure
Earthing	Not included
Protection rating	In accordance with IEC/EN 60529 : IP40 on front panel IP20 on terminal block
Overvoltage category	3 in accordance with IEC/EN 60664-1
Pollution	Degree : 2 in accordance with IEC/EN 61131-2
Max operating Altitude	Operation : 2000 m Transport : 3048 m
Mechanical resistance	Immunity to vibrations IEC/EN 60068-2-6, test Fc Immunity to shock IEC/EN 60068-2-27, test Ea
Resistance to electrostatic discharge	Immunity to ESD IEC/EN 61000-4-2, level 3
Resistance to HF interference	Immunity to radiated electrostatic fields IEC/EN 61000-4-3 Immunity to fast transients (burst immunity) IEC/EN 61000-4-4, level 3 Immunity to shock waves IEC/EN 61000-4-5 Radio frequency in common mode IEC/EN 61000-4-6, level 3 Voltage dips and breaks (AC) IEC/EN 61000-4-11 Immunity to damped oscillatory waves IEC/EN 61000-4-12
Conducted and radiated emissions	Class B (*) in accordance with EN 55022, EN 55011 (CISPR22, CISPR11) group 1 (*) Except configuration (88 970 1.1 or 88 970 1.2) + (88 970 250 or 88 970 270) + 88 970 241 class A (class B in a metal enclosure)
Operating temperature	-20 →+70 °C except CB and XB versions in VDC : -30 →+70 °C in accordance with IEC/EN 60068-2-1 and IEC/EN 60068-2-2
Storage temperature	-40 →+70 °C in accordance with IEC/EN 60068-2-1 and IEC/EN 60068-2-2
Relative humidity	95 % max. (no condensation or dripping water) in accordance with IEC/EN 60068-2-30
Mounting	On symmetrical DIN rail, 35 x 7.5 mm and 35 x 15 mm, or on panel (2 x Ø 4 mm)
Screw terminals connection capacity	Flexible wire with ferrule =  1 conductor: 0.25 to 2.5 mm <sup>2</sup> (AWG 24AWG 14)  2 conductors 0.25 to 0.75 mm <sup>2</sup> (AWG 24AWG 18)  Semi-rigid wire =  1 conductor: 0.2 to 2.5 mm <sup>2</sup> (AWG 25AWG 14)  Rigid wire =  1 conductor: 0.2 to 2.5 mm <sup>2</sup> (AWG 25AWG 14)  2 conductors 0.2 to 1.5 mm <sup>2</sup> (AWG 25AWG 16)  Tightening torque =  0.5 N.m (4.5 lb-in) (tighten using screwdriver diam. 3.5 mm)  Also valid for spring cage connectors (ref 88 970 313 and 88 970 317 for the RBT range)

**General characteristics** 

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Operating temperature	-30 →+70 °C (DC) ; -20 →+70° C (AC) ;		
	Operating temperature @ 100 % (Relays 6A) Operating temperature @ 66 % (Relays 8A)		
Storage temperature	-40 →+80 °C		
Processing characteristics of CB, CD, XD & XB pr LCD display	CD, XD : Display with 4 lines of 18 characters		
Programming method	Ladder or FBD/SFC (Grafcet)		
Program size	350 typical blocks		
	128 macros maximum		
	256 blocks maximum per macro		
Program memory	Flash EEPROM		
Removable memory	EEPROM		
Data memory	368 bits/200 words		
Back-up time in the event of power failure	Program and settings in the controller : 10 years Program and settings in the plug-in memory : 10 years		
	Data memory : 10 years		
Cycle time	Ladder : typically 20 ms		
	FBD : 6 →90 ms		
Response time	Input acquisition time + 1 to 2 cycle times		
Clock data retention	10 years (lithium battery) at 25 °C		
Clock drift	Drift < 12 min/year (at 25 °C)		
The set to the second	6 s/month (at 25 °C with user-definable correction of drift)		
Timer block accuracy	1 % ± 2 cycle times		
Start up time on power up	< 1,2 s		
Characteristics of products with AC power suppli	ed		
Supply			
Nominal voltage	24 V AC	100 →240 V AC	
Operating limits	-15 % / +20 %	-15 % / +10 %	
	or 20.4 V AC→28.8 V AC	or 85 V AC→264 V AC	
Supply frequency range	50/60 Hz (+4 % / -6 %)	50/60 Hz (+ 4 % / - 6 %) or 47 →53 Hz/57 →63 Hz	
I have the first and the first	or 47 →53 Hz/57 →63 Hz	40 (	
Immunity from micro power cuts	10 ms (repetition 20 times)  CB12-CD12-XD10-XB10 : 4 VA	10 ms (repetition 20 times) CB12-CD12-XD10-XB10 : 7 VA	
Max. absorbed power	CB20-CD20 : 6 VA	CB20-CD20 : 11 VA	
	XD10-XB10 with extension - XD26-XB26 : 7.5 VA	XD10-XB10 with extension - XD26-XB26 : 12 VA	
	XD26-XB26 with extension : 10 VA	XD26-XB26 with extension : 17 VA	
Isolation voltage	1780 V AC	1780 V AC	
Inputs			
Input voltage	24 V AC (-15 % / +20 %)	100 →240 V AC (-15 % / +10 %)	
Input current	4.4 mA @ 20.4 V AC	0.04 0.05 \/ 0.05	
	5.2 mA @ 24.0 V AC	0.24 mA @ 85 V AC 0.75 mA @ 264 V AC	
	6.3 mA @ 28.8 V AC		
Input impedance	4.6 kΩ	350 kΩ	
Logic 1 voltage threshold	≥ 14 V AC	≥ 79 V AC	
Making current at logic state 1	> 2 mA   ≤ 5 V AC	> 0.17 mA	
Logic 0 voltage threshold  Release current at logic state 0	< 0.5 mA	≤ 20 V AC (≤ 28 V AC : XE10, XR06, XR10, XR14) < 0.5 mA	
Response time with LADDER programming	50 ms	50 ms	
Response time with EADDLIX programming	State 0 →1 (50/60 Hz)	State 0 →1 (50/60 Hz)	
Response time with function blocks programming	Configurable in increments of 10 ms	Configurable in increments of 10 ms	
	50 ms min. up to 255 ms	50 ms min. up to 255 ms	
	State 0 →1 (50/60 Hz)	State 0 →1 (50/60 Hz)	
Maximum counting frequency	In accordance with cycle time (Tc) and input response time (Tr):	In accordance with cycle time (Tc) and input response time (Tr):	
0	1/((2 x Tc) + Tr)	1/ ((2 x Tc) + Tr)	
Sensor type	Contact or 3-wire PNP	Contact or 3-wire PNP	
Input type Isolation between power supply and inputs	Resistive None	Resistive None	
Isolation between power supply and inputs Isolation between inputs	None	None	
Protection against polarity inversions	Yes	Yes	
Status indicator	On LCD screen for CD and XD	On LCD screen for CD and XD	
Characteristics of relay outputs common to the e			
	5 30 V DC		
Max. breaking voltage	5 →30 V DC 24 →250 V AC		
	24 →250 V AC		
Breaking current			
	24 →250 V AC CB-CD-XD10-XB10-XR06-XR10 : 8 A XD26-XB26 : 8 x 8 A relays, 2 x 5 A relays XE10 : 4 x 5 A relays		
	24 →250 V AC  CB-CD-XD10-XB10-XR06-XR10 : 8 A  XD26-XB26 : 8 x 8 A relays, 2 x 5 A relays  XE10 : 4 x 5 A relays  XR14 : 4 x 8 A relays, 2 x 5 A relays		
Breaking current	24 →250 V AC  CB-CD-XD10-XB10-XR06-XR10: 8 A  XD26-XB26: 8 x 8 A relays, 2 x 5 A relays  XE10: 4 x 5 A relays  XR14: 4 x 8 A relays, 2 x 5 A relays  RBT (Removable Terminal Blocks) versions: verify the maximum of	current according to the type of connection used	
	24 →250 V AC  CB-CD-XD10-XB10-XR06-XR10: 8 A  XD26-XB26: 8 x 8 A relays, 2 x 5 A relays  XE10: 4 x 5 A relays  XR14: 4 x 8 A relays, 2 x 5 A relays  RBT (Removable Terminal Blocks) versions: verify the maximum of Utilization category DC-12: 24 V, 1.5 A	current according to the type of connection used	
Breaking current	24 →250 V AC  CB-CD-XD10-XB10-XR06-XR10: 8 A  XD26-XB26: 8 x 8 A relays, 2 x 5 A relays  XE10: 4 x 5 A relays  XR14: 4 x 8 A relays, 2 x 5 A relays  RBT (Removable Terminal Blocks) versions: verify the maximum of	current according to the type of connection used	
Breaking current	24 →250 V AC  CB-CD-XD10-XB10-XR06-XR10: 8 A  XD26-XB26: 8 x 8 A relays, 2 x 5 A relays  XE10: 4 x 5 A relays  XR14: 4 x 8 A relays, 2 x 5 A relays  RBT (Removable Terminal Blocks) versions: verify the maximum of Utilization category DC-12: 24 V, 1.5 A  Utilization category DC-13: 24 V (L/R = 10 ms), 0.6 A	current according to the type of connection used	
Breaking current	24 →250 V AC  CB-CD-XD10-XB10-XR06-XR10: 8 A  XD26-XB26: 8 x 8 A relays, 2 x 5 A relays  XE10: 4 x 5 A relays  XR14: 4 x 8 A relays, 2 x 5 A relays  RBT (Removable Terminal Blocks) versions: verify the maximum of Utilization category DC-12: 24 V, 1.5 A  Utilization category DC-13: 24 V (L/R = 10 ms), 0.6 A  Utilization category AC-12: 230 V, 1.5 A	current according to the type of connection used	
Breaking current  Electrical durability for 500 000 operating cycles	24 →250 V AC  CB-CD-XD10-XB10-XR06-XR10: 8 A  XD26-XB26: 8 x 8 A relays, 2 x 5 A relays  XE10: 4 x 5 A relays  XR14: 4 x 8 A relays, 2 x 5 A relays  RBT (Removable Terminal Blocks) versions: verify the maximum of the control of th	current according to the type of connection used	
Breaking current  Electrical durability for 500 000 operating cycles  Max. Output Common Current	24 →250 V AC  CB-CD-XD10-XB10-XR06-XR10: 8 A  XD26-XB26: 8 x 8 A relays, 2 x 5 A relays  XE10: 4 x 5 A relays  XR14: 4 x 8 A relays, 2 x 5 A relays  RBT (Removable Terminal Blocks) versions: verify the maximum of the control of th	current according to the type of connection used	
Breaking current  Electrical durability for 500 000 operating cycles  Max. Output Common Current  Minimum switching capacity	24 →250 V AC  CB-CD-XD10-XB10-XR06-XR10: 8 A  XD26-XB26: 8 x 8 A relays, 2 x 5 A relays  XE10: 4 x 5 A relays, 2 x 5 A relays  XR14: 4 x 8 A relays, 2 x 5 A relays  RBT (Removable Terminal Blocks) versions: verify the maximum of the version of t	current according to the type of connection used	
Breaking current  Electrical durability for 500 000 operating cycles  Max. Output Common Current  Minimum switching capacity  Minimum load  Maximum rate	24 →250 V AC  CB-CD-XD10-XB10-XR06-XR10: 8 A  XD26-XB26: 8 x 8 A relays, 2 x 5 A relays  XE10: 4 x 5 A relays  XR14: 4 x 8 A relays, 2 x 5 A relays  RBT (Removable Terminal Blocks) versions: verify the maximum of the unit	current according to the type of connection used	
Breaking current  Electrical durability for 500 000 operating cycles  Max. Output Common Current  Minimum switching capacity  Minimum load  Maximum rate  Mechanical life	24 →250 V AC  CB-CD-XD10-XB10-XR06-XR10: 8 A  XD26-XB26: 8 x 8 A relays, 2 x 5 A relays  XE10: 4 x 5 A relays  XR14: 4 x 8 A relays, 2 x 5 A relays  RBT (Removable Terminal Blocks) versions: verify the maximum of the strength of the stre	current according to the type of connection used	
Breaking current  Electrical durability for 500 000 operating cycles  Max. Output Common Current  Minimum switching capacity  Minimum load  Maximum rate	24 →250 V AC  CB-CD-XD10-XB10-XR06-XR10: 8 A  XD26-XB26: 8 x 8 A relays, 2 x 5 A relays  XE10: 4 x 5 A relays  XR14: 4 x 8 A relays, 2 x 5 A relays  RBT (Removable Terminal Blocks) versions: verify the maximum of the unit	current according to the type of connection used	

Built-in protections	A 1 4 1 4 1 1 14 A1		
	Against short-circuits : None		
	Against overvoltages and overloads : None		
Status indicator	On LCD screen for CD and XD		
Characteristics of product with DC power supp	lied		
Supply			
Nominal voltage	12 V DC	24 V DC	
Operating limits	-13 % / +20 %	-20 % / +25 %	
operating infine	or 10.4 V DC→14.4 V DC (including ripple)	or 19.2 V DC→30 V	DC (including ripple)
Immunity from micro power cuts	≤ 1 ms (repetition 20 times)	≤ 1 ms (repetition 20 times)	
Max. absorbed power	CB12 with solid state outputs : 1.5 W CD12 : 1.5 W CD20 : 2.5 W	CB12-CD12-CD20 with solid state outputs - XD10-XB10 with solid state outputs : 3 W XD10-XB10 with relay outputs : 4 W XD26-XB26 with solid state outputs : 5 W CB20-CD20 with relay outputs - XD26 with relay outputs : 6 W XD10-XB10 with extension : 8 W XD26-XB26 with extension : 10 W	
	XD26-XB26 : 3 W XD26-XB26 with extension : 5 W XD26 with solid state outputs : 2.5 W		
Protection against polarity inversions	Yes	Yes	
Digital inputs (I1 to IA and IH to IY)			
Input voltage	12 V DC (-13 % / +20 %)		24 V DC (-20 % / +25 %)
Input current	3.9 mA @ 10.44 V DC 4.4 mA @ 12.0 V DC 5.3 mA @ 14.4 VDC		2.6 mA @ 19.2 V DC 3.2 mA @ 24 V DC 4.0 mA @ 30.0 VDC
Input impedance	2.7 kΩ		7.4 kΩ
Logic 1 voltage threshold	≥7 V DC		≥ 15 V DC
Making current at logic state 1	≥ 2 mA		≥ 2.2 mA
Logic 0 voltage threshold	≤3 V DC		≤ 5 V DC
Release current at logic state 0	< 0.9 mA		< 0.75 mA
Response time	1 →2 cycle times		1 →2 cycle times
Maximum counting frequency	Inputs I1 & I2 : Ladder (1 k Hz) & FBD (up to Inputs I3 to IA & IH to IY : In accordance with input response time (Tr) : 1/ ( (2 x Tc) + Tr)	,	Inputs I1 & I2 : Ladder (1 k Hz) & FBD (up to 6 k Hz) Inputs I3 to IA & IH to IY : In accordance with cycle time (Tc) and input response time (Tr) : 1/ ( $(2 \times Tc) + Tr)$
Sensor type	Contact or 3-wire PNP		Contact or 3-wire PNP
Conforming to IEC/EN 61131-2	Type 1		Type 1
Input type	Resistive		Resistive
Isolation between power supply and inputs	None		None
Isolation between inputs	None		None
Protection against polarity inversions	Yes		Yes
Status indicator	On LCD screen for CD and XD		On LCD screen for CD and XD
Analogue or digital inputs (IB to IG)			
CB12-CD12-XD10-XB10	4 inputs IB →IE		4 inputs IB →IE
	•		Timputo IB TIE
CB20-CD20-XB26-XD26	6 innuts IB →IG		6 inputs IB →IG
	6 inputs IB →IG		6 inputs IB →IG
nputs used as analogue inputs			
inputs used as analogue inputs Measurement range	$(0 \rightarrow 10 \text{ V}) \text{ or } (0 \rightarrow \text{V power supply})$		$(0 \rightarrow 10 \text{ V}) \text{ or } (0 \rightarrow \text{V power supply})$
inputs used as analogue inputs Measurement range Input impedance	. (0 →10 V) or (0 →V power supply) 14 kΩ		$(0 \rightarrow 10 \text{ V}) \text{ or } (0 \rightarrow \text{V power supply})$ 12 k $\Omega$
Inputs used as analogue inputs Measurement range Input impedance Input voltage	. (0 →10 V) or (0 →V power supply) 14 kΩ 14.4 V DC max.		$(0 \rightarrow 10 \text{ V})$ or $(0 \rightarrow \text{V} \text{ power supply})$ 12 k $\Omega$ 30 V DC max.
nputs used as analogue inputs Measurement range Input impedance Input voltage Value of LSB	. (0 →10 V) or (0 →V power supply) 14 kΩ 14.4 V DC max. 14 mV, 4 mA		$(0 \rightarrow 10 \text{ V})$ or $(0 \rightarrow \text{V}$ power supply) 12 k $\Omega$ 30 V DC max. 29 mV, 4 mA
nputs used as analogue inputs Measurement range Input impedance Input voltage Value of LSB Input type	. (0 →10 V) or (0 →V power supply) 14 kΩ 14.4 V DC max. 14 mV, 4 mA Common mode		(0 $\rightarrow$ 10 V) or (0 $\rightarrow$ V power supply) 12 kΩ 30 V DC max. 29 mV, 4 mA Common mode
nputs used as analogue inputs Measurement range Input impedance Input voltage Value of LSB Input type	. (0 →10 V) or (0 →V power supply) 14 kΩ 14.4 V DC max. 14 mV, 4 mA		$(0 \rightarrow 10 \text{ V})$ or $(0 \rightarrow \text{V} \text{ power supply})$ 12 k $\Omega$ 30 V DC max. 29 mV, 4 mA Common mode 10 bits at max. input voltage
nputs used as analogue inputs Measurement range Input impedance Input voltage Value of LSB Input type Resolution	. (0 →10 V) or (0 →V power supply) 14 kΩ 14.4 V DC max. 14 mV, 4 mA Common mode		(0 $\rightarrow$ 10 V) or (0 $\rightarrow$ V power supply) 12 kΩ 30 V DC max. 29 mV, 4 mA Common mode
nputs used as analogue inputs  Measurement range Input impedance Input voltage Value of LSB Input type Resolution Conversion time	. (0 →10 V) or (0 →V power supply) 14 kΩ 14.4 V DC max. 14 mV, 4 mA Common mode 10 bits at max. input voltage		$(0 \rightarrow 10 \text{ V})$ or $(0 \rightarrow \text{V} \text{ power supply})$ 12 k $\Omega$ 30 V DC max. 29 mV, 4 mA Common mode 10 bits at max. input voltage
nputs used as analogue inputs  Measurement range Input impedance Input voltage Value of LSB Input type Resolution Conversion time Accuracy at 25 °C	(0 →10 V) or (0 →V power supply)  14 kΩ  14.4 V DC max.  14 mV, 4 mA  Common mode  10 bits at max. input voltage  Controller cycle time		(0 →10 V) or (0 →V power supply) 12 kΩ 30 V DC max. 29 mV, 4 mA Common mode 10 bits at max. input voltage Controller cycle time
nputs used as analogue inputs  Measurement range Input impedance Input voltage Value of LSB Input type Resolution Conversion time Accuracy at 25 °C Accuracy at 55 °C	(0 →10 V) or (0 →V power supply)  14 kΩ  14.4 V DC max.  14 mV, 4 mA  Common mode  10 bits at max. input voltage  Controller cycle time  ± 5 %		$(0 \rightarrow 10 \text{ V})$ or $(0 \rightarrow \text{V power supply})$ $12 \text{ k}\Omega$ 30  V DC max. 29  mV, 4  mA Common mode 10  bits at max. input voltage Controller cycle time $\pm 5 \text{ \%}$
Measurement range Input impedance Input voltage Value of LSB Input type Resolution Conversion time Accuracy at 25 °C Accuracy at 55 °C Repeat accuracy at 55 °C	$(0 \rightarrow 10 \text{ V}) \text{ or } (0 \rightarrow \text{V power supply})$ 14 kΩ 14.4 V DC max. 14 mV, 4 mA Common mode 10 bits at max. input voltage Controller cycle time ± 5 % ± 6.2 % ± 2 %		$(0 \rightarrow 10 \text{ V})$ or $(0 \rightarrow \text{V power supply})$ $12 \text{ k}\Omega$ 30  V DC max. 29  mV, 4  mA Common mode 10  bits at max. input voltage Controller cycle time $\pm 5 \%$ $\pm 6.2 \%$
Inputs used as analogue inputs  Measurement range Input impedance Input voltage  Value of LSB Input type Resolution Conversion time Accuracy at 25 °C Accuracy at 55 °C Repeat accuracy at 55 °C Isolation between analogue channel and power supply	$(0 \rightarrow 10 \text{ V}) \text{ or } (0 \rightarrow \text{V power supply})$ 14 kΩ 14.4 V DC max. 14 mV, 4 mA Common mode 10 bits at max. input voltage Controller cycle time ± 5 % ± 6.2 % ± 2 %	not isolated)	$(0 \rightarrow 10 \text{ V})$ or $(0 \rightarrow \text{V power supply})$ $12 \text{ k}\Omega$ 30  V DC max. 29  mV, 4  mA Common mode 10  bits at max. input voltage Controller cycle time $\pm 5 \%$ $\pm 6.2 \%$ $\pm 2 \%$
Inputs used as analogue inputs  Measurement range Input impedance Input voltage  Value of LSB Input type Resolution Conversion time Accuracy at 25 °C Accuracy at 55 °C Repeat accuracy at 55 °C Isolation between analogue channel and power supply Cable length	$(0 \rightarrow 10 \text{ V})$ or $(0 \rightarrow \text{V power supply})$ 14 kΩ 14.4 V DC max. 14 mV, 4 mA Common mode 10 bits at max. input voltage Controller cycle time ± 5 % ± 6.2 % ± 2 % None	not isolated)	$(0 \rightarrow 10 \text{ V}) \text{ or } (0 \rightarrow \text{V power supply})$ $12 \text{ k}\Omega$ $30 \text{ V DC max.}$ $29 \text{ mV, 4 mA}$ Common mode $10 \text{ bits at max. input voltage}$ Controller cycle time $\pm 5 \%$ $\pm 6.2 \%$ $\pm 2 \%$ None
nputs used as analogue inputs  Measurement range Input impedance Input voltage Value of LSB Input type Resolution Conversion time Accuracy at 25 °C Accuracy at 55 °C Repeat accuracy at 55 °C Isolation between analogue channel and power supply Cable length Protection against polarity inversions	$(0 \rightarrow 10 \text{ V})$ or $(0 \rightarrow \text{V power supply})$ 14 kΩ 14.4 V DC max. 14 mV, 4 mA Common mode 10 bits at max. input voltage Controller cycle time ± 5 % ± 6.2 % ± 2 % None 10 m maximum, with shielded cable (sensor	not isolated)	$(0 \rightarrow 10 \text{ V})$ or $(0 \rightarrow \text{V} \text{ power supply})$ 12 kΩ 30 V DC max. 29 mV, 4 mA Common mode 10 bits at max. input voltage Controller cycle time ± 5 % ± 6.2 % ± 2 % None 10 m maximum, with shielded cable (sensor not isolated)
Inputs used as analogue inputs  Measurement range Input impedance Input voltage  Value of LSB Input type Resolution  Conversion time  Accuracy at 25 °C  Accuracy at 55 °C  Repeat accuracy at 55 °C  Isolation between analogue channel and power supply Cable length  Protection against polarity inversions  Potentiometer control	(0 $\rightarrow$ 10 V) or (0 $\rightarrow$ V power supply)  14 k $\Omega$ 14.4 V DC max.  14 mV, 4 mA  Common mode  10 bits at max. input voltage  Controller cycle time $\pm$ 5 % $\pm$ 6.2 % $\pm$ 2 %  None  10 m maximum, with shielded cable (sensor Yes)  2.2 k $\Omega$ /0.5 W (recommended)	not isolated)	(0 →10 V) or (0 →V power supply)  12 kΩ  30 V DC max.  29 mV, 4 mA  Common mode  10 bits at max. input voltage  Controller cycle time  ± 5 %  ± 6.2 %  ± 2 %  None  10 m maximum, with shielded cable (sensor not isolated)  Yes  2.2 kΩ/0.5 W (recommended)
nputs used as analogue inputs  Measurement range Input impedance Input voltage Value of LSB Input type Resolution Conversion time Accuracy at 25 °C Accuracy at 55 °C Repeat accuracy at 55 °C Isolation between analogue channel and power supply Cable length Protection against polarity inversions Potentiometer control  nputs used as digital inputs	(0 →10 V) or (0 →V power supply)  14 kΩ  14.4 V DC max.  14 mV, 4 mA  Common mode  10 bits at max. input voltage  Controller cycle time $\pm$ 5 % $\pm$ 6.2 % $\pm$ 2 %  None  10 m maximum, with shielded cable (sensor Yes)  2.2 kΩ/0.5 W (recommended)  10 kΩ max.	not isolated)	$\begin{array}{l} (0 \rightarrow \! 10 \ V) \ \text{or} \ (0 \rightarrow \! V \ \text{power supply}) \\ 12 \ k\Omega \\ 30 \ V \ DC \ \text{max}. \\ 29 \ \text{mV}, 4 \ \text{mA} \\ \text{Common mode} \\ 10 \ \text{bits at max}. \ \text{input voltage} \\ \text{Controller cycle time} \\ \pm 5 \ \% \\ \pm 6.2 \ \% \\ \pm 2 \ \% \\ \text{None} \\ 10 \ \text{m maximum}, \ \text{with shielded cable (sensor not isolated)} \\ \text{Yes} \\ 2.2 \ k\Omega/0.5 \ W \ (\text{recommended}) \\ 10 \ k\Omega \ \text{max}. \\ \end{array}$
Inputs used as analogue inputs  Measurement range Input impedance Input voltage  Value of LSB Input type Resolution Conversion time Accuracy at 25 °C Accuracy at 55 °C Isolation between analogue channel and power supply Cable length Protection against polarity inversions Potentiometer control  Inputs used as digital inputs Input voltage	(0 →10 V) or (0 →V power supply)  14 kΩ  14.4 V DC max.  14 mV, 4 mA  Common mode  10 bits at max. input voltage  Controller cycle time $\pm 5\%$ $\pm 6.2\%$ $\pm 2\%$ None  10 m maximum, with shielded cable (sensor Yes)  2.2 kΩ/0.5 W (recommended)  10 kΩ max.	not isolated)	$(0 \rightarrow 10 \text{ V})$ or $(0 \rightarrow \text{V} \text{ power supply})$ 12 k $\Omega$ 30 V DC max. 29 mV, 4 mA Common mode 10 bits at max. input voltage Controller cycle time $\pm 5 \%$ $\pm 6.2 \%$ $\pm 2 \%$ None 10 m maximum, with shielded cable (sensor not isolated) Yes 2.2 k $\Omega$ /0.5 W (recommended) 10 k $\Omega$ max.
Inputs used as analogue inputs  Measurement range Input impedance Input voltage  Value of LSB Input type Resolution Conversion time Accuracy at 25 °C Accuracy at 55 °C Isolation between analogue channel and power supply Cable length Protection against polarity inversions Potentiometer control  Inputs used as digital inputs Input voltage	(0 →10 V) or (0 →V power supply)  14 kΩ  14.4 V DC max.  14 mV, 4 mA  Common mode  10 bits at max. input voltage  Controller cycle time $\pm$ 5 % $\pm$ 6.2 % $\pm$ 2 %  None  10 m maximum, with shielded cable (sensor Yes)  2.2 kΩ/0.5 W (recommended)  10 kΩ max.	not isolated)	$(0 \rightarrow 10 \text{ V}) \text{ or } (0 \rightarrow \text{V power supply})$ $12 \text{ k}\Omega$ $30 \text{ V DC max.}$ $29 \text{ mV, 4 mA}$ $Common mode$ $10 \text{ bits at max. input voltage}$ $Controller cycle time$ $\pm 5 \%$ $\pm 6.2 \%$ $\pm 2 \%$ $None$ $10 \text{ m maximum, with shielded cable (sensor not isolated)}$ $Yes$ $2.2 \text{ k}\Omega/0.5 \text{ W (recommended)}$ $10 \text{ k}\Omega \text{ max.}$ $24 \text{ V DC } (-20 \% / +25 \%)$ $1.6 \text{ mA } @ 19.2 \text{ VDC}$
Inputs used as analogue inputs  Measurement range Input impedance Input voltage  Value of LSB Input type Resolution Conversion time Accuracy at 25 °C Accuracy at 55 °C Isolation between analogue channel and power supply Cable length Protection against polarity inversions Potentiometer control  Inputs used as digital inputs Input voltage	(0 →10 V) or (0 →V power supply)  14 kΩ  14.4 V DC max.  14 mV, 4 mA  Common mode  10 bits at max. input voltage  Controller cycle time $\pm 5\%$ $\pm 6.2\%$ $\pm 2\%$ None  10 m maximum, with shielded cable (sensor Yes)  2.2 kΩ/0.5 W (recommended)  10 kΩ max.	not isolated)	$(0 \rightarrow 10 \text{ V})$ or $(0 \rightarrow \text{V} \text{ power supply})$ 12 k $\Omega$ 30 V DC max. 29 mV, 4 mA Common mode 10 bits at max. input voltage Controller cycle time $\pm 5 \%$ $\pm 6.2 \%$ $\pm 2 \%$ None 10 m maximum, with shielded cable (sensor not isolated) Yes 2.2 k $\Omega$ /0.5 W (recommended) 10 k $\Omega$ max.
Measurement range Input where the state of t	(0 →10 V) or (0 →V power supply)  14 kΩ  14.4 V DC max.  14 mV, 4 mA  Common mode  10 bits at max. input voltage  Controller cycle time $\pm 5\%$ $\pm 6.2\%$ $\pm 2\%$ None  10 m maximum, with shielded cable (sensor Yes  2.2 kΩ/0.5 W (recommended)  10 kΩ max.  12 V DC (-13 % / +20 %)  0.7 mA @ 10.44 VDC  0.9 mA @ 12.0 VDC	not isolated)	$(0 \rightarrow 10 \text{ V}) \text{ or } (0 \rightarrow \text{V power supply})$ $12 \text{ k}\Omega$ $30 \text{ V DC max.}$ $29 \text{ mV, 4 mA}$ $Common mode$ $10 \text{ bits at max. input voltage}$ $Controller cycle time$ $\pm 5 \%$ $\pm 6.2 \%$ $\pm 2 \%$ $None$ $10 \text{ m maximum, with shielded cable (sensor not isolated)}$ $\text{Yes}$ $2.2 \text{ k}\Omega/0.5 \text{ W (recommended)}$ $10 \text{ k}\Omega \text{ max.}$ $24 \text{ V DC } (-20 \% / +25 \%)$ $1.6 \text{ mA} @ 19.2 \text{ VDC}$ $2.0 \text{ mA} @ 24.0 \text{ V DC}$
Measurement range Input impedance Input woltage Value of LSB Input type Resolution Conversion time Accuracy at 25 °C Accuracy at 55 °C Repeat accuracy at 55 °C Isolation between analogue channel and power supply Cable length Protection against polarity inversions Potentiometer control  Input sused as digital inputs Input current Input impedance	(0 →10 V) or (0 →V power supply)  14 kΩ  14.4 V DC max.  14 mV, 4 mA  Common mode  10 bits at max. input voltage  Controller cycle time $\pm 5\%$ $\pm 6.2\%$ $\pm 2\%$ None  10 m maximum, with shielded cable (sensor Yes  2.2 kΩ/0.5 W (recommended)  10 kΩ max.  12 V DC (-13 % / +20 %)  0.7 mA @ 10.44 VDC  0.9 mA @ 12.0 VDC  1.0 mA @ 14.4VDC	not isolated)	$(0 \rightarrow 10 \text{ V}) \text{ or } (0 \rightarrow \text{V power supply})$ $12 \text{ k}\Omega$ $30 \text{ V DC max.}$ $29 \text{ mV, 4 mA}$ $Common mode$ $10 \text{ bits at max. input voltage}$ $Controller cycle time$ $\pm 5 \%$ $\pm 6.2 \%$ $\pm 2 \%$ $None$ $10 \text{ m maximum, with shielded cable (sensor not isolated)}$ $\text{Yes}$ $2.2 \text{ k}\Omega/0.5 \text{ W (recommended)}$ $10 \text{ k}\Omega \text{ max.}$ $24 \text{ V DC } (-20 \% / +25 \%)$ $1.6 \text{ mA } @ 19.2 \text{ VDC}$ $2.0 \text{ mA } @ 24.0 \text{ V DC}$ $2.5 \text{ mA } @ 30.0 \text{ VDC}$
Measurement range Input impedance Input wisage Value of LSB Input type Resolution Conversion time Accuracy at 25 °C Accuracy at 55 °C Repeat accuracy at 55 °C Isolation between analogue channel and power supply Cable length Protection against polarity inversions Potentiometer control  Input sused as digital inputs Input unpedance Logic 1 voltage threshold	(0 →10 V) or (0 →V power supply)  14 kΩ  14.4 V DC max.  14 mV, 4 mA  Common mode  10 bits at max. input voltage  Controller cycle time $\pm 5\%$ $\pm 6.2\%$ $\pm 2\%$ None  10 m maximum, with shielded cable (sensor Yes)  2.2 kΩ/0.5 W (recommended)  10 kΩ max.  12 V DC (-13 % / +20 %)  0.7 mA @ 10.44 VDC  0.9 mA @ 12.0 VDC  1.0 mA @ 14.4VDC  14 kΩ  ≥ 7 V DC	not isolated)	$(0 \rightarrow 10 \text{ V}) \text{ or } (0 \rightarrow \text{V power supply})$ $12 \text{ k}\Omega$ $30 \text{ V DC max.}$ $29 \text{ mV, 4 mA}$ $\text{Common mode}$ $10 \text{ bits at max. input voltage}$ $\text{Controller cycle time}$ $\pm 5 \text{ %}$ $\pm 6.2 \text{ %}$ $\pm 2 \text{ %}$ $\text{None}$ $10 \text{ m maximum, with shielded cable (sensor not isolated)}$ $\text{Yes}$ $2.2 \text{ k}\Omega/0.5 \text{ W (recommended)}$ $10 \text{ k}\Omega \text{ max.}$ $24 \text{ V DC } (-20 \text{ % / +25 \text{ %})}$ $1.6 \text{ mA @ 19.2 \text{ VDC}}$ $2.0 \text{ mA @ 24.0 \text{ V DC}}$ $2.5 \text{ mA @ 30.0 \text{ VDC}}$ $12 \text{ k}\Omega$ $\geq 15 \text{ VDC}$
Measurement range Input impedance Input impedance Input voitage Value of LSB Input type Resolution Conversion time Accuracy at 25 °C Accuracy at 55 °C Repeat accuracy at 55 °C Isolation between analogue channel and power supply Cable length Protection against polarity inversions Potentiometer control  Input sused as digital inputs Input current  Input impedance Logic 1 voltage threshold Making current at logic state 1	(0 →10 V) or (0 →V power supply)  14 kΩ  14.4 V DC max.  14 mV, 4 mA  Common mode  10 bits at max. input voltage  Controller cycle time $\pm 5\%$ $\pm 6.2\%$ $\pm 2\%$ None  10 m maximum, with shielded cable (sensor Yes)  2.2 kΩ/0.5 W (recommended)  10 kΩ max.  12 V DC (-13 % / +20 %)  0.7 mA @ 10.44 VDC  0.9 mA @ 12.0 VDC  1.0 mA @ 14.4VDC  14 kΩ  ≥ 7 V DC  ≥ 0.5 mA	not isolated)	$(0 \rightarrow 10 \text{ V}) \text{ or } (0 \rightarrow \text{V power supply})$ $12 \text{ k}\Omega$ $30 \text{ V DC max.}$ $29 \text{ mV, 4 mA}$ $\text{Common mode}$ $10 \text{ bits at max. input voltage}$ $\text{Controller cycle time}$ $\pm 5 \text{ %}$ $\pm 6.2 \text{ %}$ $\pm 2 \text{ %}$ $\text{None}$ $10 \text{ m maximum, with shielded cable (sensor not isolated)}$ $\text{Yes}$ $2.2 \text{ k}\Omega/0.5 \text{ W (recommended)}$ $10 \text{ k}\Omega \text{ max.}$ $24 \text{ V DC } (-20 \text{ % / +25 \text{ %})}$ $1.6 \text{ mA @ 19.2 \text{ VDC}}$ $2.0 \text{ mA @ 24.0 \text{ V DC}}$ $2.0 \text{ mA @ 24.0 \text{ V DC}}$ $2.5 \text{ mA @ 30.0 \text{ VDC}}$ $12 \text{ k}\Omega$ $\geq 15 \text{ VDC}$ $\geq 1.2 \text{ mA}$
Inputs used as analogue inputs  Measurement range Input impedance Input voltage  Value of LSB Input type Resolution Conversion time Accuracy at 25 °C Accuracy at 55 °C Isolation between analogue channel and power supply Cable length Protection against polarity inversions Potentiometer control  Inputs used as digital inputs Input voltage Input current  Input impedance Logic 1 voltage threshold Making current at logic state 1 Logic 0 voltage threshold	(0 →10 V) or (0 →V power supply)  14 kΩ  14.4 V DC max.  14 mV, 4 mA  Common mode  10 bits at max. input voltage  Controller cycle time $\pm 5\%$ $\pm 6.2\%$ $\pm 2\%$ None  10 m maximum, with shielded cable (sensor Yes)  2.2 kΩ/0.5 W (recommended)  10 kΩ max.  12 V DC (-13 % / +20 %)  0.7 mA @ 10.44 VDC  0.9 mA @ 12.0 VDC  1.0 mA @ 14.4VDC  14 kΩ  ≥ 7 V DC  ≥ 0.5 mA  ≤ 3 V DC	not isolated)	(0 →10 V) or (0 →V power supply)  12 kΩ  30 V DC max.  29 mV, 4 mA  Common mode  10 bits at max. input voltage  Controller cycle time  ± 5 %  ± 6.2 %  ± 2 %  None  10 m maximum, with shielded cable (sensor not isolated)  Yes  2.2 kΩ/0.5 W (recommended)  10 kΩ max.  24 V DC (-20 % / +25 %)  1.6 mA @ 19.2 VDC  2.0 mA @ 24.0 V DC  2.5 mA @ 30.0 VDC  12 kΩ  ≥ 15 VDC  ≥ 1.2 mA  ≤ 5 V DC
Measurement range Input impedance Input voltage Value of LSB Input type Resolution Conversion time Accuracy at 25 °C Accuracy at 55 °C Isolation between analogue channel and power supply Cable length Protection against polarity inversions Potentiometer control  Input sused as digital inputs Input current Input impedance Logic 1 voltage threshold Making current at logic state 1 Logic 0 voltage threshold Release current at logic state 0	(0 →10 V) or (0 →V power supply)  14 kΩ  14.4 V DC max.  14 mV, 4 mA  Common mode  10 bits at max. input voltage  Controller cycle time $\pm 5\%$ $\pm 6.2\%$ $\pm 2\%$ None  10 m maximum, with shielded cable (sensor Yes)  2.2 kΩ/0.5 W (recommended)  10 kΩ max.   12 V DC (-13 % / +20 %)  0.7 mA @ 10.44 VDC  0.9 mA @ 12.0 VDC  1.0 mA @ 14.4VDC  14 kΩ  ≥ 7 V DC  ≥ 0.5 mA  ≤ 3 V DC  ≤ 0.2 mA	not isolated)	(0 →10 V) or (0 →V power supply)  12 kΩ  30 V DC max.  29 mV, 4 mA  Common mode  10 bits at max. input voltage  Controller cycle time  ± 5 %  ± 6.2 %  ± 2 %  None  10 m maximum, with shielded cable (sensor not isolated)  Yes  2.2 kΩ/0.5 W (recommended)  10 kΩ max.  24 V DC (-20 % / +25 %)  1.6 mA @ 19.2 VDC  2.0 mA @ 24.0 V DC  2.5 mA @ 30.0 VDC  12 kΩ  ≥ 15 VDC  ≥ 1.2 mA  ≤ 5 V DC  ≤ 0.5 mA
Measurement range Input impedance Input impedance Input voltage Value of LSB Input type Resolution Conversion time Accuracy at 25 °C Accuracy at 55 °C Isolation between analogue channel and power supply Cable length Protection against polarity inversions Potentiometer control  Input sused as digital inputs Input current Input impedance Logic 1 voltage threshold Making current at logic state 1 Logic 0 voltage threshold Release current at logic state 0 Response time	(0 →10 V) or (0 →V power supply)  14 kΩ  14.4 V DC max.  14 mV, 4 mA  Common mode  10 bits at max. input voltage  Controller cycle time  ± 5 %  ± 6.2 %  ± 2 %  None  10 m maximum, with shielded cable (sensor Yes)  2.2 kΩ/0.5 W (recommended)  10 kΩ max.  12 V DC (-13 % / +20 %)  0.7 mA @ 10.44 VDC  0.9 mA @ 12.0 VDC  1.0 mA @ 14.4VDC  14 kΩ  ≥ 7 V DC  ≥ 0.5 mA  ≤ 3 V DC  ≤ 0.2 mA  1 →2 cycle times  In accordance with cycle time (Tc) and inpu		(0 $\rightarrow$ 10 V) or (0 $\rightarrow$ V power supply) 12 k $\Omega$ 30 V DC max. 29 mV, 4 mA Common mode 10 bits at max. input voltage Controller cycle time $\pm$ 5 % $\pm$ 6.2 % $\pm$ 2 % None 10 m maximum, with shielded cable (sensor not isolated) Yes 2.2 k $\Omega$ /0.5 W (recommended) 10 k $\Omega$ max.  24 V DC (-20 % / +25 %) 1.6 mA @ 19.2 VDC 2.0 mA @ 24.0 V DC 2.5 mA @ 30.0 VDC 12 k $\Omega$ $\geq$ 15 VDC $\leq$ 1.2 mA $\leq$ 5 V DC $\leq$ 0.5 mA 1 $\rightarrow$ 2 cycle times In accordance with cycle time (Tc) and input response time (Tr)
Measurement range Input wipedance Input wipedance Input voltage Value of LSB Input type Resolution Conversion time Accuracy at 25 °C Accuracy at 55 °C Repeat accuracy at 55 °C Repeat accuracy at 55 °C Repeat accuracy at 55 °C Protection against polarity inversions Potentiometer control  Input sused as digital inputs Input current Input impedance Logic 1 voltage threshold Making current at logic state 1 Logic 0 voltage threshold Release current at logic state 0 Response time Maximum counting frequency	(0 →10 V) or (0 →V power supply)  14 kΩ  14.4 V DC max.  14 mV, 4 mA  Common mode  10 bits at max. input voltage  Controller cycle time  ± 5 %  ± 6.2 %  ± 2 %  None  10 m maximum, with shielded cable (sensor Yes)  2.2 kΩ/0.5 W (recommended)  10 kΩ max.  12 V DC (-13 % / +20 %)  0.7 mA @ 10.44 VDC  0.9 mA @ 12.0 VDC  1.0 mA @ 14.4VDC  14 kΩ  ≥ 7 V DC  ≥ 0.5 mA  ≤ 3 V DC  ≤ 0.2 mA  1 →2 cycle times  In accordance with cycle time (Tc) and inpu 1/ ((2 x Tc) + Tr)		$(0 \rightarrow 10 \text{ V}) \text{ or } (0 \rightarrow \text{V power supply})$ $12 \text{ k}\Omega$ $30 \text{ V DC max.}$ $29 \text{ mV, 4 mA}$ $Common mode$ $10 \text{ bits at max. input voltage}$ $Controller cycle time$ $\pm 5 \%$ $\pm 6.2 \%$ $\pm 2 \%$ None $10 \text{ m maximum, with shielded cable (sensor not isolated)}$ $\text{Yes}$ $2.2 \text{ k}\Omega/0.5 \text{ W (recommended)}$ $10 \text{ k}\Omega \text{ max.}$ $24 \text{ V DC } (-20 \% / +25 \%)$ $1.6 \text{ mA } @ 19.2 \text{ VDC}$ $2.0 \text{ mA } @ 24.0 \text{ V DC}$ $2.5 \text{ mA} @ 30.0 \text{ VDC}$ $12 \text{ k}\Omega$ $\geq 15 \text{ VDC}$ $\geq 1.2 \text{ mA}$ $\leq 5 \text{ V DC}$ $\leq 0.5 \text{ mA}$ $1 \rightarrow 2 \text{ cycle times}$ $1 \text{ naccordance with cycle time (Tc) and input response time (Tr)}$ $1/ ( (2 \text{ x Tc)} + \text{Tr})$
Measurement range Input impedance Input impedance Input voltage Value of LSB Input type Resolution Conversion time Accuracy at 25 °C Accuracy at 55 °C Repeat accuracy at 55 °C Isolation between analogue channel and power supply Cable length Protection against polarity inversions Potentiometer control  Inputs used as digital inputs Input current Input impedance Logic 1 voltage threshold Making current at logic state 1 Logic 0 voltage threshold Release current at logic state 0 Response time Maximum counting frequency Sensor type	(0 →10 V) or (0 →V power supply)  14 kΩ  14.4 V DC max.  14 mV, 4 mA  Common mode  10 bits at max. input voltage  Controller cycle time  ± 5 %  ± 6.2 %  ± 2 %  None  10 m maximum, with shielded cable (sensor Yes)  2.2 kΩ/0.5 W (recommended)  10 kΩ max.  12 V DC (-13 % / +20 %)  0.7 mA @ 10.44 VDC  0.9 mA @ 12.0 VDC  1.0 mA @ 14.4VDC  14 kΩ  ≥ 7 V DC  ≥ 0.5 mA  ≤ 3 V DC  ≤ 0.2 mA  1 →2 cycle times  In accordance with cycle time (Tc) and input 1/ ((2 x Tc) + Tr)  Contact or 3-wire PNP		$(0 \rightarrow 10 \text{ V}) \text{ or } (0 \rightarrow \text{V power supply})$ $12 \text{ k}\Omega$ $30 \text{ V DC max.}$ $29 \text{ mV, 4 mA}$ $Common mode$ $10 \text{ bits at max. input voltage}$ $Controller cycle time$ $\pm 5 \%$ $\pm 6.2 \%$ $\pm 2 \%$ $None$ $10 \text{ m maximum, with shielded cable (sensor not isolated)}$ $Yes$ $2.2 \text{ k}\Omega/0.5 \text{ W (recommended)}$ $10 \text{ k}\Omega \text{ max.}$ $24 \text{ V DC } (-20 \% / +25 \%)$ $1.6 \text{ mA} @ 19.2 \text{ VDC}$ $2.0 \text{ mA} @ 24.0 \text{ V DC}$ $2.5 \text{ mA} @ 30.0 \text{ VDC}$ $12 \text{ k}\Omega$ $\geq 15 \text{ VDC}$ $\geq 1.2 \text{ mA}$ $\leq 5 \text{ V DC}$ $\leq 0.5 \text{ mA}$ $1 \rightarrow 2 \text{ cycle times}$ In accordance with cycle time (Tc) and input response time (Tr) $1/((2 \times \text{Tc}) + \text{Tr})$ $Contact \text{ or 3-wire PNP}$
Measurement range Input wipedance Input wipedance Input woltage Value of LSB Input type Resolution Conversion time Accuracy at 25 °C Accuracy at 55 °C Repeat accuracy at 55 °C Isolation between analogue channel and power supply Cable length Protection against polarity inversions Potentiometer control  Input sused as digital inputs Input voltage Input current Input impedance Logic 1 voltage threshold Making current at logic state 1 Logic 0 voltage threshold Release current at logic state 0 Response time Maximum counting frequency Sensor type Conforming to IEC/EN 61131-2	(0 →10 V) or (0 →V power supply)  14 kΩ  14.4 V DC max.  14 mV, 4 mA  Common mode  10 bits at max. input voltage  Controller cycle time  ± 5 %  ± 6.2 %  ± 2 %  None  10 m maximum, with shielded cable (sensor Yes)  2.2 kΩ/0.5 W (recommended)  10 kΩ max.  12 V DC (-13 % / +20 %)  0.7 mA @ 10.44 VDC  0.9 mA @ 12.0 VDC  1.0 mA @ 14.4VDC  14 kΩ  ≥ 7 V DC  ≥ 0.5 mA  ≤ 3 V DC  ≤ 0.2 mA  1 →2 cycle times  In accordance with cycle time (Tc) and input 1/ ((2 x Tc) + Tr)  Contact or 3-wire PNP  Type 1		$(0 \rightarrow 10 \text{ V}) \text{ or } (0 \rightarrow \text{V power supply})$ $12 \text{ k}\Omega$ $30 \text{ V DC max.}$ $29 \text{ mV, 4 mA}$ $Common mode$ $10 \text{ bits at max. input voltage}$ $Controller cycle time$ $\pm 5 \%$ $\pm 6.2 \%$ $\pm 2 \%$ $None$ $10 \text{ m maximum, with shielded cable (sensor not isolated)}$ $\text{Yes}$ $2.2 \text{ k}\Omega/0.5 \text{ W (recommended)}$ $10 \text{ k}\Omega \text{ max.}$ $24 \text{ V DC } (-20 \% / +25 \%)$ $1.6 \text{ mA} @ 19.2 \text{ VDC}$ $2.0 \text{ mA} @ 24.0 \text{ V DC}$ $2.5 \text{ mA} @ 30.0 \text{ VDC}$ $12 \text{ k}\Omega$ $\geq 15 \text{ VDC}$ $\geq 1.2 \text{ mA}$ $\leq 5 \text{ V DC}$ $\leq 0.5 \text{ mA}$ $1 \rightarrow 2 \text{ cycle times}$ In accordance with cycle time (Tc) and input response time (Tr) $1/((2 \text{ x Tc}) + \text{Tr})$ $Contact \text{ or 3-wire PNP}$ $Type 1$
Inputs used as analogue inputs  Measurement range Input impedance Input voltage  Value of LSB Input type Resolution Conversion time Accuracy at 25 °C Accuracy at 55 °C Repeat accuracy at 55 °C Isolation between analogue channel and power supply Cable length Protection against polarity inversions Potentiometer control  Inputs used as digital inputs Input voltage Input current  Input impedance Logic 1 voltage threshold Making current at logic state 1 Logic 0 voltage threshold Release current at logic state 0 Response time Maximum counting frequency  Sensor type Conforming to IEC/EN 61131-2 Input type	(0 →10 V) or (0 →V power supply)  14 kΩ  14.4 V DC max.  14 mV, 4 mA  Common mode  10 bits at max. input voltage  Controller cycle time  ± 5 %  ± 6.2 %  ± 2 %  None  10 m maximum, with shielded cable (sensor Yes  2.2 kΩ/0.5 W (recommended)  10 kΩ max.  12 V DC (-13 % / +20 %)  0.7 mA @ 10.44 VDC  0.9 mA @ 12.0 VDC  1.0 mA @ 14.4VDC  14 kΩ  ≥ 7 V DC  ≥ 0.5 mA  ≤ 3 V DC  ≤ 0.2 mA  1 →2 cycle times  In accordance with cycle time (Tc) and inpu 1/ ((2 x Tc) + Tr)  Contact or 3-wire PNP  Type 1  Resistive		$(0 \rightarrow 10 \text{ V}) \text{ or } (0 \rightarrow \text{V power supply})$ $12 \text{ k}\Omega$ $30 \text{ V DC max.}$ $29 \text{ mV, 4 mA}$ $Common mode$ $10 \text{ bits at max. input voltage}$ $Controller cycle time$ $\pm 5 \%$ $\pm 6.2 \%$ $\pm 2 \%$ $None$ $10 \text{ m maximum, with shielded cable (sensor not isolated)}$ $\text{Yes}$ $2.2 \text{ k}\Omega/0.5 \text{ W (recommended)}$ $10 \text{ k}\Omega \text{ max.}$ $24 \text{ V DC } (-20 \% / +25 \%)$ $1.6 \text{ mA} @ 19.2 \text{ VDC}$ $2.0 \text{ mA} @ 24.0 \text{ V DC}$ $2.5 \text{ mA} @ 30.0 \text{ VDC}$ $12 \text{ k}\Omega$ $\geq 15 \text{ VDC}$ $\geq 1.2 \text{ mA}$ $\leq 5 \text{ V DC}$ $\leq 0.5 \text{ mA}$ $1 \rightarrow 2 \text{ cycle times}$ $1 \text{ accordance with cycle time (Tc) and input response time (Tr) : 1/((2 \times \text{Tc}) + \text{Tr})$ $Contact \text{ or 3-wire PNP}$ $Type 1$ $Resistive$
Inputs used as analogue inputs  Measurement range Input impedance Input voltage  Value of LSB Input type Resolution Conversion time Accuracy at 25 °C Accuracy at 55 °C Isolation between analogue channel and power supply Cable length Protection against polarity inversions Potentiometer control  Inputs used as digital inputs Input voltage Input current  Input impedance Logic 1 voltage threshold Making current at logic state 1 Logic 0 voltage threshold Release current at logic state 0 Response time Maximum counting frequency  Sensor type Conforming to IEC/EN 61131-2 Input type Isolation between power supply and inputs	$(0 \rightarrow 10 \text{ V}) \text{ or } (0 \rightarrow \text{V power supply})$ 14 k $\Omega$ 14.4 V DC max.  14 mV, 4 mA  Common mode  10 bits at max. input voltage  Controller cycle time $\pm 5 \%$ $\pm 6.2 \%$ $\pm 2.2 \%$ None  10 m maximum, with shielded cable (sensor Yes)  2.2 k $\Omega$ /0.5 W (recommended)  10 k $\Omega$ max.   12 V DC (-13 % / +20 %)  0.7 mA @ 10.44 VDC  0.9 mA @ 12.0 VDC  1.0 mA @ 14.4VDC  14 k $\Omega$ $\geq$ 7 V DC $\geq$ 0.5 mA $\leq$ 3 V DC $\leq$ 0.2 mA  1 $\rightarrow$ 2 cycle times  In accordance with cycle time (Tc) and inputal I/ ((2 x Tc) + Tr)  Contact or 3-wire PNP  Type 1  Resistive  None		(0 →10 V) or (0 →V power supply)  12 kΩ  30 V DC max.  29 mV, 4 mA  Common mode  10 bits at max. input voltage  Controller cycle time  ± 5 %  ± 6.2 %  ± 2.2 %  None  10 m maximum, with shielded cable (sensor not isolated)  Yes  2.2 kΩ/0.5 W (recommended)  10 kΩ max.  24 V DC (-20 % / +25 %)  1.6 mA @ 19.2 VDC  2.0 mA @ 24.0 V DC  2.5 mA @ 30.0 VDC  12 kΩ  ≥ 15 VDC  ≥ 1.2 mA  ≤ 5 V DC  ≤ 0.5 mA  1 →2 cycle times  In accordance with cycle time (Tc) and input response time (Tr)  1/ ( (2 x Tc) + Tr)  Contact or 3-wire PNP  Type 1  Resistive  None
Inputs used as digital inputs Input voltage Input current  Input impedance Logic 1 voltage threshold Making current at logic state 1 Logic 0 voltage threshold Release current at logic state 0 Response time Maximum counting frequency  Sensor type Conforming to IEC/EN 61131-2 Input type Isolation between power supply and inputs Isolation between inputs	$(0 \rightarrow 10 \text{ V}) \text{ or } (0 \rightarrow \text{V power supply})$ 14 k $\Omega$ 14.4 V DC max.  14 mV, 4 mA  Common mode  10 bits at max. input voltage  Controller cycle time $\pm 5\%$ $\pm 6.2\%$ $\pm 2\%$ None  10 m maximum, with shielded cable (sensor Yes)  2.2 k $\Omega$ /0.5 W (recommended)  10 k $\Omega$ max.   12 V DC (-13 % / +20 %)  0.7 mA @ 10.44 VDC  0.9 mA @ 12.0 VDC  1.0 mA @ 14.4VDC  14 k $\Omega$ $\geq 7$ V DC $\geq 0.5$ mA $\leq 3$ V DC $\leq 0.2$ mA  1 $\rightarrow 2$ cycle times  In accordance with cycle time (Tc) and inputation of the control of the cycle time (Tc) and inputation of the cycle tim		(0 →10 V) or (0 →V power supply)  12 kΩ  30 V DC max.  29 mV, 4 mA  Common mode  10 bits at max. input voltage  Controller cycle time  ± 5 %  ± 6.2 %  ± 2 %  None  10 m maximum, with shielded cable (sensor not isolated)  Yes  2.2 kΩ/0.5 W (recommended)  10 kΩ max.  24 V DC (-20 % / +25 %)  1.6 mA @ 19.2 VDC  2.0 mA @ 24.0 V DC  2.5 mA @ 30.0 VDC  12 kΩ  ≥ 15 VDC  ≥ 1.2 mA  ≤ 5 V DC  ≤ 0.5 mA  1 →2 cycle times  In accordance with cycle time (Tc) and input response time (Tr)  1/ ((2 x Tc) + Tr)  Contact or 3-wire PNP  Type 1  Resistive  None  None
Inputs used as analogue inputs  Measurement range Input impedance Input voltage  Value of LSB Input type Resolution Conversion time Accuracy at 25 °C Accuracy at 55 °C Isolation between analogue channel and power supply Cable length Protection against polarity inversions Potentiometer control  Inputs used as digital inputs Input voltage Input current  Input impedance Logic 1 voltage threshold Making current at logic state 1 Logic 0 voltage threshold Release current at logic state 0 Response time Maximum counting frequency  Sensor type Conforming to IEC/EN 61131-2 Input type Isolation between power supply and inputs	$(0 \rightarrow 10 \text{ V}) \text{ or } (0 \rightarrow \text{V power supply})$ 14 k $\Omega$ 14.4 V DC max.  14 mV, 4 mA  Common mode  10 bits at max. input voltage  Controller cycle time $\pm 5 \%$ $\pm 6.2 \%$ $\pm 2.2 \%$ None  10 m maximum, with shielded cable (sensor Yes)  2.2 k $\Omega$ /0.5 W (recommended)  10 k $\Omega$ max.   12 V DC (-13 % / +20 %)  0.7 mA @ 10.44 VDC  0.9 mA @ 12.0 VDC  1.0 mA @ 14.4VDC  14 k $\Omega$ $\geq$ 7 V DC $\geq$ 0.5 mA $\leq$ 3 V DC $\leq$ 0.2 mA  1 $\rightarrow$ 2 cycle times  In accordance with cycle time (Tc) and inputal I/ ((2 x Tc) + Tr)  Contact or 3-wire PNP  Type 1  Resistive  None		(0 →10 V) or (0 →V power supply)  12 kΩ  30 V DC max.  29 mV, 4 mA  Common mode  10 bits at max. input voltage  Controller cycle time  ± 5 %  ± 6.2 %  ± 2.2 %  None  10 m maximum, with shielded cable (sensor not isolated)  Yes  2.2 kΩ/0.5 W (recommended)  10 kΩ max.  24 V DC (-20 % / +25 %)  1.6 mA @ 19.2 VDC  2.0 mA @ 24.0 V DC  2.5 mA @ 30.0 VDC  12 kΩ  ≥ 15 VDC  ≥ 1.2 mA  ≤ 5 V DC  ≤ 0.5 mA  1 →2 cycle times  In accordance with cycle time (Tc) and input response time (Tr)  1/ ( (2 x Tc) + Tr)  Contact or 3-wire PNP  Type 1  Resistive  None

Max. breaking voltage	5 →30 V DC 24 →250 V AC	
New Output Comment		
Max. Output Common Current	12A (10A UL) for O8, O9, OA	
Breaking current	CB-CD-XD10-XB10-XR06-XR10 : 8 A XD26-XB26 : 8 x 8 A relays, 2 x 5 A relays	
	XE10: 4 x 5 A relays	
	XR14: 4 x 8 A relays, 2 x 5 A relays	
Electrical durability for 500 000 operating cycles	Utilization category DC-12: 24 V, 1.5 A Utilization category DC-13: 24 V (L/R = 10 ms), 0.6 A	
	Utilization category AC-12 : 230 V, 1.5 A	
	Utilization category AC-15 : 230 V, 0.9 A	
Minimum switching capacity	10 mA (at minimum voltage of 12 V)	
Minimum load	12 V, 10 mA	
Maximum rate	Off load : 10 Hz	
	At operating current : 0.1 Hz	
Mechanical life	10,000,000 (operations)	
Voltage for withstanding shocks	In accordance with IEC/EN 60947-1 and IEC/EN 60664-1 : 4 kV	
Response time	Make 10 ms	
Puilt in protections	Release 5 ms	
Built-in protections	Against short-circuits : None Against overvoltages and overloads : None	
Status indicator	On LCD screen for CD and XD	
	On EOD GOLOGITION OF GIRD AF	
Digital / PWM solid state output	0040 04	OD40 VD40 VD40 O4
PWM solid state output*	CB12 : O4 XD26 : O4 →O7	CD12-XD10-XB10 : O4 CD20-XD26-XB26 : O4 →O7
* Only available with "FBD" programming language	* Only available with "FBD" programming language	0D20 ND20 ND20 . 04 -701
Breaking voltage	10.4 →30 V DC	19.2 →30 V DC
Nominal voltage	12-24 VDC	24 V DC
Nominal current	0.5 A	0.5 A
Max. breaking current	0.625 A	0.625 A
Voltage drop	≤ 2 V for I = 0.5 A (at state 1)	≤ 2 V for I = 0.5 A (at state 1)
Response time	Make ≤ 1 ms	Make ≤ 1 ms
	Release ≤ 1 ms	Release ≤ 1 ms
Frequency (Hz)		
Built-in protections	Against overloads and short-circuits : Yes	Against overloads and short-circuits : Yes
	Against overvoltages (*) : Yes	Against overvoltages (*): Yes
	Against inversions of power supply : Yes  (*) In the absence of a volt-free contact between the logic	Against inversions of power supply: Yes  (*) In the absence of a volt-free contact between the logic
	controller output and the load	controller output and the load
Min. load	1 mA	1 mA
Maximum incandescent load	0,2 A / 12 V DC	0.1 A / 24 V/DC
	0,1 A / 24 V DC	0,1 A / 24 V DC
Galvanic isolation	No	No
PWM frequency	14.11 Hz	14.11 Hz
	56.45 Hz	56.45 Hz
	112.90 Hz 225.80 Hz	112.90 Hz 225.80 Hz
	451.59 Hz	451.59 Hz
	1806.37 Hz	1806.37 Hz
PWM cyclic ratio	$0 \rightarrow$ 100 % (256 steps for CD, XD and 1024 steps for XA)	$0 \rightarrow 100$ % (256 steps for CD, XD and 1024 steps for XA)
Max. Breaking current PWM	50 mA	50 mA
Max. cable length PWM (m)	20	20
PWM accuracy at 120 Hz	< 5 % (20 % →80 %) load at 10 mA	< 5 % (20 % →80 %) load at 10 mA

#### Accessories

PWM accuracy at 500 Hz

Туре	Description	Code
M3 SOFT	Multilingual programming software containing specific library functions (CD-ROM)	88970111
PA	EEPROM memory cartridge	88970108
PA	3 m serial link cable : PC →Millenium 3	88970102
PA	USB cable 3 m : PC →Millenium 3	88970109
PA	Millenium 3 interface →Bluetooth (class A 10 m)	88970104

< 10 % (20 %  $\rightarrow$ 80 %) load at 10 mA

On LCD screen for XD

< 10 % (20 % →80 %) load at 10 mA

On LCD screen for CD and XD

# Comments

\* to be marketed 1st quarter 2006

### Dimensions (mm)

CB12 Smart

