

SPOC™+2 User Manual

Multichannel SPI High-Side Power Controller

About this document

Scope and purpose

This User Manual is intended to enable users to integrate the SPOC™+2 Software for the SPOC™+2-Demoboard.

Intended audience

This document is intended for anyone using the SPOC™+2 Software.

Document conventions

Table 1 Conventions

Convention	Explanation
Bold	Emphasizes heading levels, column headings, table and figure captions, screen names, windows, dialog boxes , menus and sub-menus
Italics	Denotes variable(s) and reference(s)
Courier New	Denotes APIs, functions, interrupt handlers, events, data types, error handlers, file/folder names, directories, command line inputs, code snippets

Conventions for reading the configuration class field

The following examples help the integrator to identify the configuration class of the parameter for a given delivery type.

Abbreviations and definitions

Table 2 **Abbreviations**

Abbreviation	Definition
SPOC TM +2	SPI Power Controller
SPOC TM +2 MB	SPOC TM +2 Motherboard
SPOC TM +2 DB	SPOC TM +2 Daughterboard
NC	Not Connected
LHI	Limp Home Input
IS	Sense current

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- **μIO-Stick**
 - Communication between your computer and the Demoboard
 - Isar Number: SP001215532
 - See Figure 3



Figure 3 - μIO-Stick

- **Connection cable**
 - Ribbon cable
 - 16 pin female connector
 - See figure 4

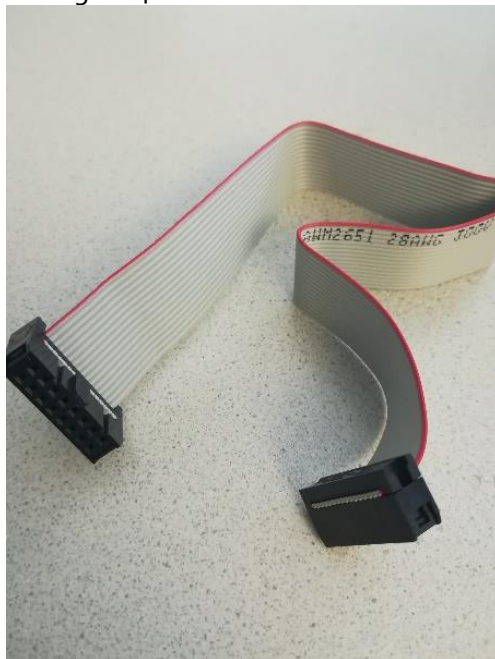


Figure 4 - Connection cable

- **USB-Stick**
 - For software installation
 - See Figure 5



Figure 5 - Software installation USB-Stick

1.2 Software Installation

1.2.1 SPOC™+2 Application

How to install software for the **SPOC™+2 Evaluation Board**:

- Plug in the Software-USB-Stick into a USB port of your computer
- Run **setup.exe** in the following location:
 - **USB-Drive:\SPOC+2_Installer\Volume\setup.exe** (see Figure 6)

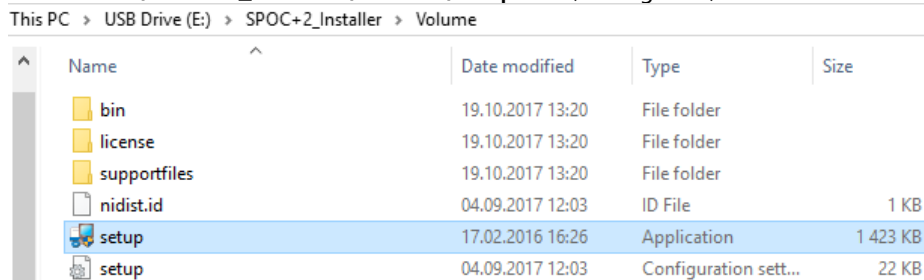


Figure 6 – SPOC™+2 - setup.exe

- Note: You must log in as administrator!
- Follow the steps of the Installation Wizard (see Figures below):
 - Select installation directory, then click "next"

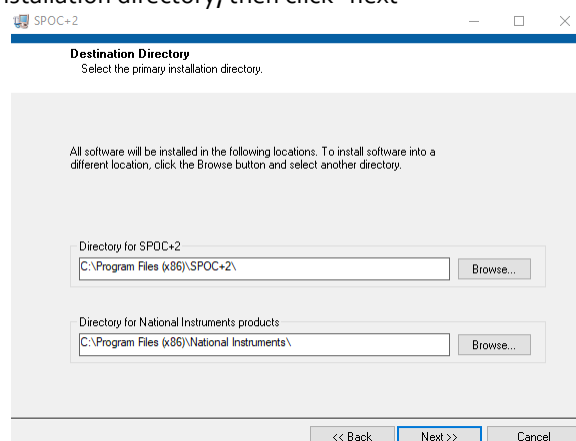


Figure 7 - SPOC™+2 Application - Select Directory

- Again click "next"

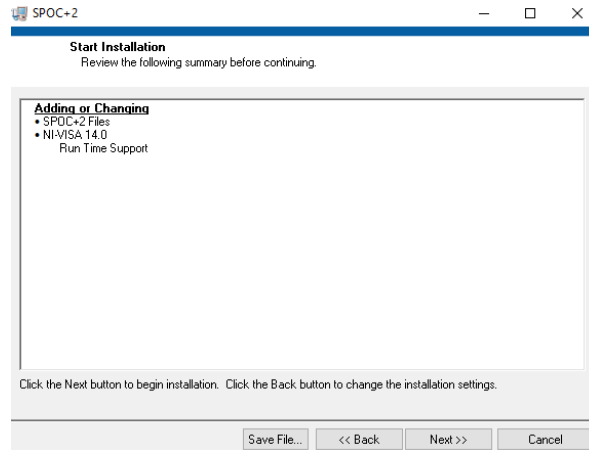


Figure 8 – SPOC™+2 - Application - Start Installation

- The installation will start, after that click „finish“

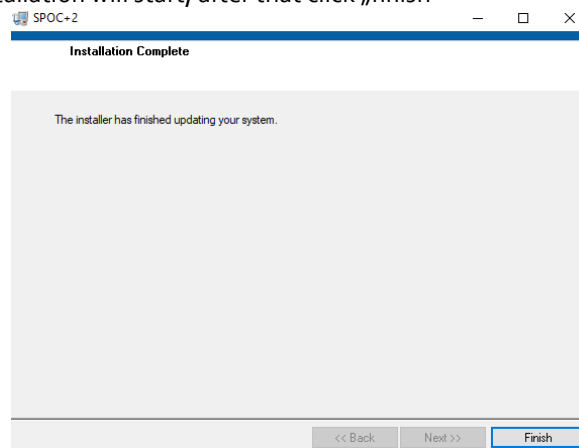


Figure 9 – SPOC™+2 - Application – Finish

1.2.2 μ IO-Stick Driver Install

After installing the SPOC™+2-Application keep the Software-USB plugged in and plug in the μ IO-Stick. In order to use the virtual COM-port (neccesairly for the application) go to <https://www.ehitex.de/usb-application-sticks/infineon/2529/uio-stick>, scroll to **Available Downloads** and select **Download uIO Updater (zip file)** see Figure 10. Extract the zip file and run *UpdatePEK* afterwards.

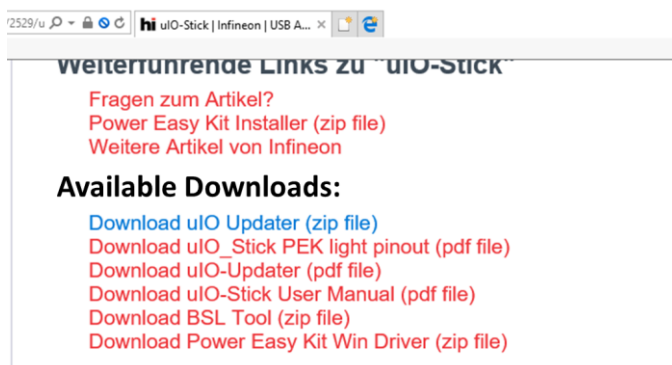


Figure 10 - μ IO-Updater (for vCOM)

1.3 Setup Hardware

- Plug the SPOC™+2 DB onto the SPOC™+2 MB (see Figure 11)

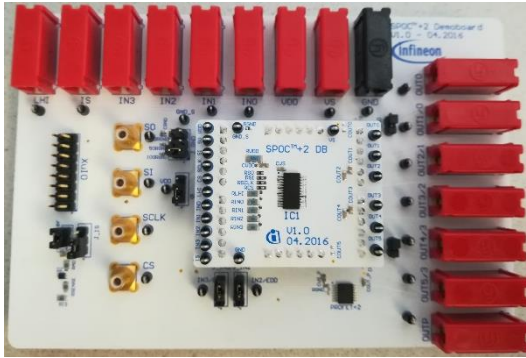


Figure 11 – SPOC™+2 DB plugged onto SPOC™+2 MB

- Connect the μ IO-Stick to the SPOC™+2 MB via the connector cable (see Figure 12)
 - **Be careful:** Position of Pin 1 is marked with a dot on the SPOC™+2 MB!

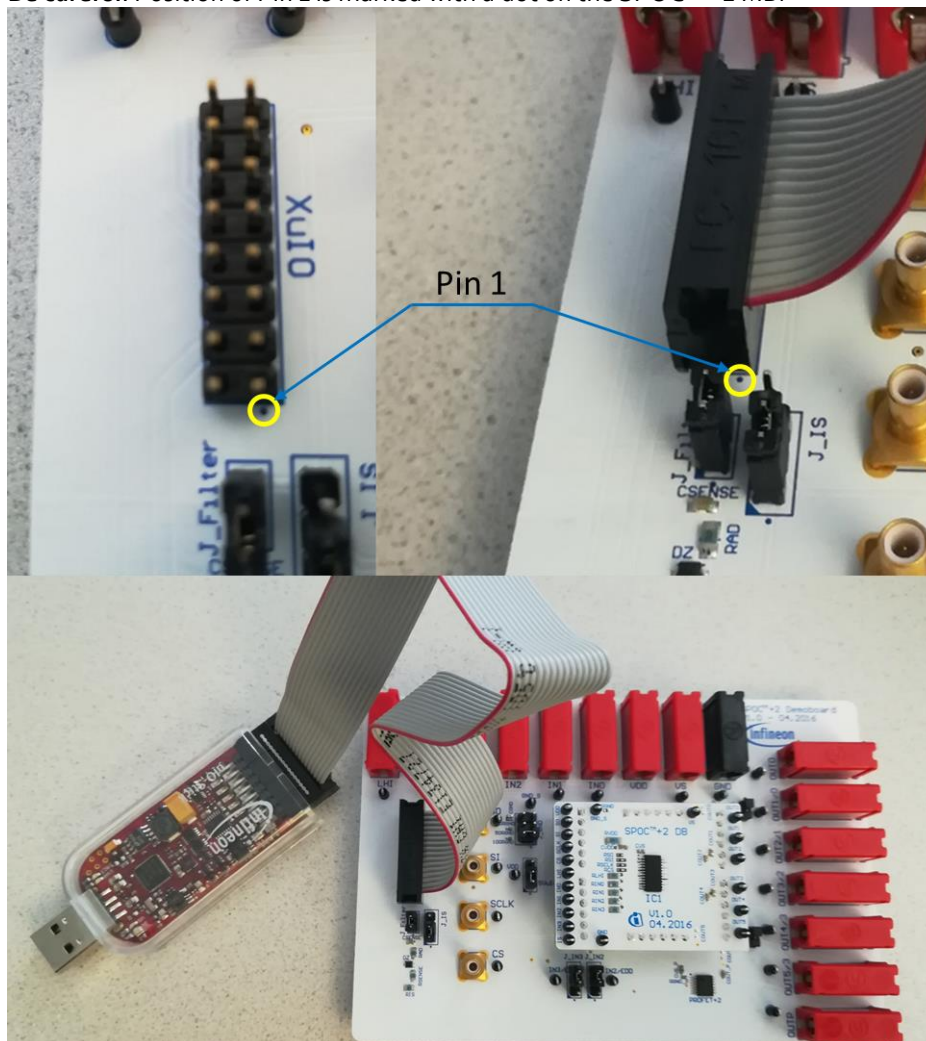


Figure 12 - Connecting μ IO-Stick to SPOC™+2 MB

- Connect the μ IO-Stick to your computer and run the SPOC™+2-Application. (see Figure 13)

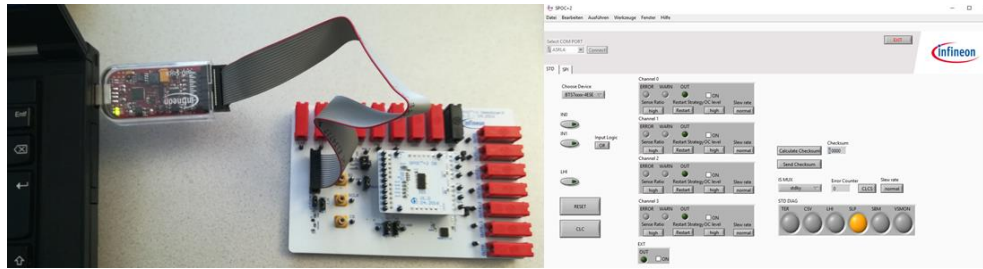


Figure 13 - Finished setup

1.3.1 Setup details

Table 3	
XμIO	
Pin #	
○ 1	NC
○ 2	GND
○ 3	NC
○ 4	+5VμIO
○ 5	NC
○ 6	NC
○ 7	NC
○ 8	IN ₃
○ 9	CS
○ 10	IN ₂
○ 11	SCLK
○ 12	IN ₁
○ 13	SO
○ 14	IN ₀
○ 15	SI
○ 16	Sense
J_Filter	Closed by default
J_IS	1-2 closed by default If 2-3 is closed: - J_Filter has to be opened! - Sense directly switched to IS (Filter disconnected)
J_GND	1-2 closed: R_GND = 150 Ω (default) 3-4 closed: R_GND = 50 Ω 5-6 closed: R_GND = 0 Ω
J_IN ₂	3-2 closed by default. If 1-2 is closed: Connect PROFET ²
J_IN ₃	3-2 closed by default. If 1-2 is closed: Connect PROFET ²
J_VDD	1-2 closed (default VDD via μIO-Stick): - Use +5VμIO (USB) as digital supply voltage 2-3 closed: - VDD via external supply
J_cho ¹	Closed if 4 Channel SPOC TM +2 is used:

	OUT₀ and OUT_{1/0} in parallel.
J_ch3 ¹	Closed if 4 Channel SPOC+2 is used: OUT_{4/3} and OUT_{5/3} in parallel.
SO	Slave Out (SPI Interface)
SI	Slave In (SPI Interface)
SCLK	Serial Clock (SPI Interface)
CS	Chip Select (SPI Interface)
IN ₀	activate the corresponding output channel
IN ₁	activate the corresponding output channel
IN ₂ /EDD ²	activate the corresponding output channel
IN ₃ /EDO ²	activate the corresponding output channel
OUT ₀	Output channel 0
OUT _{1/0} ¹	Output channel 1 if J_ch0 is open, Output channel 0 if J_ch0 is closed
OUT _{2/1} ¹	Output channel 2 if J_ch0 is open, Output channel 1 if J_ch0 is closed
OUT _{3/2} ¹	Output channel 3 if J_ch0 is open, Output channel 2 if J_ch0 is closed
OUT _{4/3} ¹	Output channel 4 if J_ch3 is open, Output channel 3 if J_ch3 is closed
OUT _{5/3} ¹	Output channel 5 if J_ch3 is open, Output channel 3 if J_ch3 is closed
OUTP	Output PROFET ²
IS	Sense current
LIH	Limp Home Input
VDD	Digital supply voltage
GND	Ground
VS	Supply voltage

¹ If 4-Channel-SPOC™ are used J_ch0 and J_ch3 had to be closed, otherwise (6-Channel-SPOC) opened.

² If Jumpers J_IN2 and J_IN3 are set to 1-2: SPOC™ Outputs EDD and EDO can control the PROFET.

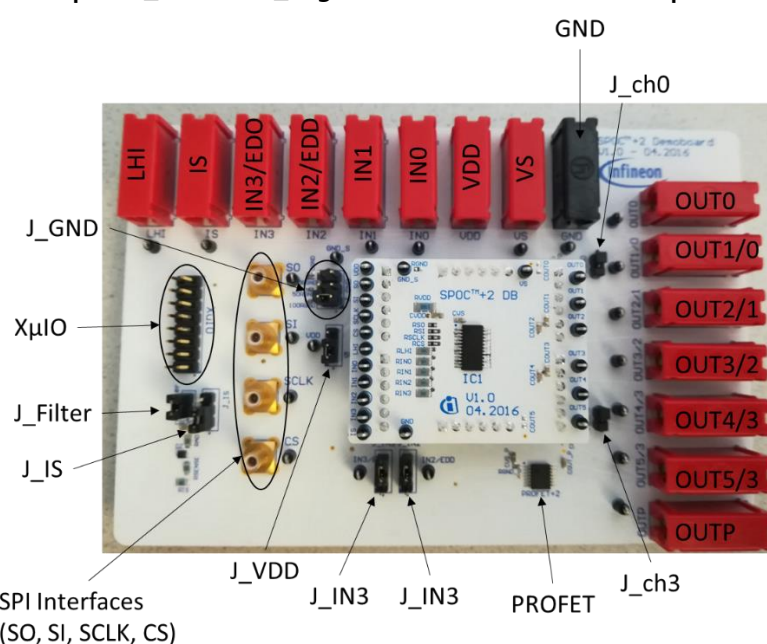


Figure 14 - Device components

2 Using the software

2.1 Starting the program

- Installed Application can be found in the windows start menu in the section "all programs" → "SPOC+2" → SPOC+2 (see Figure 15):

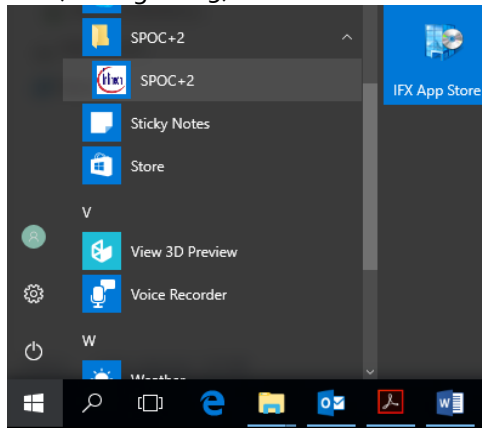


Figure 15 - SPOC+2 - Application - Finding it

or by using the search bar (see Figure 16):

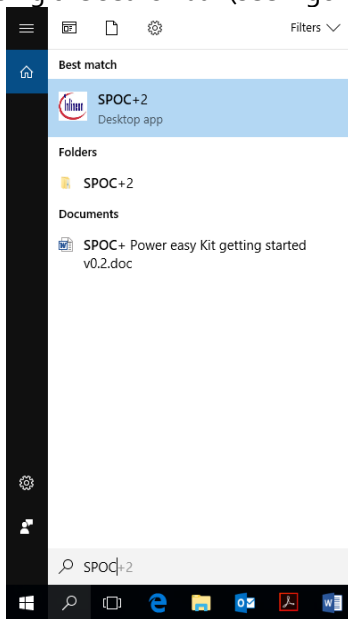


Figure 16 – SPOCTM+2 - Application - searching for it

- Run the program by clicking on the file (see Figures 15 and 16)

2.2 User Interface

2.2.1 STD-View

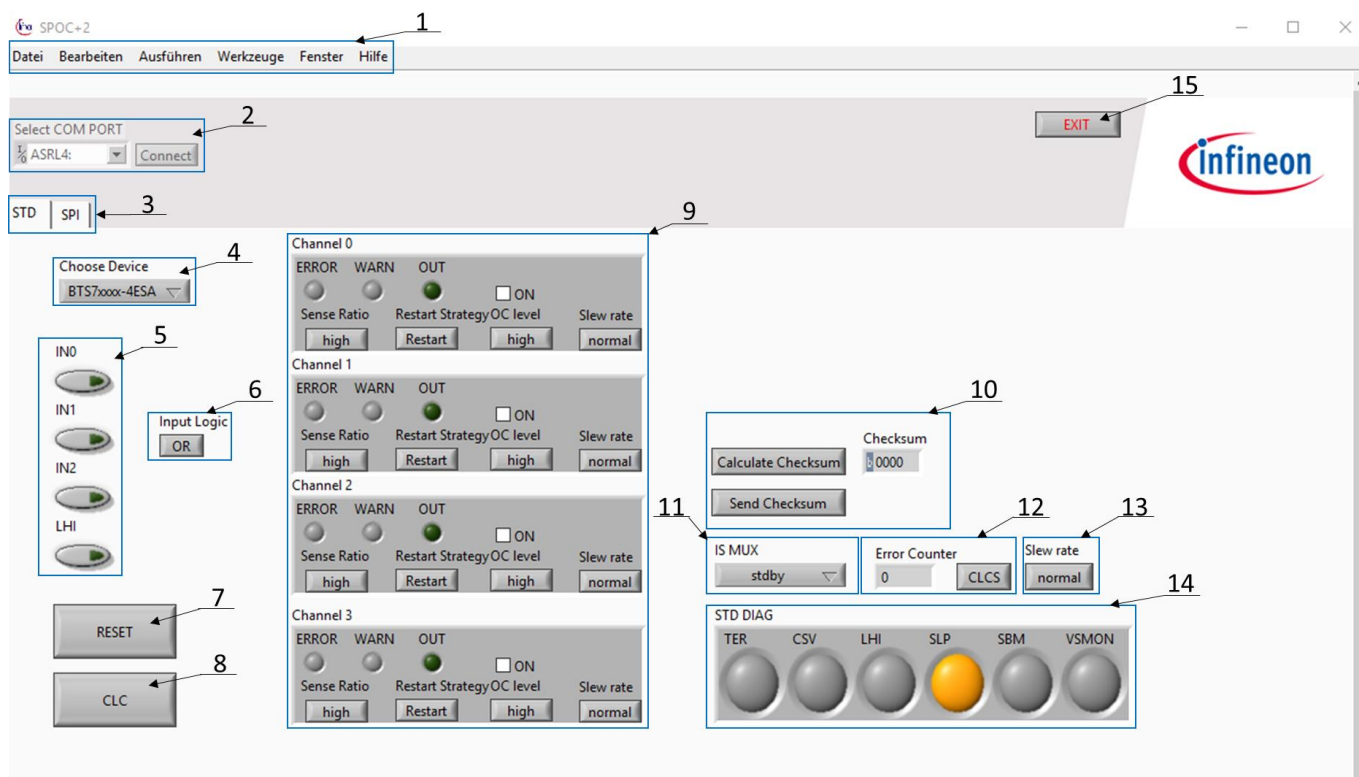


Figure 17 - User Interface - STD-View

Table 4 - STD-View

1	Menu bar	*
2	Port selection	Software should detect the Comport automatically. If not: select the needed Comport.
3	Standard or SPI view	Change between a button based control(Figure 17) and a low level SPI command control(Figure 18)
4	Device selection	Select the used device type
5	Direct inputs and LHI	- Switch IN0-IN2 on or off - LHI can be set on or off
6	Input logics	OR/AND operation between direct inputs (IN0-IN3) with the channel's on-status (channel 0 to 3)
7	Reset	Reset SPOC TM +2
8	Clear	Clear all Error latches and error counter
9	Channels	Indicates the Status of a channel (Error, Warn, OUT, Slew rate) and configures the channel (ON, Sense ratio, Restart Strategy, OC level)
10	Checksum	Shows the calculated checksum reflecting the configuration. This value will be transmitted when clicking on send checksum.
11	IS MUX	Configure the mux setting. For more information see datasheet of SPOC TM +2
12	Error counter	Error counter of the selected channel
13	Slew rate settings	configures the slew rate of the selected channel
14	Status display	Visualizes the standard diagnosis (spi response)
15	Exit button	Closes connection and program

2.2.2 SPI-View

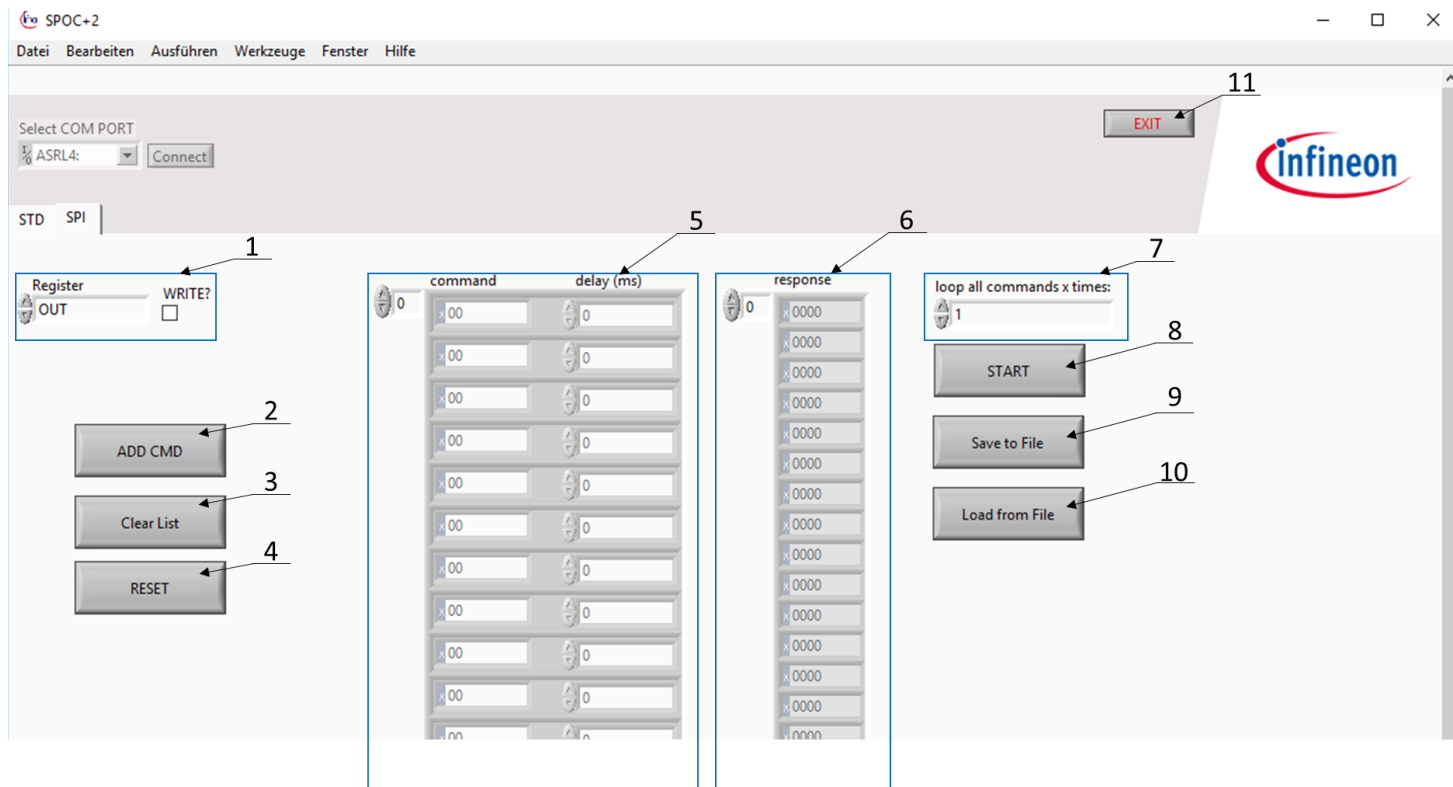


Figure 18 - User Interface - SPI-View

Table 5 - SPI-View

1	Register selection	Select the register address and in case WRITE is enabled the content for the next spi command. If WRITE is disabled a read command will be added.
2	Add command	Adds the composed command to the command list (see 8)
3	Clear command list	Clears the content of the command list
4	Reset	Resets SPOC TM +2
5	Command list	Displays all added commands in ascending order
6	Response list	Displays SPOC TM +2's response to the currently processed command (see datasheet of the used SPOC TM +2)
7	Loop configuration	Commands are embedded in a loop Change the number of iterations (default is 1)
8	Start button	Starts the command sequence resp. the loop
9	Save to file	Saves the command sequence to a file
10	Load from File	Loads a saved command sequence from a file
11	Exit button	Closes connection and program

*...menu description not necessary at the moment → Tobias

2.3 Examples: Command sequences, SPI-View

Figure 19 below illustrates a possible test setup. The examples in 2.3.1 and 2.3.2 refer to this setup.

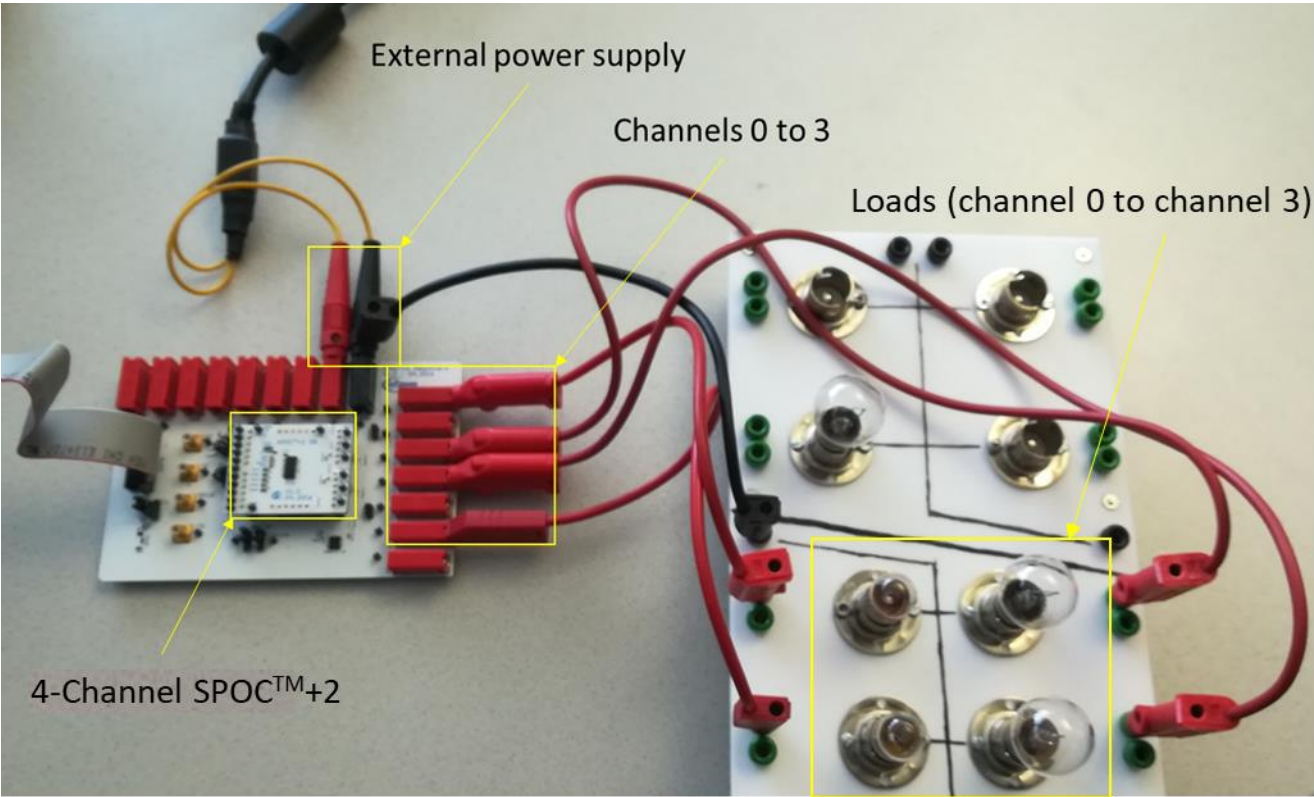


Figure 19 - Possible setup

2.3.1 Example 1: Switching on 4 lights step by step with 1 Second delay

- Switch to SPI view and select register OUT (See Figure 20)

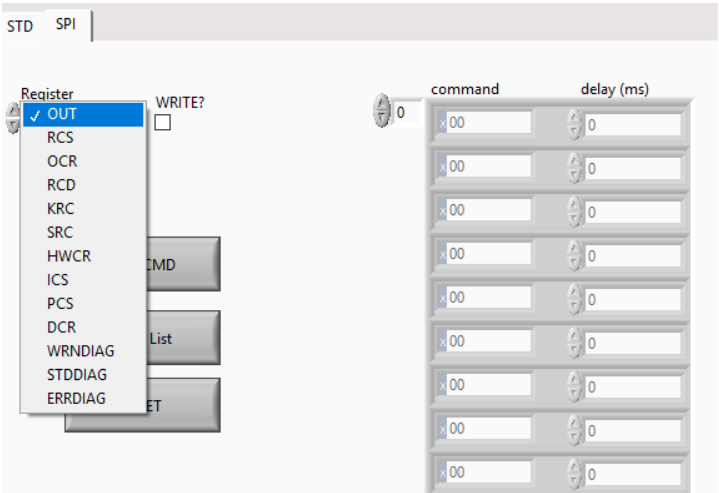
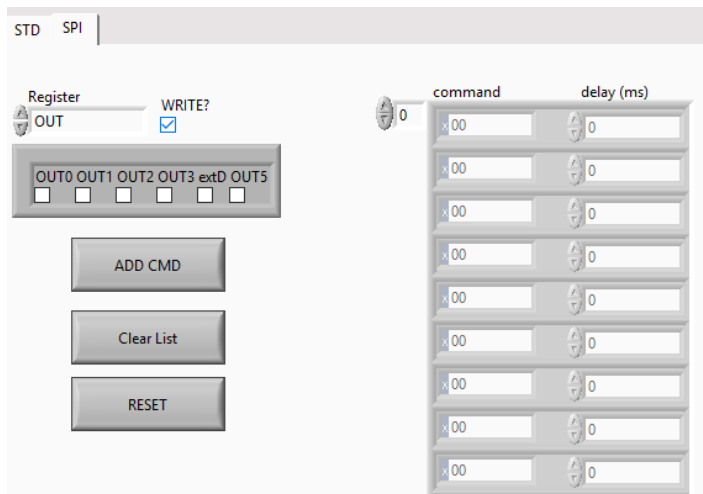


Figure 20 - Select register OUT

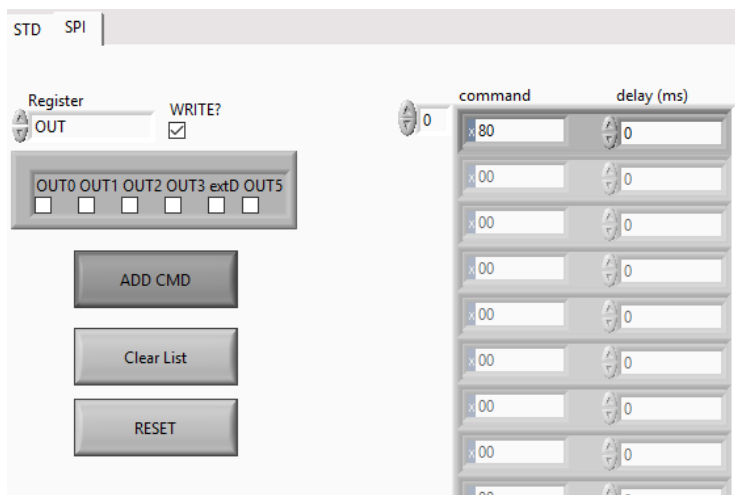
- Tick the WRITE?-Box and select no Output (See Figure 21)



The interface shows the 'STD' and 'SPI' tabs. Under 'Register', 'OUT' is selected. The 'WRITE?' checkbox is checked. Below the register selection, there are checkboxes for 'OUT0', 'OUT1', 'OUT2', 'OUT3', 'extD', and 'OUT5'. The 'ADD CMD' button is visible. The command list on the right is empty, showing a table with columns 'command' and 'delay (ms)'.

Figure 21 - Write to register OUT

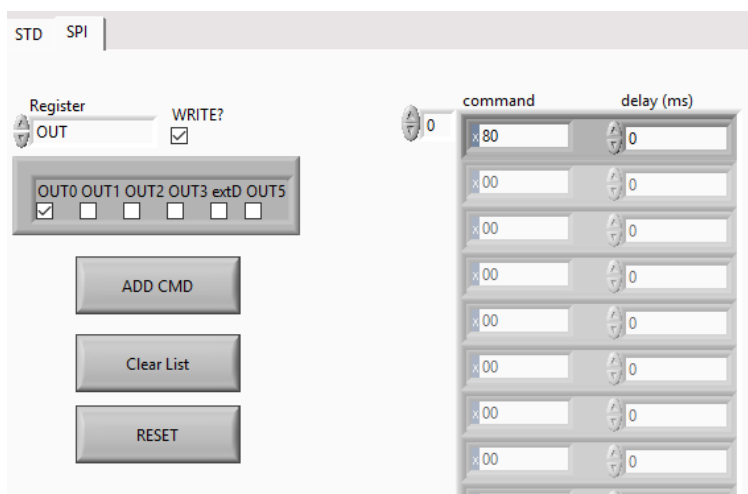
- Click ADD CMD and your command is added to the command list (See Figure 22)



The interface is the same as Figure 21, but the 'ADD CMD' button has been clicked. The command list now contains one entry with 'command' 'x 80' and 'delay (ms)' '0'.

Figure 22 - Add command to command list

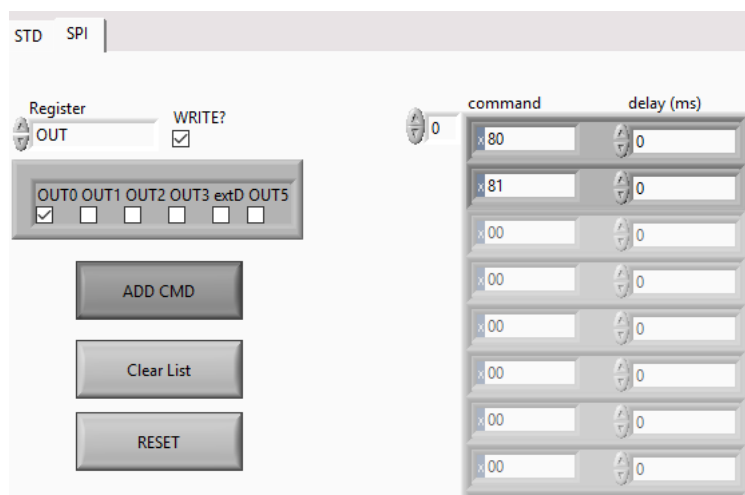
- Select OUT0 in the WRITE-Box (See Figure 23)



The interface shows the 'Register' dropdown set to 'OUT0'. The 'WRITE?' checkbox is checked. The 'OUT0' checkbox under the register selection is also checked. The command list on the right still contains the entry from Figure 22.

Figure 23 - Write OUT0

- Click ADD CMD (See Figure 24)



STD SPI

Register: OUT WRITE? ☒

OUT0 OUT1 OUT2 OUT3 extD OUT5

☒ ☐ ☐ ☐ ☐ ☐

ADD CMD

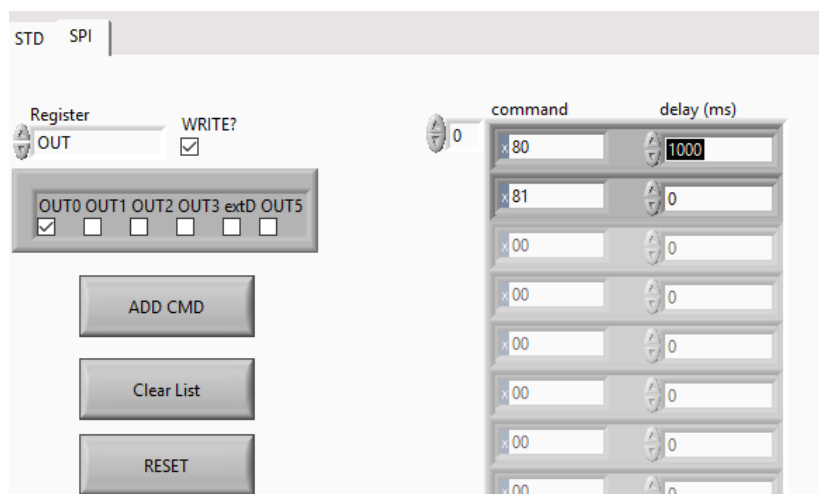
Clear List

RESET

command	delay (ms)
x80	0
x81	0
x00	0
x00	0
x00	0
x00	0
x00	0
x00	0

Figure 24 - Add to command list

- Change the delay of each command to 1000 (delay of 1 second, See Figure 25)



STD SPI

Register: OUT WRITE? ☒

OUT0 OUT1 OUT2 OUT3 extD OUT5

☒ ☐ ☐ ☐ ☐ ☐

ADD CMD

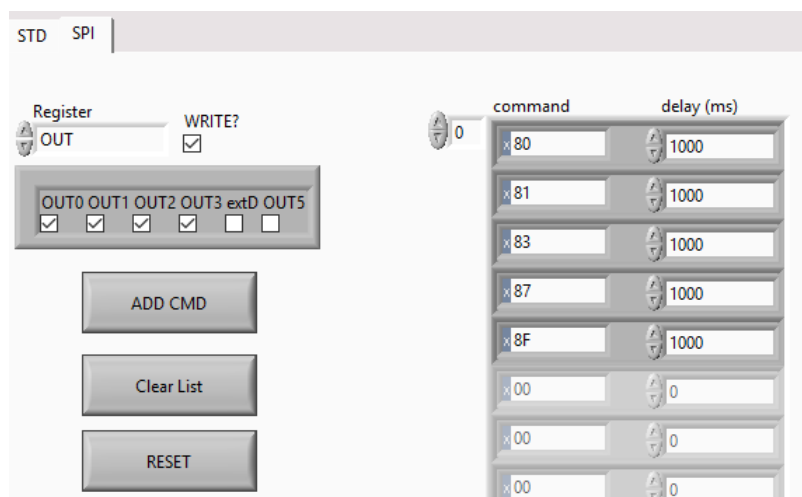
Clear List

RESET

command	delay (ms)
x80	1000
x81	0
x00	0
x00	0
x00	0
x00	0
x00	0
x00	0

Figure 25 - change delay of cammands

- Repeat the last three steps until you reach OUT₃ (See Figure 26)



STD SPI

Register: OUT WRITE? ☒

OUT0 OUT1 OUT2 OUT3 extD OUT5

☒ ☒ ☒ ☒ ☐ ☐

ADD CMD

Clear List

RESET

command	delay (ms)
x80	1000
x81	1000
x83	1000
x87	1000
x8F	1000
x00	0
x00	0
x00	0

Figure 26 - repeat until all OUTS (OUT0-OUT3) are selected

- Switch to STD view (See Figure 27) and select a channel (0 – 3) at IS MUX (See Figure 28)

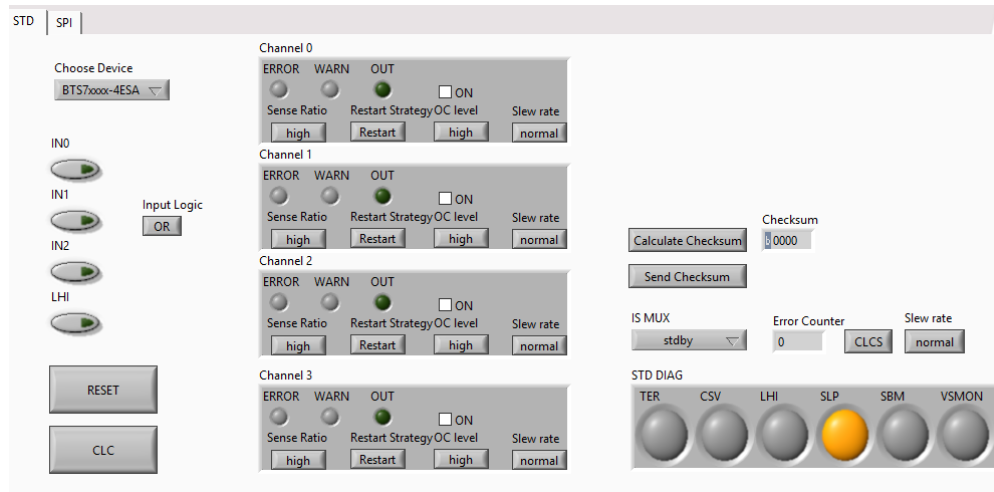


Figure 27 - switch to STD view

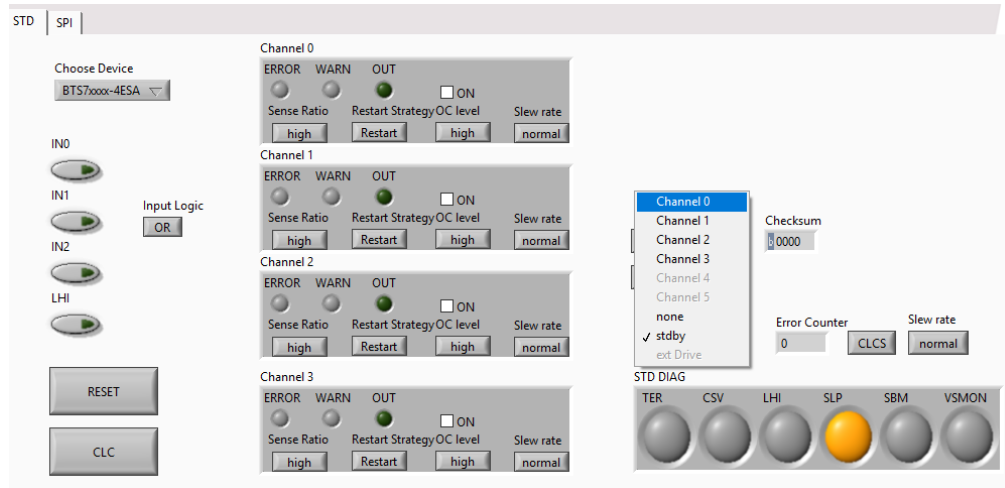


Figure 28 - Select channel at IS MUX

- Switch back to SPI view and click the START-button (See Figure 29)

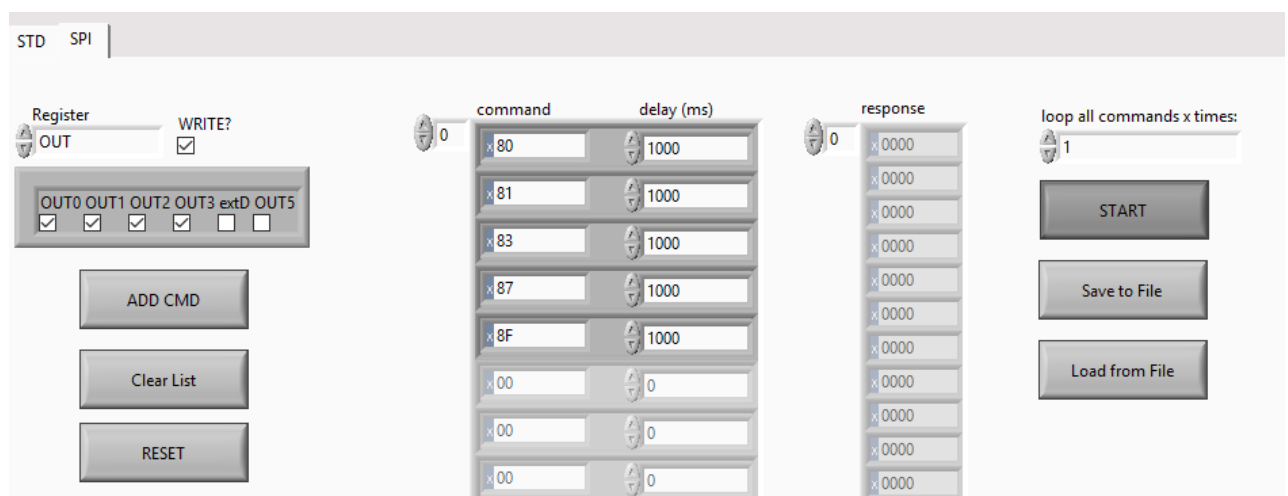


Figure 29 - Start command sequence

- The response of the SPOC™+2 is shown in the response list (See Figure 30)

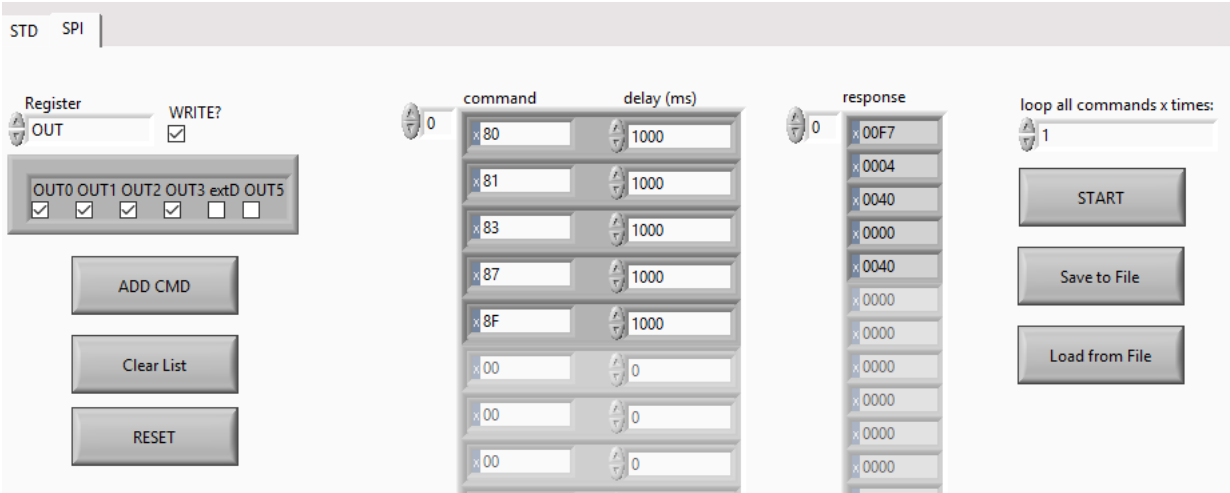


Figure 30 - response of SPOC™+2 to command sequence

2.3.2 Example 2: Let one light blink 10 times

	Description	t [ms]
T_ON	Duration light on	500
T_OFF	Duration light off	500

- Switch to SPI view and select register OUT (See Figure 31)

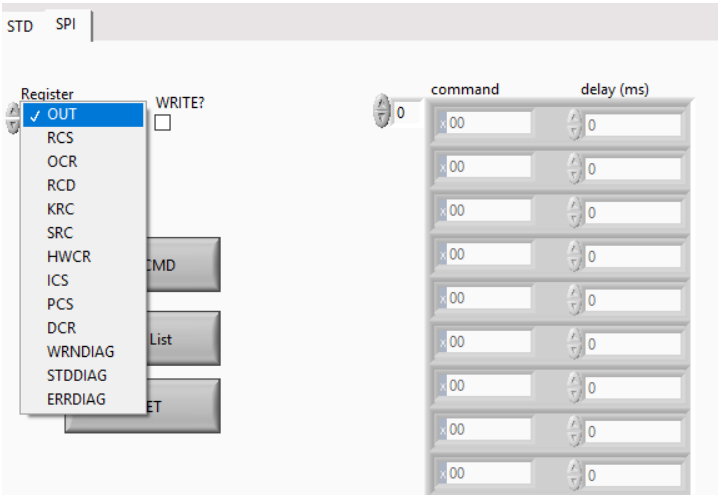
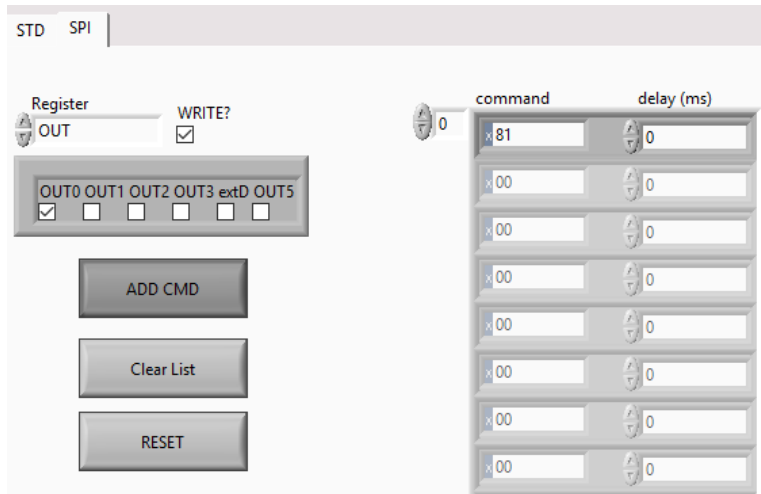


Figure 31 - Select Register OUT

- Tick the WRITE?-Box and select OUT0 and click ADD CMD (See Figure 32)

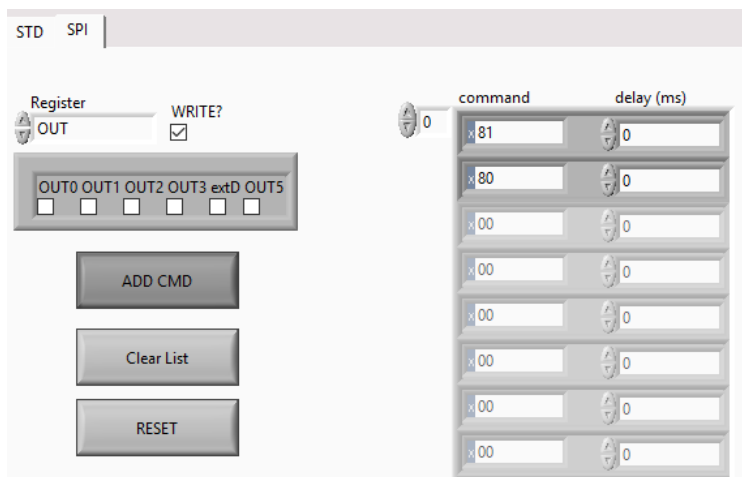


The screenshot shows the 'STD' and 'SPI' tabs. Under 'Register', 'OUT' is selected. The 'WRITE?' checkbox is checked. Below, a row of checkboxes for 'OUT0', 'OUT1', 'OUT2', 'OUT3', 'extD', and 'OUT5' is shown, with 'OUT0' checked. To the right, a table lists commands and delays:

command	delay (ms)
81	0
00	0
00	0
00	0
00	0
00	0
00	0
00	0

Figure 32 - Select OUT0 and add command

- Select no output in the WRITE-Box and click ADD CMD (See Figure 33)



The screenshot shows the 'STD' and 'SPI' tabs. Under 'Register', 'OUT' is selected. The 'WRITE?' checkbox is checked. Below, a row of checkboxes for 'OUT0', 'OUT1', 'OUT2', 'OUT3', 'extD', and 'OUT5' is shown, with none checked. To the right, a table lists commands and delays:

command	delay (ms)
81	0
80	0
00	0
00	0
00	0
00	0
00	0
00	0

Figure 33 - Select no output and add command

- Also typing in commands directly is possible (See SPOCTM+2 datasheet for command reference)
 - E.g.:
 - The command 80_h means *Write no output to OUT*
 - The command 81_h would mean *Write to OUT and set OUT0 high.*
 - See Figure 32 above
- Change the delay of command 81 to T_ON, the delay of command 80 to T_OFF (See Figure 34)



- Register

OUT

WRITE?

☒

OUT0

OUT1

OUT2

OUT3

extD

OUT5

☐

☐

☐

☐

☐

☐

ADD CMD

Clear List

RESET

command

delay (ms)

response

command	delay (ms)	response
x 81	500	x 0000
x 80	500	x 0000
x 00	0	x 0000
x 00	0	x 0000
x 00	0	x 0000
x 00	0	x 0000
x 00	0	x 0000
x 00	0	x 0000
x 00	0	x 0000
x 00	0	x 0000

loop all commands x times:

10

START

Save to File

Load from File

STD

SPI

Choose Device

BTS7xxxx-4ESA

IN0

IN1

IN2

LHI

Input Logic

OR

RESET

CLC

Channel 0

ERROR

WARN

OUT

ON

Sense Ratio

Restart Strategy

OC level

Slew rate

high

Restart

high

normal

Channel 1

ERROR

WARN

OUT

ON

Sense Ratio

Restart Strategy

OC level

Slew rate

high

Restart

high

normal

Channel 2

ERROR

WARN

OUT

ON

Sense Ratio

Restart Strategy

OC level

Slew rate

high

Restart

high

normal

Channel 3

ERROR

WARN

OUT

ON

Sense Ratio

Restart Strategy

OC level

Slew rate

high

Restart

high

normal

Checksum

Calculate Checksum

0000

Send Checksum

IS MUX

stdby

Error Counter

0

CLCS

Slew rate

normal

STD DIAG

TER

CSV

LHI

SLP

SBM

VSMON

Version 1.0
2017-11

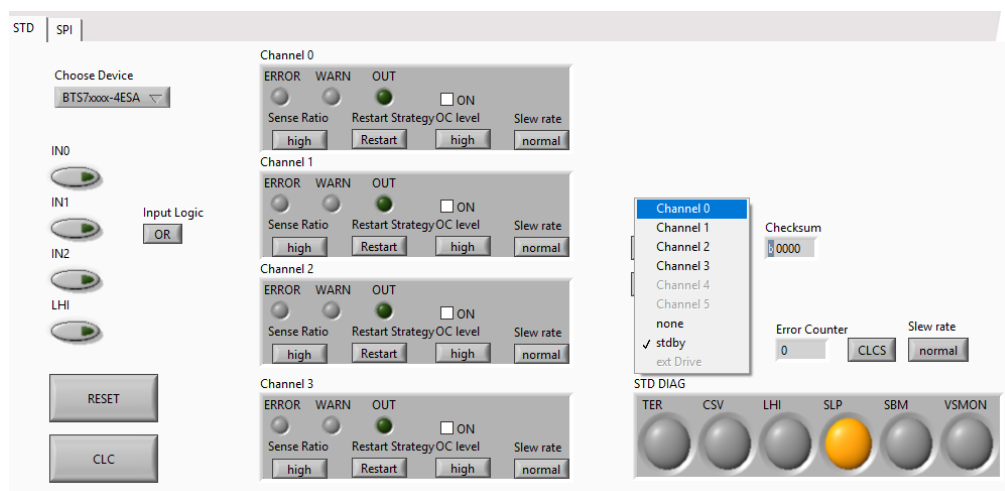


Figure 37 - Select a channel at IS MUX

- Switch back to SPI view and click the START-button (See Figure 38)

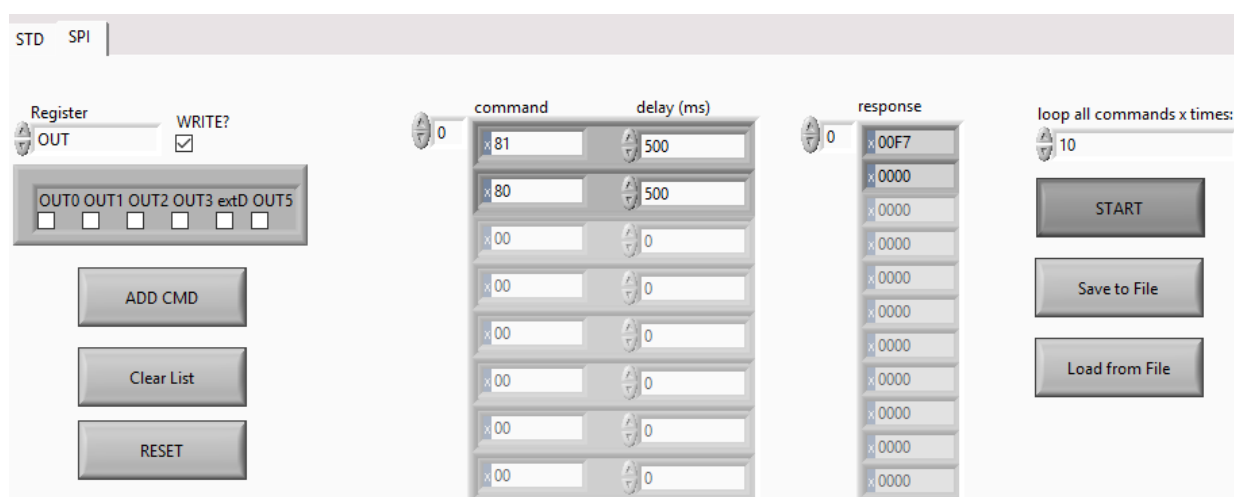


Figure 38 - Switch to SPI and start command sequence

- The response of the SPOCTM+2 is shown in the response list (See Figure 39)

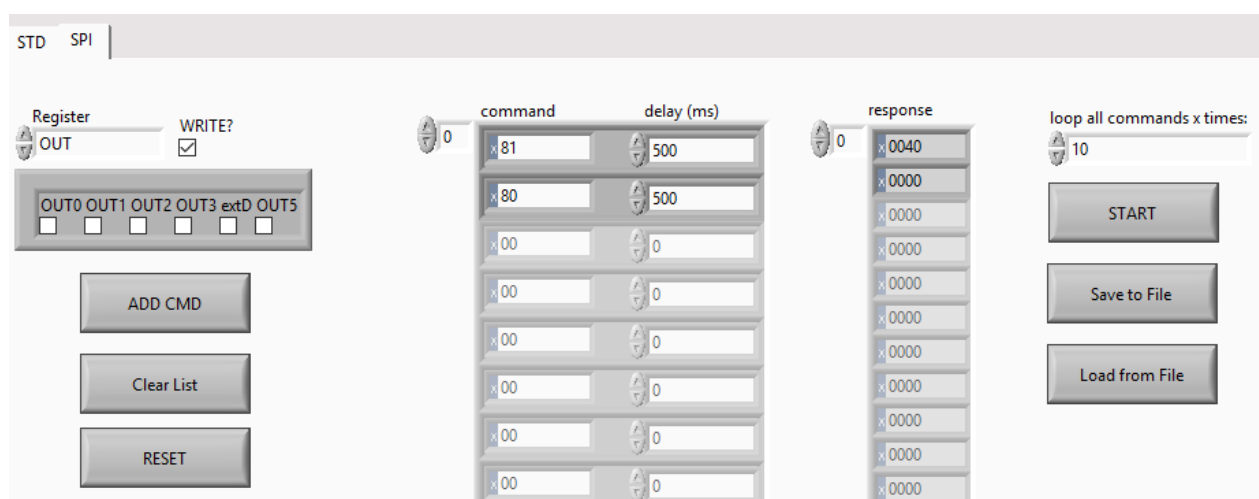


Figure 39 - Response of SPOCTM+2 in response list

Revision history

Major changes since the last revision

Date	Version	Description

Template revision history

Note: The below table is for reference purpose only. Delete this table before circulation.

Changes since the last revision

Date	Version	Author	Description
11-2017	1.0	Rasser René	Initial released version

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