

*Datasheet* Revision 1.8 August 2017



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PI7C9X7952

# **REVISION HISTORY**

Date	Revision Number	Description
10/31/07 0.1		Preliminary Datasheet
		Fixed the diagrams
		Corrected Section 4.2 Pin Description (RREF, GPIO[7])
		Updated Section PCI Express Registers(6.2.42 [3], 6.2.36 UART Driver Setting, 6.2.41 GPIO Control
		Register )
		Revised Section 7.1 Registers in I/O Mode
		Updated Section 11 Ordering Info
12/28/07	0.2	Updated Section 4 Pin Assignment (description for shared pins added, MODE_SEL changed to
		DRIVER_SEL, VAUX changed to VDDCAUX)
		Updated Section 6 PCI Express Register Description (B4h, D0h)
		Updated Section 7 UART Register Description
		Updated Section 8 EEPROM Interface
04/22/08	0.3	Updated 1 Features (Clock prescaler, Data frame size, Power Dissipation)
04/22/08	0.5	
		Corrected 3 General Description
		Updated 4 Pin Assignment (description for shared pins added, MODE_SEL changed to DRIVER_SEL,
		VAUX changed to VDDCAUX, WAKEUP_L, CLKINP, CLKINN)
		Added 5.2.4 Mode Selection, 5.2.5 450/550 Mode, 5.2.6 Enhanced 550 Mode, 5.2.7 Enhanced 950 Mode
		Corrected 5.2.8 Transmit and Receive FIFOs, 5.2.9 Automated Flow Control
		Modified 5.2.12 Baud Rate Generation
		Updated Section 6 PCI Express Register Description (6.2.36, 6.2.42)
		Updated Format (6.2.20, 6.2.36, 6.2.54, 6.2.55, 6.2.57)
		Updated Section 7 UART Register Description (7.1.6 LCR Bit[5:0], 7.1.7 MCR Bit[5] and Bit[7], 7.1.9
		MSR Bit[3:0], 7.2.6 LCR Bit[5:0], 7.2.7 MCR Bit[5] and Bit[7], 7.2.9 MSR Bit[3:0], 7.2.11 DLL, 7.2.12
		DLH, 7.2.13 EFR, 7.2.18 ACR Bit[7:2], 7.2.23 CPRM)
		Updated Section 8.3 EEPROM Space Address Map And Description (00h, 0Ah, 40h)
		Added Section 9 Electrical Specification
		Corrected Section 9.2 DC Specification
		Updated Section 9.3 AC Specification
		Added Section 10 Clock Scheme
08/13/08	0.4	Updated Section 1 Features (added Industrial Temperature Range)
00/15/00	0.4	Updated Section 9.1 Absolute Maximum Ratings: Ambient Temperature with power applied
11/25/09	1.0	
11/25/08	1.0	Updated Section 7.1.13 Sample Clock Register and 7.2.27 Sample Clock Register
		Updated Section 12 Ordering Information
00/06/00		Removed "Preliminary" and "Confidential" references
03/06/09	1.1	Corrected Figure 3.1 PI7C9X7952 Block Diagram (SYN_UART_CLK removed)
		Corrected Section 4.2.1 UART Interface (SYNCLK_IN_EN and SYN_UART_CLK removed)
		Corrected Figure 5.2 Internal Loopback in PI7C7952
		Corrected Figure 5.3 Crystal Oscillator as the Clock Source (14.7456 MHz)
		Corrected Section 7.1.7 Modem Control Register (Bit[5]), 7.1.10 Special Function Register (Bit[4]), 7.2.7
		Modem Control Register (Bit[5]), 7.2.10 Special Function Register (Bit[4]), 7.2.29 Receive FIFO Data
		Registers, 7.2.30 Transmit FIFO Data Register, 7.2.31
04/21/09	1.2	Updated Section 4.2 Pin Description
09/24/09	1.3	Updated Figure 5-3 Crystal Oscillator as the Clock Source
		Updated Section 6.2.24 Message Signaled Interrupt (MSI) Next Item Pointer 8Ch
		Added Section 6.2.25 Message Address Register – Offset 90h
		Added Section 6.2.26 Message Upper Address Register - Offset 94h
		Added Section 6.2.27 Message Data Register – Offset 98h
06/04/14	1.4	Updated Section 4.1 Pin List (SR_DO and SR_DI)
00/01/11	1.1	Updated Section 4.2.5 EEPROM Interface (SR DO and SR DI)
		Created for IC Revision B
		Updated Section 12 Ordering Information
		Added Section 6.2.25 Message Control Register – OFFSET 8Ch
01/09/15	1.5	Updated Section 11 Package Information
05/11/15	1.6	Updated Table 5.2 Baud Rate Generator Setting
		Updated Section 7.2.23 Clock Prescale Register –Offset 14h
12/13/16	1.7	Updated Logo
		Updated Table 9.1 Absolute Maximum Ratings
		Updated Table 9.2 DC Electrical Characteristics
08/29/17	1.8	Updated Section 4.1 Pin List of 160-Pin LFBGA
50,27,11	1.0	Updated Section 4.2.1 UART Interface
		Updated Table 9.2 DC Electrical Characteristics
		Updated Section 12 Ordering Information
		LINDARD SECOND 17 UNDERING INFORMATION

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## 1. FEATURES

- x1 PCI Express link host interface
- Dual high performance 950-class UARTs
- Compliant with PCI Express Base Specification 1.1
- Compliant with PCI Express CEM Specification 1.1
- Compliant with PCI Power Management 1.2
- Fully 16C550 software compatible UARTs
- 128-byte FIFO for each transmitter and receiver
- Baud rate up to 15 Mbps in asynchronous mode
- Flexible clock prescaler from 4 to 46
- Automated in-band flow control using programmable Xon/Xoff in both directions
- Automated out-of-band flow control using CTS#/RTS# and/or DSR#/DTR#
- Arbitrary trigger levels for receiver and transmitter FIFO interrupts and automatic in-band and out-of-band flow control
- Global Interrupt Status and readable FIFO levels to facilitate implementation of efficient device drivers
- Detection of bad data in the receiver FIFO
- Data framing size including 5, 6, 7, 8 and 9 bits
- Hardware reconfiguration through Microwire compatible EEPROM
- Operations via I/O or memory mapping
- Dual power operation (1.8V for PCIe I/O and core, 3.3V for UART I/O)
- Power dissipation: 0.7 W typical in normal mode
- Industrial Temperature Range -40° to 85°
- 128-pin LQFP, Pb-free and 100% Green

## 2. APPLICATIONS

- Remote Access Servers
- Network / Storage Management
- Factory Automation and Process Control
- Instrumentation
- Multi-port RS-232/ RS-422/ RS-485 Cards
- Point-of-Sale Systems (PoS)
- Industrial PC (IPC)
- Industrial Control
- Gaming Machines
- Building Automation
- Embedded Systems

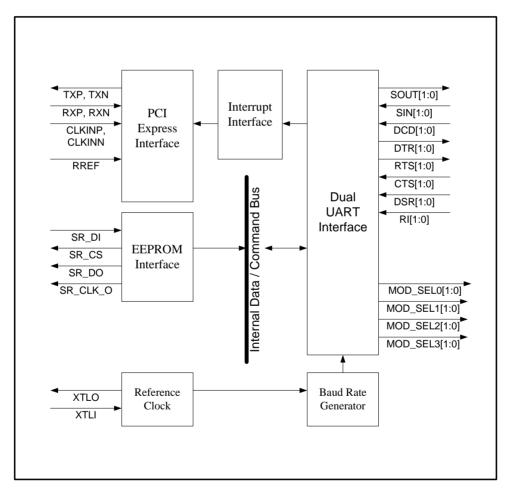


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## **3. GENERAL DESCRIPTION**

The PI7C9X7952 is a PCI Express Dual UART (Universal Asynchronous Receiver-Transmitters) I/O Bridge. It is specifically designed to meet the latest system requirements of high performance and lead (Pb) -free. The bridge can be used in a wide range of applications such as Remote Access Servers, Automation, Process Control, Instrumentation, POS, ATM and Multi-port RS232/ RS422/ RS485 Cards. The PI7C9X7952 provides one x1 PCIe (dual simplex 2.5 Gbps) uplink port, and it is fully compliant with PCI express 1.1 and PCI power management 1.2 specifications. The bridge supports two high performance UARTs, each of which supports Baud rate up to 15 Mbps in asynchronous mode. The UARTs support in-band and out-band auto flow control, arbitrary trigger level, I/O mapping and memory mapping. The PI7C9X7952 is fully software compatible with 16C550 type device drivers and can be configured to fit the requirements of RS232, RS422 and RS485 applications. The EEPROM interface is provided for system implementation. For programming flexibility, all of the default configuration registers can be overwritten by EEPROM data, such as sub-vendor and sub-system ID.



#### Figure 3-1 PI7C9X7952 Block Diagram

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## 4. PIN ASSIGNMENT

## 4.1. PIN LIST OF 128-PIN LQFP

PIN	NAME	PIN	NAME	PIN	NAME	PIN	NAME
1	VDDR	33	VDDC	65	NC	97	NC
2	VDDR	34	VDDCAUX	66	NC	98	VDDC
3	VSS	35	VSS	67	NC	99	VDDC
4	VSS	36	PERST_L	68	NC	100	VSS
5	SCAN_EN	37	TEST	69	VDDC	101	VSS
6	XTLI	38	GPIO[0]/DEQ[1]	70	VSS	102	NC
7	XTLO	39	GPIO[1]/DEQ[2]	71	SOUT[0]	103	NC
8	SR_CLK_O	40	VDDR	72	RTS[0]/EEPROM_BYPASS	104	NC
9	SR_DI	41	VDDR	73	DTR[0]/TEST2	105	NC
10	SR_DO	42	VSS	74	SIN[0]	106	JTAG_TDI
11	SR_CS	43	GPIO[2]/DEQ[3]	75	CTS[0]	107	JTAG_TMS
12	VDDC	44	GPIO[3]/TXTERMADJ[0]	76	DSR[0]	108	JTAG_TCK
13	VSS	45	GPIO[4]/TXTERMADJ[1]	77	RI[0]	109	JTAG_TDO
14	WAKEUP_L	46	GPIO[5]/RXTERMADJ[0]	78	DCD[0]	110	JTAG_TRST_L
15	VSS	47	GPIO[6]/RXTERMADJ[1]	79	SOUT[1]/DEBUG_PIN	111	NC
16	CLKINP	48	GPIO[7] /SR_ORG	80	RTS[1]/UART_TEST_MODE	112	NC
17	VDDA	49	DRIVER_SEL0[0]/HI_DRV	81	DTR[1]	113	NC
18	CLKINN	50	DRIVER_SEL0[1]/PHY_TM	82	SIN[1]	114	NC
19	VSS	51	DRIVER_SEL0[2]/LO_DRV	83	CTS[1]	115	VDDR
20	VDDC	52	DRIVER_SEL0[3]/DTX[0]	84	DSR[1]	116	VDDR
21	VTT	53	VDDC	85	RI[1]	117	VSS
22	TXN	54	VSS	86	DCD[1]	118	VSS
23	TXP	55	DRIVER_SEL1[0]/DTX[1]	87	NC	119	NC
24	VSS	56	DRIVER_SEL1[1]/DTX[2]	88	NC	120	NC
25	VDDCAUX	57	DRIVER_SEL1[2]/DTX[3]	89	NC	121	NC
26	RXP	58	DRIVER_SEL1[3]/DEQ[0]	90	NC	122	NC
27	VSS	59	NC	91	NC	123	NC
28	RXN	60	NC	92	NC	124	NC
29	RREF	61	NC	93	NC	125	NC
30	VDDA	62	NC	94	NC	126	NC
31	VSS	63	VDDR	95	VDDR	127	VDDC
32	VDDA	64	VSS	96	VSS	128	VDDC

#### Table 4-1 Pin-List of 128-Pin LQFP



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## 4.2. PIN DESCRIPTION

## 4.2.1. UART INTERFACE

PIN NO.	NAME	TYPE	DESCRIPTION
*79, 71	SOUT [1:0]	0	UART Serial Data Outputs: The output pins transmit serial data
			packets with start and end bits. SOUT[0] and SOUT[1] are output
			signals with weak internal pull-down resistors.
			<b>DEBUG_PIN:</b> During system initialization, SOUT[1] acts as the
			DEBUG_IN pin, and it is used to internal debugging used only. In
			normal operation, it should be low. By default, it is set to '0' without
			pin strapped.
82,74	SIN [1:0]	I	UART Serial Data Inputs: The input pins receive serial data
02, 71	Shtting	1	packets with start and end bits. The pins are idle high.
86,78	DCD [1:0]	Ι	Modem Data-Carrier-Detect Input and General Purpose Input
,			(Active Low)
81, *73	DTR [1:0]	0	Modem Data-Terminal-Ready Output (Active LOW): If
			automated DTR# flow control is enabled, the DTR# pin is asserted
			and deasserted if the receiver FIFO reaches or falls below the
			programmed thresholds, respectively. DTR[0] and DTR[1] are
			output signals with weak internal pull-down resistors.
			TEST1. During system initialization DTD[0]
			<b>TEST2:</b> During system initialization, DTR[0] acts as the TEST pin,
			and it is used for internal debugging used only. In normal operation, it should be low. By default, it is set to '0' without pin strapped.
*80. *72	RTS [1:0]	0	Modem Request-To-Send Output (Active LOW): If automated
180, 172	KIS[1.0]	0	RTS# flow control is enabled, the RTS# pin is deasserted and
			reasserted whenever the receiver FIFO reaches or falls below the
			programmed thresholds, respectively. RTS[0] and RTS[1] are output
			signals with weak internal pull-down resistors.
			<b>UART_TEST_MODE:</b> During system initialization, RTS[1] acts as
			the UART_TEST_MODE pin, and it is used for internal debugging
			used only. In normal operation, it should be low. By default, it is set
			to '0' without pin strapped.
			<b>EEPROM Bypass:</b> During system initialization, RTS[0] acts as the
			EEPROM Bypass pin, and it is used to bypass EEPROM
			pre-loading. The pin is active-high. When it is asserted at start-up,
			the EEPROM pre-loading is bypassed, and no configuration data is loaded from the EEPRPOM. Otherwise, configuration data is loaded
			from the EEPROM. Otherwise, configuration data is loaded
83,75	CTS [1:0]	I	Modem Clear-To-Send Input (Active LOW): If automated CTS#
05,75	015[1.0]	1	flow control is enabled, upon deassertion of the CTS# pin, the
			transmitter will complete the current character and enter the idle
			mode until the CTS# pin is reasserted. Note: flow control characters
			are transmitted regardless of the state of the CTS# pin.
84, 76	DSR [1:0]	Ι	Modem Data-Set-Ready Input (Active LOW): If automated
	_		DSR# flow control is enabled, upon deassertion of the DSR# pin,
			the transmitter will complete the current character and enter the idle
			mode until the DSR# pin is reasserted. Note: flow control characters
			are transmitted regardless of the state of the DSR# pin.
85,77	RI [1:0]	I	Modem Ring-Indicator Input (Active LOW)
7	XTLO	0	Crystal Oscillator Output
6	XTLI	Ι	Crystal Oscillator Input Or External Clock Pin: The maximum
			frequency supported by this device is 60MHz.





PIN NO.	NAME	TYPE	DESCRIPTION
*52, *51, *50, *49	DRIVER_SEL0 [3:0]	0	<b>DRIVER_SEL0:</b> Used to select RS-232/ RS-424/ 4-Wire RS-485/ 2-Wire RS-458 Serial Port Mode for UART 0. DRIVER_SEL0 [3:0] are output signals with weak internal pull-down resistors.
			<b>Driver Current Level Control (DTX[0]):</b> During system initialization, DRIVER_SEL0[3] acts as the DTX[0] pin, and it is used to control the driver current level. By default, it is set to '0' without pin strapped.
			<b>Low Driver Control (LO_DRV):</b> During system initialization, DRIVER_SEL0[2] acts as the LO_DRV pin, and it is used to decrease the nominal value of the PCI Express lane's driver current level. By default, it is set to '0' without pin strapped.
			<b>PHY_TM:</b> During system initialization, DRIVER_SEL0[1] acts as the PHY_TM pin, and it is used for internal debugging used only. In normal operation, it should be low. By default, it is set to '0' without pin strapped.
			<b>High Driver Control (HI_DRV):</b> During system initialization, DRIVER_SEL0[0] acts as the HI_DRV pin, and it is used to increase the nominal value of the PCI Express lane's driver current level. By default, it is set '0' without pin strapped.
*58, *57, *56, *55	DRIVER_SEL1 [3:0]	0	DRIVER_SEL1: Used to select RS-232/RS-424/ 4-Wire RS-485/ 2-Wire RS-458 Serial Port Mode for UART 1.
			<b>Driver Equalization Level Control (DEQ[0]):</b> During system initialization, DRIVER_SEL1[3] acts as the DEQ[0] pin, and it is used to control the driver current level. By default, it is set to '0' without pin strapped.
			<b>Driver Current Level Control (DTX[3:1]):</b> During system initialization, DRIVER_SEL1[2:0] acts as the DTX[3:1] pins, and they are used to control the driver current level. By default, they are set to '000' without pin strapped.

## 4.2.2. PCI EXPRESS INTERFACE

PIN NO.	NAME	TYPE	DESCRIPTION
23, 22	TXP, TXN	0	PCI Express Serial Output Signal: Differential PCI Express
			output signals.
26, 28	RXP, RXN	Ι	PCI Express Serial Input Signal: Differential PCI Express input
			signals.
16, 18	CLKINP,	Ι	Reference Input Clock: Connects to external 100MHz differential
	CLKINN		clock
			The input clock signals must be delivered to the clock buffer cell
			through an AC-coupled interface so that only the AC information of
			the clock is received, converted, and buffered. It is recommended
			that a 0.1uF be used in the AC-coupling.
29	RREF	Ι	Reference Resistor: To accurately set internal bias references, a
			precision resistor must be connected between Rref and Vss. The
			resistor should have a nominal value of 2.1 K $\Omega$ and accuracy of +/-
			1%

## 4.2.3. SYSTEM INTERFACE

PIN NO.	NAME	TYPE	DESCRIPTION
36	PEREST_L	Ι	System Reset Input





PIN NO.	NAME	TYPE	DESCRIPTION
*48, *47,	GPIO [7:0]	I/O	General-Purpose Bi-Direction Signals / SR_ORG: These eight
*46, *45,			general-purpose pins are programmed as either input-only or
*44, *43,			bi-directional pins by writing the GPIO output enable control
*39, *38			register. GPIO[2] is a bi-directional signal with a weak internal
			pull-up resistor, and other GPIO pins are bi-directional signals with
			weak internal pull-down resistors.
			EEPROM Organization Pin (SR_ORG): During system
			initialization, GPIO[7] acts as the SR_ORG pin, and it is used to
			select the organization structure of the EEPROM. The pin is
			active-high. When it is asserted at start-up, the EEPROM
			configuration data is organized in 16-bit structure. Otherwise, 8-bit
			structure is used.
			Designed Transition (in a dimension of (DVTEDMAD U1.01), During
			<b>Receiver Termination Adjustment (RXTERMADJ[1:0]):</b> During system initialization, GPIO[6:5] acts as the RXTERMADJ[1:0] pins,
			and they are used to adjust the receive termination resistor value. By
			default, they are set to '00' without pin strapped.
			donaan, moy ale set to so williout pli shappedi
			Transmit Termination Adjustment (TXTERMADJ[1:0]): During
			system initialization, GPIO[4:3] acts as the TXTERMADJ[1:0] pins,
			and they are used to adjust the transmit termination resistor value.
			By default, they are set to "00" without pin strapped.
			Driver Equalization Level Control (DEQ[3:1]): During system
			initialization, GPIO[2:0] acts as the DEQ[3:1] pins, and they are
			used to control the driver current level. By default, they are set to
			'100' without pin strapped.
14	WAKEUP_L	0	Wakeup Signal (Active LOW): When the Ring Indicator is
			received on UART channel 0 in L2 state, the WAKEUP_L is
			asserted. WAKEUP_L is an output signal with a weak internal
			pull-down resistor.

## 4.2.4. TEST SIGNALS

PIN NO.	NAME	TYPE	DESCRIPTION
106	JTG_TDI	I	Test Data Input: When SCAN_EN is high, the pin is used (in
			conjunction with TCK) to shift data and instructions into the TAP in
			a serial bit stream. JTG_TDI is an input signal with a weak internal
			pull-up resistor.
109	JTG_TDO	0	Test Data Output: When SCAN_EN is high, it is used (in
			conjunction with TCK) to shift data out of the Test Access Port
			(TAP) in a serial bit stream
107	JTG_TMS	I	Test Mode Select: Used to control the state of the Test Access Port
			controller. JTG_TMS is an input signal with a weak internal pull-up
			resistor.
108	JTG_TCK	I	Test Clock: Used to clock state information and data into and out of
			the chip during boundary scan.
110	JTG_TRST_L	Ι	Test Reset: Active LOW signal to reset the TAP controller into an
			initialized state. JTG_TRST_L is an input signal with a weak
			internal pull-up resistor.
5	SCAN_EN	Ι	Scan Test Enable Pin: SCAN_EN is an input signal with a weak
			internal pull-up resistor.
37	TEST	Ι	This input signal should be tied to ground during normal operation.





PIN NO.	NAME	TYPE	DESCRIPTION
59, 60, 61,	NC		These pins can be left floating.
62, 65, 66,			
67, 68, 87,			
88, 89, 90,			
91, 92, 93,			
94, 97, 102,			
103, 104,			
105, 111,			
112, 113,			
114, 119,			
120, 121,			
122, 123,			
124, 125,			
126			

#### 4.2.5. EEPROM INTERFACE

PIN NO.	NAME	TYPE	DESCRIPTION
11	SR_CS	0	EEPROM Chip Select: SR_CS is an output signal with a weak
			internal pull-up resistor.
10	SR_DO	0	EEPROM Data Output: Serial data output interface to the
			EEPROM. SR_DO is an output signal with a weak internal pull-up
			resistor.
9	SR_DI	Ι	<b>EEPROM Data Input:</b> Serial data input interface to the EEPROM.
			SR_DI is an input signal with a weak internal pull-up resistor.
8	SR_CLK_O	0	EEPROM Clock Output.

#### 4.2.6. POWER PINS

PIN NO.	NAME	I/O	DESCRIPTION
12, 20, 33,	VDDC	Р	1.8 V Power Pin: Used as digital core power pins.
53, 69, 98,			
99, 127, 128			
17, 30, 32,	VDDA	Р	<b>1.8 V Power Pin:</b> Used as analog core power pins.
1, 2, 40, 41,	VDDR	Р	3.3 V Power Pin: Used as digital I/O power pins.
63, 95, 115,			
116			
25, 34	VDDCAUX	Р	<b>1.8 V Power Pin:</b> Used as auxiliary power pins.
21	VTT	Р	1.8V Termination Voltage: Provides driver termination voltage at
			transmitter. Should be given the same consideration as VDDCAUX.
3, 4, 13, 15,	VSS	Р	Ground Pin: Used as ground pins.
19, 24, 27,			
31, 35, 42,			
54, 64, 70,			
96, 100, 101,			
117, 118			





## 5. FUNCTIONAL DESCRIPTION

The PI7C9X7952 is an integrated solution of two high-performance 16C550 UARTs with one x1 PCI Express host interface. The PCI Express host interface is compliant with the PCI Express Base Specification 1.1, PCI Express CEM Specification 1.1, and PCI Power Management 1.2. In addition, the chip is compliant with the Advanced Configuration Power Interface (ACPI) Specification and the PCI Standard Hot-Plug Controller (SHPC) and Subsystem Specification Revision 1.0. The x1 PCI Express host interface supports up to 2.5 Gbps bandwidth and complete PCI Express configuration register set. The PCI Express interface allows direct access to the configuration and status registers of the UART channels.

The UARTs in the PI7C9X7952 support the complete register set of the 16C550-type devices. The UARTs support Baud Rates up to 15 Mbps in asynchronous mode. Each UART channel has 128-byte deep transmit and receive FIFOs. The high-speed FIFOs reduce CPU utilization and improve data throughput. In addition, the UARTs support enhanced features including automated in-band flow control using programmable Xon/ Xoff in both directions, automated out-band flow control using CTS#/ RTS# and/or DRS#/ DTR#, and arbitrary transmit and receive trigger levels.

## 5.1. CONFIGURATION SPACE

The PI7C9X7952 has two sets of registers to allow various configuration and status monitoring functions. The PCI Express Configuration Space Registers enable the plug-and-play and auto-configuration when the device is connected to the PCI Express system bus. The UART configuration and internal registers enable the general UART operation functions, status control and monitoring.

## 5.1.1. PCI Express Configuration Space

The PI7C9X7952 is recognized as a PCI Express endpoint, which is mapped into the configuration space as a single logical device. Each endpoint in the system, including the PI7C9X7952, is part of a Hierarchy Domains originated by the Root Complex, which is a tree with a Root Port at its head in the configuration space. The device configuration registers are implemented for the user to access the functionalities provided by the PCI Express specification. The specification utilizes a flat memory-mapped configuration space to access device configuration registers.

All PCI Express endpoints facilitate a PCI-compatible configuration space to maintain compatibility with PCI software configuration mechanism. PCI Local Bus Specification, Revision 3.0 allocates 256 bytes per device function. PCI Express Base Specification 1.1 extends the configuration space to 4096 bytes to allow enhanced features. The first 256 bytes of the PCI Express Configuration Space are PCI 3.0 compatible region, and the rest of the 4096 bytes are PCI Express Configuration Space. The user can access the PCI 3.0 compatible region either by conventional PCI 3.0 configuration addresses or by the PCI Express memory-mapping addresses. These two types of accesses to the PCI 3.0 compatible region have identical results. The enhanced features in the PCI Express configuration space can only be accessed by PCI Express memory-mapping accesses.

## 5.1.2. UART Configuration Space

Through the UART registers, the user can control and monitor various functionalities of the UARTs on the PI7C9X7952 including FIFOs, interrupt status, line status, modem status and sample clock. Each of the UART's transmit and receive data FIFOs can be conveniently accessed by reading and writing the registers in the UART configuration space. These registers allow flexible programming capability and versatile





device operations of the PI7C9X7952. Each UART is accessed through an 8-byte I/O blocks. The addresses of the UART blocks are offset by the base address referred by the Base Address Register (BAR). The value of the base address is loaded from the I/O or Memory Base Address defined in the PCI Express configuration space.

The PI7C9X7952 also supports enhanced features such as Xon/Xoff, automatic flow control, Baud Rate prescaling and various status monitoring. These enhanced features are available through the memory address offset by the BAR in the PCI Express configuration space.

The basic features available in the registers in I/O mode are also available in the registers in memory-mapping mode. Accesses to these registers are equivalent in these two modes.

The UARTs on the PI7C9X7952 supports operations in 16C450, 16C550 and 16C950 modes. These modes of operation are selected by writing the SFR, FCR and EFR registers. The PI7C9X7952 is backward compatible with these modes of operation.

## 5.2. DEVICE OPERATION

The PI7C9X7952 is configured by the Root Complex in the bootstrap process during system start-up. The Root Complex performs bus scans and recognizes the device by reading vendor and device IDs. Upon successful device identification, the system then loads device-specific driver software and allocates I/O, memory and interrupt resources. The driver software allows the user to access the functions of the device by reading and writing the UART registers. The PCI Express interface incorporates convenient device operation and high system performance.

## 5.2.1. Configuration Access

The PI7C9X7952 accepts type 0 configuration read and write accesses defined in the PCI Express Base1.1 Specification. The first 256 bytes of the PCI Express configuration are compatible with PCI 3.0.

## 5.2.2. I/O Reads/Writes

The PCI Express interface of the PI7C9X7952 decodes incoming transaction packets. If the address is within the region assigned by the I/O Base Address Registers, the transaction is recognized as an I/O Read or Write.

#### 5.2.3. Memory Reads/Writes

Similar to the I/O Read/Write, if the address of the transaction packet is within the memory range, a Memory Read/Write occurs.





#### 5.2.4. Mode Selection

All of the internal UART channels in the I/O Bridge support the 16C450, 16C550, Enhanced 16C550, and Enhanced 950 UART Modes. The mode of the UART operation is selected by toggling the Special Function Register (SFR[5]) and Enhanced Function Register (EFR[4]). The FIFO depth of each mode and the mode selection is tabulated in the table below.

Table 5-	1 Mode	Selection
----------	--------	-----------

UART Mode	SFR[5]	EFR[4]	FIFO Size			
450/550	Х	0	1/16			
Enhanced 550	0	1	128			
Enhanced 950	1	1	128			

#### 5.2.5. 450/550 Mode

The 450 Mode is inherently supported when 550 Mode is selected. When in the 450 Mode, the FIFOs are in the "Byte Mode", which refers to the one-byte buffer in the Transmit Holding Register and the Receive Holding Register in each of the UART channels. When in the 550 Mode, the UARTs support an increased FIFO depth of 16.

When EFR[4] is set to "0", the SFR[5] is ignored, and the 450/550 Mode is selected.

#### 5.2.6. Enhanced 550 Mode

Setting the SFR[5] to "0" and EFR[4] to "1" enables the Enhanced 550 Mode. The Enhanced 550 Mode further increases FIFO depth to 128.

#### 5.2.7. Enhanced 950 Mode

128-deep FIFOs are supported in the Enhanced 950 Mode. When the Enhanced 950 Mode is enabled, the UART channels support additional features:

- Sleep mode
- Special character detection
- Automatic in-band flow control
- Automatic flow control using selectable arbitrary thresholds
- Readable status for automatic in-band and out-of-band flow control
- Flexible clock prescaler
- Programmable sample clock
- DSR/DTR automatic flow control

#### 5.2.8. Transmit and Receive FIFOs

Each channel of the UARTs consists of 128 bytes of transmit FIFOs and 128 bytes of receive FIFOs, namely the Transmit Holding Registers (THR) and the Receive Holding Registers (RHR). The FIFOs provide storage space for the data before they can be transmitted or processed. The THR and RHR operate simultaneously to transmit and read data.

The transmitter reads data from the THR into the Transmit Shift Register (TSR) and removes the data from top of the THR. It then converts the data into serial format with start and stop bits and parity bits if required. If the transmitter completes transmitting the data in the TSR and the THR is empty, the transmitter is in the idle state. The data that arrive most recently are written to the bottom of the THR. If the THR is full, and

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the user attempts to write data to the THR, a data overrun occurs and the data is lost.

The receiver writes data to the bottom of the RHR when it finishes receiving and decoding the data bits. If the RHR is full when the receiver attempts to write data to it, a data overrun occurs. Any read operation to an empty RHR is invalid.

The empty and full status of the THR and RHR can be determined by reading the empty and full flags in the Line Status Register (LSR). When the transmitter and receiver are ready to transfer data to and from the FIFOs, interrupts are raised to signal this condition. Additionally, the user can use the Receive FIFO Data Counter (RFDC) and Transmit FIFO Data Counter (TFDC) registers to determine the number of items in each FIFO.

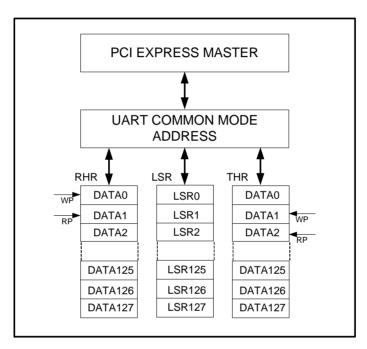


Figure 5-1 Transmit and Receive FIFOs



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#### 5.2.9. Automated Flow Control

The device uses automatic in-band flow control to prevent data-overrun to the local receive FIFO and remote receive FIFO. This feature works in conjunction with the special character detection. When an XOFF condition is detected, the UART transmitter will suspend any further data transmission after the current character transmission is completed. The transmitter will resume data-transmission as soon as an XON condition is detected. The automatic in-band feature is enabled by the Enhanced Function Register (EFR). EFR[1:0] enables the in-band receive flow control, and EFR[3:2] enables the in-band transmit flow control.

The out-of-band flow control utilizes RTS# and CTS# pins to suspend and resume the data transmission and to prevent data-overrun. An asserted CTS# pin signals the UART to suspend transmission due to a full remote receive FIFO. Upon detecting an asserted CTS# pin, the UART will complete the current character transmission and enters idle mode until the CTS# pin is deasserted.

The UART deasserts RTS# to signal the remote transmitter that the local receive FIFO reaches the programmed upper trigger level. When the local receive FIFO falls below the programmed lower trigger level, the RTS# is reasserted. The automatic out-of-band flow control is enabled by EFR[7:6].



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#### 5.2.10. Internal Loopback

The internal loopback capability of the UARTs is enabled by setting Modem Control Register bit-4 (MCR[4]) to 1. When the feature is enabled, the data from the output of the transmit shift register are looped back to the input of the receive shift register. This feature provides the users a way to perform system diagnostics by allowing the UART to receive the same data it is sending.

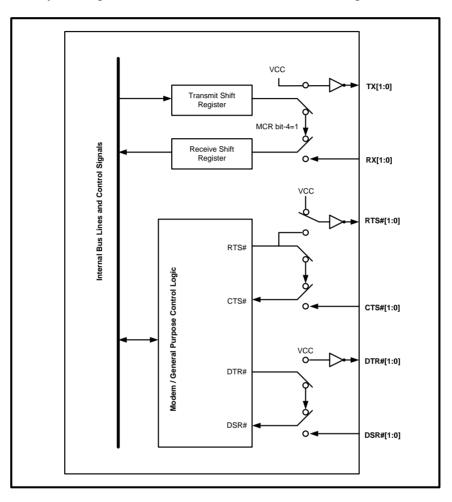


Figure 5-2 Internal Loopback in PI7C9X7952





#### 5.2.11. Crystal Oscillator

The PI7C9X7952 uses a crystal oscillator or an external clock source to provide system clock to the Baud Rate Generator. When a clock source is used, the clock signal should be connected to the XTLI pin, and a 2K pull-up resistor should be connected to the XTLO pin.

When a crystal oscillator is used, the XTLI is the input and XTLO is the output, and the crystal should be connected in parallel with two capacitors.

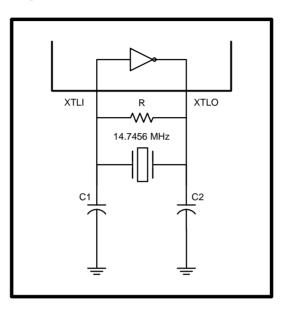


Figure 5-3 Crystal Oscillator as the Clock Source

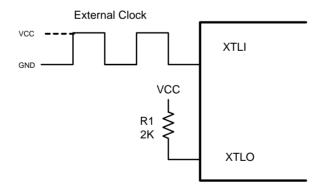


Figure 5-4 External Clock Source as the Clock Source





#### 5.2.12. Baud Rate Generation

The built-in Baud Rate Generator (BRG) allows a wide range of input frequency and flexible Baud Rate generation. To obtain the desired Baud Rate, the user can set the Sample Clock Register (SCR), Divisor Latch Low Register (DLL), Divisor Latch High Register (DLH) and Clock Prescale Registers (CPRM and CPRN). The Baud Rate is generated according to the following equation:

 $BaudRate = \frac{InputFrequency}{Divisor*Prescaler}$ 

The parameters in the equation above can be programmed by setting the "SCR", "DLL", "DLH", "CPRM" and "CPRN" registers according to the table below.

Setting	Description
Divisor	DLL + (256 * DLH)
Prescaler	$2^{M} * (\text{SampleClock} + N)$
SampleClock	16-SCR, (SCR = '0h' to 'Ch')
М	CPRM, (CPRM = $(01h)$ to $(02h)$ )
Ν	CPRN, (CPRN = ' $0h$ ' to ' $7h$ ')

Table	5-2	Baud	Rate	Generator	Setting
Lanc	5-2	Dauu	Nate	Generator	Setting

To ensure the proper operation of the Baud Rate Generator, users should avoid setting the value '0' to Sample Clock, Divisor and Prescaler.

The following table lists some of the commonly used Baud Rates and the register settings that generate a specific Baud Rate. The examples assume an Input Clock frequency of 14.7456 Mhz. The SCR register is set to '0h', and the CPRM and CPRN registers are set to '1h' and '0h' respectively. In these examples, the Baud Rates can be generated by different combination of the DLH and DLL register values.

Table 5-5 Bample Data Rate Betting					
Baud Rate	DLH	DLL			
1,200	3h	00h			
2,400	1h	80h			
4,800	Oh	C0h			
9,600	Oh	60h			
19,200	Oh	30h			
28,800	Oh	20h			
38,400	Oh	18h			
57,600	Oh	10h			
115,200	Oh	08h			
921,600	Oh	01h			

|--|

#### 5.2.13. Power Management

The PI7C9X7952 supports the D0, D1, D2 and D3 power states. The device is compliant with PCI Power Management Specification Revision 1.2.



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PI7C9X7952

## 6. PCI EXPRESS REGISTER DESCRIPTION

## 6.1. REGISTER TYPES

REGISTER TYPE	DEFINITION
HwInt	Hardware Initialization
RO	Read Only
WO	Write Only
RW	Read / Write
RWC	Read / Write 1 to Clear
RWCS	Sticky - Read Only / Write 1 to Clear
RWS	Sticky - Read / Write

## 6.2. CONFIGURATION REGISTERS

31 – 24	23 - 16	15 - 8	7 – 0	BYTE OFFSET			
Dev	ice ID	Vend	00h				
St	atus	Com	Command				
	Class Code		Revision ID	08h			
Reserved	Header Type	Primary Latency Timer	Cache Line Size	0Ch			
	Base Addres			10h			
	Base Addres			14h			
	Base Addres			18h			
	Rese	0		1Ch~28h			
Subsy	stem ID	Subsystem	Vendor ID	2Ch			
	Rese	rved		30h			
	Capabilit	y Pointer		34h			
	Rese			38h			
	erved	Interrupt Pin	Interrupt Line	3Ch			
Power Manager	nent Capabilities	Next $ID = 8C$	Capability ID = 01	80h			
PM Data	PPB Support		gement Data	84h			
Message Co	ntrol Register	Next ID =9C	Capability ID = 05	8Ch			
	Message Address Register						
	Message Upper Address Register						
	Message Da	ata Register	98h				
VPD I	Register	Next ID = $A4$	Capability ID = 03	9Ch			
	VPD Data	a Register		A0h			
Vendor Defin	e Register(28h)	Next $ID = E0$	Capability ID = 09	A4h			
	XPIP	CSR0		A8h			
	XPIP	CSR1		ACh			
ACK Lat	ency Timer	Replay Time	e-out counter	B0h			
	GPIO Data			D8h			
	OM Data	EEPRON		DCh			
PCI Express Ca	pability Register	Next ID = 00h	Capability ID = 10	E0h			
	Device C			E4h			
Devic	e Status	Device Control		E8h			
	Link Ca			ECh			
Link	Status	Link Control		F0h			
	Rese	rved		F4h			
	Rese			F8h			
		ress Extend Capability					
Next Capability Offset = 000h	Capability Version	PCI Express Ext ID =		100h			
	Uncorrectable Err			104h			
	Uncorrectable Err			108h			
	Uncorrectable Erro			10Ch			

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31 - 24	23 - 16	15 - 8	7 - 0	BYTE OFFSET		
	110h					
	114h					
А	118h					
Header Log Register 11Ch~128						

#### 6.2.1. VENDOR ID REGISTER – OFFSET 00h

BIT	FUNCTION	TYPE	DESCRIPTION
15:0	Vendor ID	RO	Identifies Pericom as the vendor of this device. The register is
			hardwired as 12D8h.

#### 6.2.2. DEVICE ID REGISTER – OFFSET 00h

BIT	FUNCTION	TYPE	DESCRIPTION
31:16	Device ID	RO	Identifies this device as the PI7C9X7952. Reset to 7952h.

#### 6.2.3. COMMAND REGISTER – OFFSET 04h

BIT	FUNCTION	TYPE	DESCRIPTION
0	I/O Space Enable	RW	Controls a device's response to I/O Space accesses. A value of 0 disables the device response. A value of 1 allows the device to respond to I/O Space accesses. Reset to 0b.
1	Memory Space Enable	RW	Controls a device's response to Memory Space accesses. A value of 0 disables the device response. A value of 1 allows the device to response to memory Space accesses. Reset to 0b.
2	Bus Master Enable	RO	It is not implemented. Hardwired to 0b.
3	Special Cycle Enable	RO	Does not apply to PCI Express. Must be hardwired to 0b.
4	Memory Write And Invalidate Enable	RO	Does not apply to PCI Express. Must be hardwired to 0b.
5	VGA Palette Snoop Enable	RO	Does not apply to PCI Express. Must be hardwired to 0b.
6	Parity Error Response Enable	RW	Controls the device's response to parity errors. When the bit is set, the device must take its normal action when a parity error is detected. When the bit is 0, the device sets its Detected Parity Error Status bit when an error is detected. Reset to 0b.
7	Wait Cycle Control	RO	Does not apply to PCI Express. Must be hardwired to 0b.
8	SERR# enable	RW	This bit, when set, enables reporting of Non-fatal and Fatal errors detected by the device to the Root Complex. Reset to 0b.
9	Fast Back-to-Back Enable	RO	Does not apply to PCI Express. Must be hardwired to 0b.
10	Interrupt Disable	RW	Controls the ability of the I/O bridge to generate INTx interrupt Messages. Reset to 0b.
15:11	Reserved	RO	Reset to 00000b.

#### 6.2.4. STATUS REGISTER - OFFSET 04h

BIT	FUNCTION	TYPE	DESCRIPTION
18:16	Reserved	RO	Reset to 000b.
19	Interrupt Status	RO	Indicates that an INTx interrupt Message is pending internally to the

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BIT	FUNCTION	TYPE	DESCRIPTION
			device.
			Reset to 0b.
			Set to 1 to enable support for the capability list (offset 34h is the
20	Capabilities List	RO	pointer to the data structure)
	1		Reset to 1b.
21	66MHz Capable	RO	Does not apply to PCI Express. Must be hardwired to 0b.
21	Reserved	RO	Reset to 0b.
	Fast Back-to-Back	KU	Does not apply to PCI Express. Must be hardwired to 0b.
23	Capable	RO	Does not apply to I CI Express. Must be hardwired to 00.
24	Master Data Parity	RWC	It is not implemented. Hardwired to 0b.
	Error	KWC	
26:25	DEVSEL# Timing	RO	Does not apply to PCI Express. Must be hardwired to 0b.
			Set to 1 (by a completer) whenever completing a request in the I/O
27	Signaled Target	RWC	bridge side using Completer Abort Completion Status.
	Abort		D
	D 100		Reset to 0b.
28	Received Target Abort	RWC	It is not implemented. Hardwired to 0b.
29	Received Master	RWC	It is not implemented. Hardwired to 0b.
-	Abort		
			Set to 1 when the I/O bridge sends an ERR_FATAL or
	Signaled System	DUVG	ERR_NONFATAL Message, and the SERR Enable bit in the
30	Error	RWC	Command register is 1.
			Deast to Oh
			Reset to 0b.
31	Detected Parity	RWC	Set to 1 whenever the I/O bridge receives a Poisoned TLP.
51	Error	KWC	Reset to 0b.
		I	Reset to 00.

## 6.2.5. REVISION ID REGISTER – OFFSET 08h

BIT	FUNCTION	TYPE	DESCRIPTION
7:0	Revision	RO	Indicates revision number of the I/O bridge. The default value may be changed by auto-loading from EEPROM. Reset to 00h.

#### 6.2.6. CLASS CODE REGISTER – OFFSET 08h

BIT	FUNCTION	TYPE	DESCRIPTION
15:8	Programming	RO	Read as 02h to indicate no programming interfaces have been
	Interface		defined for PCI-to-PCI bridges
23:16	Sub-Class Code	RO	Read as 00h to indicate device is PCI-to-PCI bridge
31:24	Base Class Code	RO	Read as 07h to indicate device is a bridge device

## 6.2.7. CACHE LINE REGISTER – OFFSET 0Ch

BIT	FUNCTION	TYPE	DESCRIPTION
7:0	Cache Line Size	RW	The cache line size register is set by the system firmware and the operating system to system cache line size. This field is implemented by PCI Express devices as a RW field for legacy compatibility purposes but has no impact on any PCI Express device functionality. Reset to 00h.





#### 6.2.8. MASTER LATENCY TIMER REGISTER – OFFSET 0Ch

BIT	FUNCTION	TYPE	DESCRIPTION
15:8	Latency timer	RO	Does not apply to PCI Express. Must be hardwired to 00h.

#### 6.2.9. HEADER TYPE REGISTER – OFFSET OCh

BIT	FUNCTION	TYPE	DESCRIPTION
23:16	Header Type	RO	Read as 00h to indicate that the register layout conforms to the standard PCI-to-PCI bridge layout.

#### 6.2.10. BASE ADDRESS REGISTER 0 – OFFSET 10h

BIT	FUNCTION	TYPE	DESCRIPTION
31:0	Base Address 0	RW	Use this I/O base address to map the UART 16550 compatible registers. The base address can be allocated to 64 Bytes. Reset to 00000001h.

## 6.2.11. BASE ADDRESS REGISTER 1 – OFFSET 14h

BIT	FUNCTION	TYPE	DESCRIPTION
31:0	Base Address 1	RW	Use this memory base address to map the UART 16550 compatible and enhanced registers. The base address can be allocated to 4096 Bytes. Reset to 00000000h

## 6.2.12. SUBSYSTEM VENDOR REGISTER – OFFSET 2Ch

BIT	FUNCTION	TYPE	DESCRIPTION
15:0	Sub Vendor ID	RO	Indicates the sub-system vendor id. The default value may be changed by auto-loading from EEPROM.
			Reset to 0000h.

#### 6.2.13. SUBSYSTEM ID REGISTER – OFFSET 2Ch

BIT	FUNCTION	TYPE	DESCRIPTION
31:16 Sub System II	Sub System ID	) RO	Indicates the sub-system device id. The default value may be changed by auto-loading from EEPROM.
			Reset to 0000h.

#### 6.2.14. CAPABILITIES POINTER REGISTER – OFFSET 34h

BIT	FUNCTION	TYPE	DESCRIPTION
7:0	Capabilities Pointer	RO	This optional register points to a linked list of new capabilities implemented by the device. This default value may be changed by auto-loading from EEPROM. The default value is 80h.

## 6.2.15. INTERRUPT LINE REGISTER – OFFSET 3Ch

BIT	FUNCTION	TYPE	DESCRIPTION
7:0	Interrupt Line	RW	Used to communicate interrupt line routing information. POST





BIT	FUNCTION	TYPE	DESCRIPTION
			software will write the routing information into this register as it
			initializes and configures the system.
			Reset to 00h.

#### 6.2.16. INTERRUPT PIN REGISTER – OFFSET 3Ch

BIT	FUNCTION	TYPE	DESCRIPTION
15:8	Interrupt Pin	RO	Identifies the legacy interrupt Message(s) the device uses.
15.0	interrupt Fin	ĸo	Reset to 01h.

#### 6.2.17. POWER MANAGEMENT CAPABILITY ID REGISTER – OFFSET 80h

BIT	FUNCTION	TYPE	DESCRIPTION
7:0	Enhanced Capabilities ID	RO	Read as 01h to indicate that these are power management enhanced capability registers.

#### 6.2.18. NEXT ITEM POINTER REGISTER – OFFSET 80h

BIT	FUNCTION	TYPE	DESCRIPTION
15:8 Next Item Pointer	RO	The pointer points to the Power Management capability register (8Ch).	
			Reset to 8Ch.

## 6.2.19. POWER MANAGEMENT CAPABILITIES REGISTER - OFFSET 80h

BIT	FUNCTION	TYPE	DESCRIPTION
18:16	Power Management Revision	RO	Read as 011b to indicate the I/O bridge is compliant to Revision 1.1 of <i>PCI Power Management Interface Specifications</i> .
19	PME# Clock	RO	Does not apply to PCI Express. Must be hardwired to 0b.
20	Auxiliary Power	RO	Read as 1b to indicate the I/O bridge forwards the PME# message in D3cold and an auxiliary power source is required.
21	Device Specific Initialization	RO	Read as 0b to indicate the I/O bridge does not have device specific initialization requirements. The default value may be changed by auto-loading from EEPROM.
24:22	AUX Current	RO	Reset as 111b to indicate the I/O bridge need 375 mA in D3 state. The default value may be changed by auto-loading from EEPROM.
25	D1 Power State Support	RO	Read as 1b to indicate the I/O bridge supports the D1 power management state. The default value may be changed by auto-loading from EEPROM.
26	D2 Power State Support	RO	Read as 1b to indicate the I/O bridge supports the D2 power management state. The default value may be changed by auto-loading from EEPROM.
31:27	PME# Support	RO	Read as 01000b to indicate the I/O bridge supports the forwarding of PME# message in all power states. The default value may be changed by auto-loading from EEPROM.

## 6.2.20. POWER MANAGEMENT DATA REGISTER - OFFSET 84h

BIT	FUNCTION	TYPE	DESCRIPTION
1:0	Power State	RW	Indicates the current power state of the I/O bridge. Writing a value of D0 causes a hot reset without asserting PEREST_L when the previous state was D3. 00b: D0 state 01b: D1 state 10b: D2 state





BIT	FUNCTION	TYPE	DESCRIPTION
			11b: D3 hot state
			Reset to 00b.
2	Reserved	RO	Read as 0b.
			When set, this bit indicates that I/O bridge transitioning from D3hot
			to D0 does not perform an internal reset.
			When clear, an internal reset is performed when power state transits
3	No_Soft_Reset	RO	from D3hot to D0. The default value may be changed by
			auto-loading from EEPROM.
			Reset to 0b.
7:4	Reserved	RO	Read as 0h.
			When asserted, the I/O bridge will generate the PME# message.
8	PME# Enable	RW	
			Reset to 0b.
			Select data registers.
12:9	Data Select	RW	
			Reset to 0h.
14:13	Data Scale	RO	Read as 00b.
			Indicates that the PME# message is pending internally to the I/O
15	PME status	RO	bridge.
15	FIVE Status	ĸŪ	
			Reset to 0b.

## 6.2.21. PPB SUPPORT EXTENSIONS – OFFSET 84h

BIT	FUNCTION	TYPE	DESCRIPTION
21:16	Reserved	RO	Reset to 000000b.
22	B2_B3 Support for	RO	Does not apply to PCI Express. Must be hardwired to 0b.
22	D3 <sub>HOT</sub>	ĸO	
23	Bus Power / Clock	RO	Does not apply to PCI Express. Must be hardwired to 0b.
23	Control Enable	ĸo	

## 6.2.22. PM DATA REGISTER - OFFSET 84h

BIT	FUNCTION	TYPE	DESCRIPTION
			PM Data Register.
31:24	PM Data Register	RO	
			Reset to 00h

## 6.2.23. MESSAGE SIGNALED INTERRUPTS (MSI) Capability ID Register 8Ch

BIT	FUNCTION	TYPE	DESCRIPTION
7:0	Enhanced RO	Read as 05h to indicate that this is Message Signaled Interrupt	
7.0	Capability ID	KU	capability register.

## 6.2.24. MESSAGE SIGNALED INTERRUPTS (MSI) NEXT ITEM POINTER 8Ch

BIT	FUNCTION	TYPE	DESCRIPTION
15:8	Next Item Pointer	RO	The pointer points to the Vendor Specific capability register (9Ch).
			Reset to 9Ch.

## 6.2.25. MESSAGE CONTROL REGISTER – OFFSET 8Ch

BIT	FUNCTION	TYPE	DESCRIPTION
16	MSI Enable	RW	0b: The function is prohibited from using MSI to request service 1b: The function is permitted to use MSI to request service and is prohibited from using its INTx # pin





BIT	FUNCTION	TYPE	DESCRIPTION
			Reset to 1'b0.
19:17	Multiple Message Capable	RO	Read as 3'b000.
22:20	Multiple Message Enable	RW	Reset to 3'b000.
23	64-bit address capable	RO	<ul> <li>Ob: The function is not capable of generating a 64-bit message address</li> <li>1b: The function is capable of generating a 64-bit message address</li> <li>Reset to 1'b1.</li> </ul>
31:24	Reserved	RO	Reset to 8'h00.

## 6.2.26. MESSAGE ADDRESS REGISTER – OFFSET 90h

BIT	FUNCTION	TYPE	DESCRIPTION
1:0	Reserved	RO	Reset to 00b.
31:2	Message Address	RW	If the message enable bit is set, the contents of this register specify the DWORD aligned address for MSI memory write transaction. Reset to 0.

## 6.2.27. MESSAGE UPPER ADDRESS REGISTER – OFFSET 94h

BIT	FUNCTION	TYPE	DESCRIPTION
31:0	Message Upper Address	RW	This register is only effective if the device supports a 64-bit message address is set.
	/ Hulless		Reset to 00000000h.

#### 6.2.28. MESSAGE DATA REGISTER - OFFSET 98h

BIT	FUNCTION	TYPE	DESCRIPTION
15:0	Message Data	RW	Reset to 0000h.

#### 6.2.29. VPD CAPABILITY ID REGISTER – OFFSET 9Ch

BIT	FUNCTION	TYPE	DESCRIPTION
7:0	Enhanced	RO	Read as 03h to indicate that these are VPD enhanced capability
7.0	Capabilities ID	KO	registers.

#### 6.2.30. NEXT ITEM POINTER REGISTER – OFFSET 9Ch

BIT	FUNCTION	TYPE	DESCRIPTION
15:8	Next Item Pointer	RO	The pointer points to the VPD capability register (A4h).
			Reset to A4h

#### 6.2.31. VPD REGISTER – OFFSET 9Ch

BIT	FUNCTION	TYPE	DESCRIPTION
16	VPD Start	RW	Starts VPD read or write cycle. Assert by software and is de-asserted by hardware. Reset to 0b.
17	VPD Operation	RW	<ul><li>0b: Performs VPD read command to VPD table at the location as specified in VPD address</li><li>1b: Performs VPD write command to VPD table at the location</li></ul>





BIT	FUNCTION	TYPE	DESCRIPTION
			as specified in VPD address
			Reset to 0b.
22:18	VPD Address	RW	Contains DWORD address that is used to generate read or write cycle to the VPD table stored in EEPROM.
			Reset to 00000b.
31:23	Reserved	RO	Read as 000h.

#### 6.2.32. VPD DATA REGISTER – OFFSET A0h

BIT	FUNCTION	TYPE	DESCRIPTION
31:0	VPD Data	RW	<ul><li>When read, it returns the last data read from VPD table at the location as specified in VPD Address.</li><li>When writes, it places the current data into VPD table at the location as specified in VPD Address.</li><li>Reset to 00000000h.</li></ul>

## 6.2.33. VENDOR SPECIFIC CAPABILITY ID REGISTER – OFFSET A4h

BIT	FUNCTION	TYPE	DESCRIPTION
7:0	Enhanced PO	RO	Read as 09h to indicate that these are Vendor Specific capability
7.0	Capabilities ID	кU	registers.

#### 6.2.34. NEXT ITEM POINTER REGISTER – OFFSET A4h

BIT	FUNCTION	TYPE	DESCRIPTION
15:8	Next Item Pointer	RO	The pointer points to the PCI Express capability register (E0h).
			Reset to E0h.

## 6.2.35. LENGTH REGISTER – OFFSET A4h

BIT	FUNCTION	TYPE	DESCRIPTION
31:16 Length Information	RO	The length field provides the information for number of bytes in the capability structure (including the ID and Next pointer bytes).	
			Reset to 28h.

#### 6.2.36. XPIP CSR0 – OFFSET A8h (Test Purpose Only)

BIT	FUNCTION	TYPE	DESCRIPTION
31:0	Reserved	RW	Reset to 04001060h.

## 6.2.37. XPIP CSR1 – OFFSET ACh (Test Purpose Only)

BIT	FUNCTION	TYPE	DESCRIPTION
31:0	Reserved	RW	Reset to 004000271h.





#### 6.2.38. REPLAY TIME-OUT COUNTER – OFFSET BOh

BIT	FUNCTION	TYPE	DESCRIPTION
11:0	User Replay Timer	RW	A 12-bit register contains a user-defined value. The default value may be changed by auto-loading from EEPROM. Reset to 000h.
12	Enable User Replay Timer	RW	When asserted, the user-defined replay time-out value would be employed. The default value may be changed by auto-loading from EEPROM. Reset to 0b.
15:13	Reserved	RO	Reset to 000b.

## 6.2.39. ACKNOWLEDGE LATENCY TIMER – OFFSET B0h

BIT	FUNCTION	TYPE	DESCRIPTION
29:16	User ACK Latency Timer	RW	A 14-bit register contains a user-defined value. The default value may be changed by auto-loading from EEPROM.
			Reset to 0000h
30	Enable User ACK Latency	RW	When asserted, the user-defined ACK latency value would be employed. The default value may be changed by auto-loading from EEPROM.
			Reset to 0b.
31	Reserved	RO	Reset to 0b.

## 6.2.40. UART DRIVE SETTING – OFFSET B4h

BIT	FUNCTION	TYPE	DESCRIPTION
3:0	UART 0 Transmitter Driver Enable	RW	UART 0 DRIVER. The default value may be changed by auto-loading from EEPROM. 0000b: RS232 0001b: RS422 1011b: RS485-4W 1111b: RS485-2W Reset to 0000b.
7:4	UART 1 Transmitter Driver Enable	RW	UART 1 DRIVER. The default value may be changed by auto-loading from EEPROM. 0000b: RS232 0001b: RS422 1011b: RS485-4W 1111b: RS485-2W Reset to 0000b.
31:8	Reserved	RW	Reserved

#### 6.2.41. POWER MANAGEMENT CONTROL PARAMETER - OFFSET B8h

BIT	FUNCTION	TYPE	DESCRIPTION
5:0	Power Management Control Parameter	RW	The default value may be changed by auto-loading from EEPROM. Reset to 000001b.
31:6	Reserved	RO	Reset to 0000000h.





#### 6.2.42. DEBUG REGISTER 1 – OFFSET BCh (Test Purpose Only)

BIT	FUNCTION	TYPE	DESCRIPTION
			Used for test purpose only.
31:0	Debug Register 1	RO	
			Reset to 00000000h.

#### 6.2.43. DEBUG REGISTER 2 – OFFSET C0h (Test Purpose Only)

BIT	FUNCTION	TYPE	DESCRIPTION
			Used for test purpose only.
31:0	Debug Register 2	RO	
			Reset to 00000000h.

#### 6.2.44. DEBUG REGISTER 3 – OFFSET C4h (Test Purpose Only)

BIT	FUNCTION	TYPE	DESCRIPTION
31:0	Debug Register 3	RO	Used for test purpose only.
			Reset to 0000000h.

#### 6.2.45. DEBUG REGISTER 4 – OFFSET C8h (Test Purpose Only)

BIT	FUNCTION	TYPE	DESCRIPTION
0	Low Driver Current	HwInt	It indicates the status of the strapping pin LODRV. The default value may be changed by auto-loading from EEPROM.
1	High Driver Current	HwInt	It indicates the status of the strapping pin HIDRV. The default value may be changed by auto-loading from EEPROM.
5:2	Driver Transmit Current	HwInt	It indicates the status of the strapping pins DTX[3:0]. The default value may be changed by auto-loading from EEPROM.
9:6	De-emphasis Transmit Equalization	HwInt	It indicates the status of the strapping pins DEQ[3:0]. The default value may be changed by auto-loading from EEPROM.
11:10	Receive Termination Adjustment	HwInt	It indicates the status of the strapping pins RXTRMADJ[1:0]. The default value may be changed by auto-loading from EEPROM.
13:12	Transmit Termination Adjustment	HwInt	It indicates the status of the strapping pins TXTRMADJ[1:0]. The default value may be changed by auto-loading from EEPROM.
31:14	Reserved	RO	Reset to 00000h.

#### 6.2.46. GPIO CONTROL REGISTER – OFFSET D8h

BIT	FUNCTION	TYPE	DESCRIPTION
7:0	GPIO Input	RO	The current state of the GPIO[x] pin can be read from bit[x] in this register, where $x=7$ to 0. The bits are effective only when the corresponding GPIO I/O Enable bits are set to "0".
15:8	GPIO I/O Enable	RW	These 8 bits determine whether the GPIO pins are input or output pins. Bit $[x+8]$ corresponds to GPIO $[x]$ , where $x=7$ to 0. If the bit is set to "0", the corresponding GPIO pin is an input pin. If the bit is set to "1", the corresponding GPIO pin is an output pin.
23:16	GPIO Output	RW	The current state of the GPIO[x] pin can be written by $bit[x+16]$ in this register, where x=7 to 0. The bits are effective only when the corresponding GPIO I/O Enable bits are set to "1".
31:24	Reserved	RO	Reserved





#### 6.2.47. EEPROM CONTROL REGISTER – OFFSET DCh

BIT	FUNCTION	TYPE	DESCRIPTION
0	EEPROM Start	RW	Starts the EEPROM read or write cycle. Reset to 0b.
1	Reserved	RO	Reset to 0b.
2	EEPROM Preload Control	RW	Enable preload start. Reset to 0b.
4:3	EEPROM Operation Command	RW	EEPROM Operation Command. 00b: Reserved 01b: Write operation command 10b: Read operation command 11b: Reserved Reset to 00b.
15:5	EEPROM Address	RW	EEPROM RW address. Reset to 000h.
31:16	EEPROM Write DATA Buffer	RW	EEPROM write data buffer register. Reset to 0000h.

#### 6.2.48. PCI EXPRESS CAPABILITY ID REGISTER – OFFSET E0h

BIT	FUNCTION	TYPE	DESCRIPTION
7:0	Enhanced Capabilities ID	RO	Read as 10h to indicate that these are PCI express enhanced capability registers.

#### 6.2.49. NEXT ITEM POINTER REGISTER – OFFSET EOh

BIT	FUNCTION	TYPE	DESCRIPTION
15:8	Next Item Pointer	RO	Read as 00h. No other ECP registers.
15.0	Next Rem Fonder	ĸo	Reset to 00h.

#### 6.2.50. PCI EXPRESS CAPABILITIES REGISTER - OFFSET E0h

BIT	FUNCTION	TYPE	DESCRIPTION
19:16	Capability Version	RO	Read as 0001b to indicate the I/O bridge is compliant to Revision 1.0a of <i>PCI Express Base Specifications</i> .
23:20	Device/Port Type	RO	Indicates the type of Legacy PCI Express Endpoint device. Reset to 1h.
24	Slot Implemented	RO	It is not implemented. Hardwired to 0b.
29:25	Interrupt Message Number	RO	It is not implemented. Hardwired to 00000b.
31:30	Reserved	RO	Reset to 00b.

## 6.2.51. DEVICE CAPABILITIES REGISTER – OFFSET E4h

BIT	FUNCTION	TYPE	DESCRIPTION
2:0	Max_Payload_Size Supported	RO	Indicates the maximum payload size that the I/O bridge can support for TLPs. The I/O bridge supports 128 bytes max payload size. Reset to0000b.
4:3	Phantom Functions Supported	RO	It is not implemented. Hardwired to 00b.





5       Supported       RO       Acceptable total latency that an Endpoint can withstand due to the transition from L0s state to the L0 state.         8:6       Endpoint L0s Acceptable Latency       RO       Acceptable total latency that an Endpoint can withstand due to the transition from L0s state to the L0 state.         11:9       Endpoint L1 Acceptable Latency       RO       Acceptable total latency that an Endpoint can withstand due to the transition from L1 state to the L0 state.         12       Attention Button Present       RO       It is not implemented. Hardwired to 0b.         13       Present       RO       It is not implemented. Hardwired to 0b.         14       Power Indicator Present       RO       It is not implemented. Hardwired to 0b.         15       Role_Base Error Reporting       RO       It is not implemented. Hardwired to 0b.         17:16       Reserved       RO       Ro       It is not implemented. Hardwired to 0b.         17:16       Reserved       RO       Reset to 1b.       Ro         25:18       Captured Slot Power Limit Value       RO       Reset to 00b.       Reset to 00b.         27:26       Captured Slot Power Limit Scale       RO       Specifies the scale used for the Slot Power_Limit message or hardwired to "00b".         27:26       Captured Slot Power Limit Scale       RO       Rese	BIT	FUNCTION	TYPE	DESCRIPTION
8:6       Endpoint L0s Acceptable Latency       RO       transition from L0s state to the L0 state. Reset to 000b.         11:9       Endpoint L1 Acceptable Latency       RO       Acceptable total latency that an Endpoint can withstand due to the transition from L1 state to the L0 state. Reset to 000b.         12       Attention Button Present       RO       It is not implemented. Hardwired to 0b.         13       Attention Indicator Present       RO       It is not implemented. Hardwired to 0b.         14       Power Indicator Present       RO       It is not implemented. Hardwired to 0b.         15       Role_Base Error Reporting       RO       When set, indicated that the device implements the functionality originally defined in the Error Reporting ECN. The default value may be changed by auto-loading from EEPROM.         17:16       Reserved       RO       Reset to 00b.         25:18       Captured Slot Power Limit Value       RO       Reset to 00b.         27:26       Captured Slot Power Limit Scale       RO       Specifies the scale used for the Slot Power_Limit message or hardwired to "00b".         27:26       Captured Slot Power Limit Scale       RO       Specifies the scale used for the Slot Power_Limit message or hardwired to "00b".         27:26       Captured Slot Power Limit Scale       RO       Specifies the scale used for the Slot Power_Limit message or hardwired to "00b".	5		RO	It is not implemented. Hardwired to 0b.
11:9       Endpoint L1 Acceptable Latency       RO       Acceptable total latency that an Endpoint can withstand due to the transition from L1 state to the L0 state. Reset to 000b.         12       Attention Button Present       RO       It is not implemented. Hardwired to 0b.         13       Present       RO       It is not implemented. Hardwired to 0b.         14       Power Indicator Present       RO       It is not implemented. Hardwired to 0b.         15       Role_Base Error Reporting       RO       It is not implemented that the device implements the functionality originally defined in the Error Reporting ECN. The default value may be changed by auto-loading from EEPROM.         17:16       Reserved       RO       Reset to 00b.         12:17:16       Reserved       RO       Reset to 00b.         17:16       Reserved       RO       Reset to 00b.         17:16       Reserved       RO       Reset to 00b.         17:16       Reserved       RO       Reset to 00b.         25:18       Captured Slot Power Limit Value       RO       This value is set by the Set_Slot_Power_Limit message or hardwired to "00h".         27:26       Captured Slot Power Limit Scale       RO       Specifies the scale used for the Slot Power_Limit Talue.         27:26       Captured Slot Power Limit Scale       RO       This value is set by the Set_Slot_Po	8:6		RO	transition from L0s state to the L0 state.
12       Attention Button Present       RO       It is not implemented. Hardwired to 0b.         13       Attention Indicator Present       RO       It is not implemented. Hardwired to 0b.         14       Power Indicator Present       RO       It is not implemented. Hardwired to 0b.         15       Role_Base Error Reporting       RO       It is not implemented. Hardwired to 0b.         15       Role_Base Error Reporting       RO       When set, indicated that the device implements the functionality originally defined in the Error Reporting ECN. The default value may be changed by auto-loading from EEPROM.         17:16       Reserved       RO       Reset to 1b.         17:16       Reserved       RO       Reset to 00b.         12       Captured Slot Power Limit Value       RO       Reset to 00b.         25:18       Captured Slot Power Limit Value       RO       Reset to 00b.         27:26       Captured Slot Power Limit Scale       RO       Specifies the scale used for the Slot Power_Limit message or hardwired to "00b".         27:26       Captured Slot Power       RO       Rou       This value is set by the Set_Slot_Power_Limit message or hardwired to "00b".         27:26       Captured Slot Power       RO       Reset to 00b.       Reset to 00b.	11:9		RO	Acceptable total latency that an Endpoint can withstand due to the transition from L1 state to the L0 state.
13       Present       RO       In a brond prime of the prime of	12		RO	
14       Present       RO         15       Role_Base Error Reporting       RO       When set, indicated that the device implements the functionality originally defined in the Error Reporting ECN. The default value may be changed by auto-loading from EEPROM.         15       Role_Base Error Reporting       RO       Reset to 1b.         17:16       Reserved       RO       Reset to 00b.         17:17       Reserved       RO       Reset to 00b.         25:18       Captured Slot Power Limit Value       RO       Reset to 00b.         25:18       Captured Slot Power Limit Value       RO       This value is set by the Set_Slot_Power_Limit message or hardwired to "00h".         27:26       Captured Slot Power Limit Scale       RO       RO       Specifies the scale used for the Slot Power_Limit message or hardwired to "00b".         27:26       Captured Slot Power Limit Scale       RO       This value is set by the Set_Slot_Power_Limit message or hardwired to "00b".         27:26       Reset Slot Power Limit Scale       RO       Reset to 00b.	13		RO	It is not implemented. Hardwired to 0b.
15Role_Base Error ReportingROoriginally defined in the Error Reporting ECN. The default value may be changed by auto-loading from EEPROM. Reset to 1b.17:16ReservedROReset to 00b.17:16ReservedROReset to 00b.17:16ReservedROReset to 00b.25:18Captured Slot Power Limit ValueROThis value is set by the Set_Slot_Power_Limit message or hardwired to "00h". Reset to 00b.27:26Captured Slot Power Limit ScaleROSpecifies the scale used for the Slot Power Limit Value. This value is set by the Set_Slot_Power_Limit Walue.27:26Captured Slot Power Limit ScaleROThis value is set by the Set_Slot_Power_Limit message or hardwired to "00b". Reset to 00b.27:26Captured Slot Power Limit ScaleROThis value is set by the Set_Slot_Power_Limit message or hardwired to "00b". Reset to 00b.	14		RO	It is not implemented. Hardwired to 0b.
17:16       Reserved       RO       Reset to 00b.         25:18       Captured Slot Power Limit Scale Value       In combination with the Slot Power Limit Scale Value, specifies the upper limit on power supplied by slot.         25:18       Captured Slot Power Limit Value       RO       This value is set by the Set_Slot_Power_Limit message or hardwired to "00h".         27:26       Captured Slot Power Limit Scale       RO       Specifies the scale used for the Slot Power_Limit Value.         27:26       Captured Slot Power Limit Scale       RO       This value is set by the Set_Slot_Power_Limit message or hardwired to "00b".         27:26       Captured Slot Power Limit Scale       RO       This value is set by the Set_Slot_Power_Limit message or hardwired to "00b".	15	—	RO	originally defined in the Error Reporting ECN. The default value may be changed by auto-loading from EEPROM.
25:18       Captured Slot Power Limit Value       RO       In combination with the Slot Power Limit Scale value, specifies the upper limit on power supplied by slot.         25:18       Captured Slot Power Limit Value       RO       This value is set by the Set_Slot_Power_Limit message or hardwired to "00h".         27:26       Captured Slot Power Limit Scale       RO       Specifies the scale used for the Slot Power Limit Value.         27:26       Captured Slot Power Limit Scale       RO       This value is set by the Set_Slot_Power_Limit message or hardwired to "00b".         27:26       Reset to 00b.       RO       This value is set by the Set_Slot_Power_Limit message or hardwired to "00b".	17:16	Reserved	RO	
27:26 Captured Slot Power Limit Scale RO RO RO Specifies the scale used for the Slot Power Limit Value. This value is set by the Set_Slot_Power_Limit message or hardwired to "00b". Reset to 00b.		Captured Slot Power		In combination with the Slot Power Limit Scale value, specifies the upper limit on power supplied by slot. This value is set by the Set_Slot_Power_Limit message or hardwired to "00h".
27:26 Captured Slot Power Limit Scale RO RO Reset to 00b.				
	27:26		RO	This value is set by the Set_Slot_Power_Limit message or hardwired to "00b".
	31:28	Reserved	RO	Reset to 0h.

## 6.2.52. DEVICE CONTROL REGISTER – OFFSET E8h

BIT	FUNCTION	TYPE	DESCRIPTION
0	Correctable Error Reporting Enable	RW	0b: Disable Correctable Error Reporting. 1b: Enable Correctable Error Reporting. Reset to 0b.
1	Non-Fatal Error Reporting Enable	RW	0b: Disable Non-Fatal Error Reporting. 1b: Enable Non-Fatal Error Reporting. Reset to 0b.
2	Fatal Error Reporting Enable	RW	0b: Disable Fatal Error Reporting. 1b: Enable Fatal Error Reporting. Reset to 0b.
3	Unsupported Request Reporting Enable	RW	0b: Disable Unsupported Request Reporting. 1b: Enable Unsupported Request Reporting. Reset to 0b.
4	Enable Relaxed Ordering	RO	It is not implemented. Reset to 0b.





BIT	FUNCTION	TYPE	DESCRIPTION
7:5	Max_Payload_Size	RW	This field sets maximum TLP payload size for the device. Permissible values that can be programmed are indicated by the Max_Payload_Size Supported in the Device Capabilities register. Any value exceeding the Max_Payload_Size Supported written to this register results into clamping to the Max_Payload_Size Supported value. Reset to 000b.
8	Extended Tag Field Enable	RO	It is not implemented. Hardwired to 0b.
9	Phantom Function Enable	RO	It is not implemented. Hardwired to 0b.
10	Auxiliary (AUX) Power PM Enable	RWS	When set, indicates that the I/O bridge is enabled to draw AUX power independent of PME AUX power. Reset to 0b.
11	Enable No Snoop	RO	It is not implemented. Hardwired to 0b.
14:12	Max_Read_ Request_Size	RO	It is not implemented. Hardwired to 000b.
15	Reserved	RO	Reset to 0b.

## 6.2.53. DEVICE STATUS REGISTER – OFFSET E8h

BIT	FUNCTION	TYPE	DESCRIPTION
16	Correctable Error Detected	RW1C	Asserted when correctable error is detected. Errors are logged in this register regardless of whether error reporting is enabled or not in the Device Control register. Reset to 0b.
17	Non-Fatal Error Detected	RW1C	Asserted when non-fatal error is detected. Errors are logged in this register regardless of whether error reporting is enabled or not in the Device Control register. Reset to 0b.
18	Fatal Error Detected	RW1C	Asserted when fatal error is detected. Errors are logged in this register regardless of whether error reporting is enabled or not in the Device Control register. Reset to 0b.
19	Unsupported Request Detected	RW1C	Asserted when unsupported request is detected. Errors are logged in this register regardless of whether error reporting is enabled or not in the Device Control register. Reset to 0b.
20	AUX Power Detected	RO	Asserted when the AUX power is detected by the I/O bridge Reset to 1b.
21	Transactions Pending	RO	It is not implemented. Hardwired to 0b.
31:22	Reserved	RO	Reset to 000h.

## 6.2.54. LINK CAPABILITIES REGISTER – OFFSET ECh

BIT	FUNCTION	TYPE	DESCRIPTION
3:0	Maximum Link Speed	RO	Indicates the Maximum Link Speed of the given PCIe Link. Defined encodings are: 0001b, which indicates 2.5 Gb/s Link Reset to 1h.
9:4	Maximum Link Width	RO	Indicates the maximum width of the given PCIe Link. Reset to 000001b (x1).

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BIT	FUNCTION	TYPE	DESCRIPTION
11:10	Active State Power Management (ASPM) Support	RO	Indicates the level of ASPM supported on the given PCIe Link. The I/O bridge supports LOs and L1 entry. The default value may be changed by auto-loading from EEPROM. Reset to 11b.
14:12	L0s Exit Latency	RO	Indicates the L0s exit latency for the given PCIe Link. The length of time this I/O bridge requires to complete transition from L0s to L0 is in the range of 256ns to less than 512ns. The default value may be changed by auto-loading from EEPROM. Reset to 011b.
17:15	L1 Exit Latency	RO	Indicates the L1 exit latency for the given PCIe Link. The length of time this I/O bridge requires to complete transition from L1 to L0 is in the range of 16us to less than 32us. The default value may be changed by auto-loading from EEPROM. Reset to 000b.
23:18	Reserved	RO	Reset to 00000b.
31:24	Port Number	RO	It is not implemented. Hardwired to 00h.

### 6.2.55. LINK CONTROL REGISTER – OFFSET F0h

BIT	FUNCTION	TYPE	DESCRIPTION
1:0	Active State Power Management (ASPM) Control	RW	00b: ASPM is Disabled. 01b: L0s Entry Enabled. 10b: L1 Entry Enabled. 11b: L0s and L1 Entry Enabled. Note that the receiver must be capable of entering L0s even when the field is disabled. Reset to 00b.
2	Reserved	RO	Reset to 0h.
3	Read Completion Boundary (RCB)	RO	It is not implemented. Hardwired to 0b.
4	Link Disable	RO	It is not implemented. Hardwired to 0b.
5	Retrain Link	RO	It is not implemented. Hardwired to 0b.
6	Common Clock Configuration	RW	<ul><li>0b: The components at both ends of a link are operating with asynchronous reference clock.</li><li>1b: The components at both ends of a link are operating with a distributed common reference clock.</li><li>Reset to 0b.</li></ul>
7	Extended Synch	RW	When set, it transmits 4096 FTS ordered sets in the L0s state for entering L0 state and transmits 1024 TS1 ordered sets in the L1 state for entering L0 state Reset to 0b.
15:8	RsvdP	RO	Reset to 00h.

#### 6.2.56. LINK STATUS REGISTER – OFFSET F0h

BIT	FUNCTION	TYPE	DESCRIPTION
19:16	Link Speed	RO	Indicates the negotiated Link Speed of the given PCIe Link. Defined encodings are: 0001b, which indicates 2.5 Gb/s Link Reset to 1h.
25:20	Negotiated Link Width	RO	Indicates the negotiated width of the given PCIe Link, Reset to 000001b.





BIT	FUNCTION	TYPE	DESCRIPTION
26	Training Error	RO	When set, indicates a Link training error occurred. This bit is cleared by hardware upon successful training of the link to the L0 link state. Reset to 0b.
27	Link Training	RO	When set, indicates the link training is in progress. Hardware clears this bit once link training is complete. Reset to 0b.
28	Slot Clock Configuration	RO	It is not implemented. Hardwired to 0b.
31:29	Reserved	RO	Reset to 000b.

# 6.2.57. PCI EXPRESS ADVANCED ERROR REPORTING CAPABILITY ID REGISTER – OFFSET 100h

BIT	FUNCTION	TYPE	DESCRIPTION
15:0	Extended Capabilities ID	RO	Read as 0001h to indicate that these are PCI express extended capability registers for advance error reporting.

#### 6.2.58. CAPABILITY VERSION – OFFSET 100h

BIT	FUNCTION	TYPE	DESCRIPTION
19:16	Capability Version	RO	Indicates PCI-SIG defined PCI Express capability structure version number.
			Reset to 1h.

#### 6.2.59. NEXT ITEM POINTER REGISTER – OFFSET 100h

BIT	FUNCTION	TYPE	DESCRIPTION
31:20	Next Capability	RO	Read as 00h. No other ECP registers.
	Offset		Reset to 000h.

#### 6.2.60. UNCORRECTABLE ERROR STATUS REGISTER – OFFSET 104h

BIT	FUNCTION	TYPE	DESCRIPTION
0	Training Error Status	RW1CS	When set, indicates that the Training Error event has occurred. Reset to 0b.
3:1	Reserved	RO	Reset to 000b.
4	Data Link Protocol Error Status	RW1CS	When set, indicates that the Data Link Protocol Error event has occurred. Reset to 0b.
11:5	Reserved	RO	Reset to 0000000b.
12	Poisoned TLP Status	RW1CS	When set, indicates that a Poisoned TLP has been received or generated. Reset to 0b.
13	Flow Control Protocol Error Status	RW1CS	When set, indicates that the Flow Control Protocol Error event has occurred. Reset to 0b.
14	Completion Timeout Status	RW1CS	When set, indicates that the Completion Timeout event has occurred. Reset to 0b.





BIT	FUNCTION	TYPE	DESCRIPTION
15	Completer Abort Status	RW1CS	When set, indicates that the Completer Abort event has occurred. Reset to 0b.
16	Unexpected Completion Status	RW1CS	When set, indicates that the Unexpected Completion event has occurred. Reset to 0b.
17	Receiver Overflow Status	RW1CS	When set, indicates that the Receiver Overflow event has occurred. Reset to 0b.
18	Malformed TLP Status	RW1CS	When set, indicates that a Malformed TLP has been received. Reset to 0b.
19	ECRC Error Status	RW1CS	When set, indicates that an ECRC Error has been detected. Reset to 0b.
20	Unsupported Request Error Status	RW1CS	When set, indicates that an Unsupported Request event has occurred. Reset to 0b.
31:21	Reserved	RO	Reset to 000h.

#### 6.2.61. UNCORRECTABLE ERROR MASK REGISTER – OFFSET 108h

BIT	FUNCTION	TYPE	DESCRIPTION
0	Training Error Mask	RWS	When set, the Training Error event is not logged in the Header Log register and not issued as an Error Message to RC either. Reset to 0b.
3:1	Reserved	RO	Reset to 000b.
4	Data Link Protocol Error Mask	RWS	When set, the Data Link Protocol Error event is not logged in the Header Log register and not issued as an Error Message to RC either. Reset to 0b.
11:5	Reserved	RO	Reset to 0000000b.
12	Poisoned TLP Mask	RWS	When set, an event of Poisoned TLP has been received or generated is not logged in the Header Log register and not issued as an Error Message to RC either. Reset to 0b.
13	Flow Control Protocol Error Mask	RWS	When set, the Flow Control Protocol Error event is not logged in the Header Log register and not issued as an Error Message to RC either. Reset to 0b.
14	Completion Timeout Mask	RWS	When set, the Completion Timeout event is not logged in the Header Log register and not issued as an Error Message to RC either. Reset to 0b.
15	Completer Abort Mask	RWS	When set, the Completer Abort event is not logged in the Header Log register and not issued as an Error Message to RC either. Reset to 0b.
16	Unexpected Completion Mask	RWS	When set, the Unexpected Completion event is not logged in the Header Log register and not issued as an Error Message to RC either. Reset to 0b.
17	Receiver Overflow Mask	RWS	When set, the Receiver Overflow event is not logged in the Header Log register and not issued as an Error Message to RC either. Reset to 0b.





BIT	FUNCTION	TYPE	DESCRIPTION
18	Malformed TLP Mask	RWS	When set, an event of Malformed TLP has been received is not logged in the Header Log register and not issued as an Error Message to RC either. Reset to 0b.
19	ECRC Error Mask	RWS	When set, an event of ECRC Error has been detected is not logged in the Header Log register and not issued as an Error Message to RC either. Reset to 0b.
20	Unsupported Request Error Mask	RWS	When set, the Unsupported Request event is not logged in the Header Log register and not issued as an Error Message to RC either. Reset to 0b.
31:21	Reserved	RO	Reset to 000h.

#### 6.2.62. UNCORRECTABLE ERROR SEVERITY REGISTER – OFFSET 10Ch

BIT	FUNCTION	TYPE	DESCRIPTION
			0b: Non-Fatal.
0	Training Error Severity	RWS	1b: Fatal.
			Reset to 1b.
3:1	Reserved	RO	Reset to 000b.
4	Data Link Protocol Error Severity	RWS	0b: Non-Fatal. 1b: Fatal.
	<b>D</b>		Reset to 1b.
11:5	Reserved	RO	Reset to 0000000b.
12	Poisoned TLP Severity	RWS	0b: Non-Fatal. 1b: Fatal.
			Reset to 0b. 0b: Non-Fatal.
13	Flow Control Protocol Error	RWS	1b: Fatal.
	Severity		Reset to 1b.
	a 1.1		0b: Non-Fatal.
14	Completion Timeout Error	RWS	1b: Fatal.
	Severity		Reset to 0b.
		RWS	0b: Non-Fatal.
15	Completer Abort Severity		1b: Fatal.
	5		Reset to 0b.
	Unexpected		0b: Non-Fatal.
16	Completion	RWS	1b: Fatal.
	Severity		Reset to 0b.
		RWS	0b: Non-Fatal.
17	Receiver Overflow Severity		1b: Fatal.
			Reset to 1b.
			0b: Non-Fatal.
18	Malformed TLP Severity	RWS	1b: Fatal.
	-		Reset to 1b.
			0b: Non-Fatal.
19	ECRC Error Severity	RWS	1b: Fatal.
		1000	Deart to Oh
L			Reset to 0b.

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BIT	FUNCTION	TYPE	DESCRIPTION
20	Unsupported Request Error Severity	RWS	0b: Non-Fatal. 1b: Fatal. Reset to 0b.
31:21	Reserved	RO	Reset to 000h.

#### 6.2.63. CORRECTABLE ERROR STATUS REGISTER – OFFSET 110h

BIT	FUNCTION	TYPE	DESCRIPTION
0	Receiver Error Status	RW1CS	When set, the Receiver Error event is detected. Reset to 0b.
5:1	Reserved	RO	Reset to 0h.
6	Bad TLP Status	RW1CS	When set, the event of Bad TLP has been received is detected. Reset to 0b.
7	Bad DLLP Status	RW1CS	When set, the event of Bad DLLP has been received is detected. Reset to 0b.
8	REPLAY_NUM Rollover status	RW1CS	When set, the REPLAY_NUM Rollover event is detected. Reset to 0b.
11:9	Reserved	RO	Reset to 000b.
12	Replay Timer Timeout status	RW1CS	When set, the Replay Timer Timeout event is detected. Reset to 0b.
31:13	Reserved	RO	Reset to 00000h.

#### 6.2.64. CORRECTABLE ERROR MASK REGISTER – OFFSET 114h

BIT	FUNCTION	TYPE	DESCRIPTION
0	Receiver Error Mask	RWS	When set, the Receiver Error event is not logged in the Header Log register and not issued as an Error Message to RC either. Reset to 0b.
5:1	Reserved	RO	Reset to 0h.
6	Bad TLP Mask	RWS	When set, the event of Bad TLP has been received is not logged in the Header Log register and not issued as an Error Message to RC either. Reset to 0b.
7	Bad DLLP Mask	RWS	When set, the event of Bad DLLP has been received is not logged in the Header Log register and not issued as an Error Message to RC either. Reset to 0b.
8	REPLAY_NUM Rollover Mask	RWS	When set, the REPLAY_NUM Rollover event is not logged in the Header Log register and not issued as an Error Message to RC either. Reset to 0b.
11:9	Reserved	RO	Reset to 000b.
12	Replay Timer Timeout Mask	RWS	When set, the Replay Timer Timeout event is not logged in the Header Log register and not issued as an Error Message to RC either. Reset to 0b.
31:13	Reserved	RO	Reset to 00000h.





#### 6.2.65. ADVANCE ERROR CAPABILITIES AND CONTROL REGISTER – OFFSET 118h

BIT	FUNCTION	TYPE	DESCRIPTION
4:0	First Error Pointer	ROS	It indicates the bit position of the first error reported in the Uncorrectable Error Status register. Reset to 00000b.
5	ECRC Generation Capable	RO	When set, it indicates the I/O bridge has the capability to generate ECRC. Reset to 1b.
6	ECRC Generation Enable	RWS	When set, it enables the generation of ECRC when needed. Reset to 0b.
7	ECRC Check Capable	RO	When set, it indicates the I/O bridge has the capability to check ECRC. Reset to 1b.
8	ECRC Check Enable	RWS	When set, the function of checking ECRC is enabled. Reset to 0b.
31:9	Reserved	RO	Reset to 000000h.

#### 6.2.66. HEADER LOG REGISTER – OFFSET From 11Ch to 128h

BIT	FUNCTION	TYPE	DESCRIPTION
3:0	1 <sup>st</sup> DWORD	RO	Hold the 1st DWORD of TLP Header. The Head byte is in big endian.
7:4	2 <sup>nd</sup> DWORD	RO	Hold the 2nd DWORD of TLP Header. The Head byte is in big endian.
11:8	3 <sup>rd</sup> DWORD	RO	Hold the 3rd DWORD of TLP Header. The Head byte is in big endian.
15:12	4 <sup>th</sup> DWORD	RO	Hold the 4th DWORD of TLP Header. The Head byte is in big endian.



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### 7. UART REGISTER DESCRIPTION

### 7.1. REGISTERS IN I/O MODE

Each UART channel has a dedicated 8-byte register block in I/O mode. The register block can be accessed by the UART I/O Base Address, which is obtained by adding the UART Register Offset to the content of the Base Address Register 0 (BAR0). The following diagram shows the arrangement of individual UART register blocks.

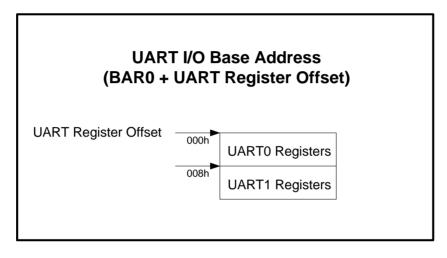


Figure 7-1 UART Register Block Arrangement in I/O Mode

Table 7-1	UART	<b>Base Address</b>	in I/O	Mode
-----------	------	---------------------	--------	------

UART	UART I/O Base Address
UART0	BAR0 + 000h
UART1	BAR0 + 008h





Each register in the UART Register Block can be access by adding an offset to the UART I/O Base Address. The following table lists the arrangement of the registers in the UART Register Block in I/O mode.

Öffset	Register Name	Mnemonic	Register Type
UART I/O Base Address + 00h	Receive Holding Register	RHR	RO
UART I/O Base Address + 00h	Transmit Holding Register	THR	WO
UART I/O Base Address + 01h	Interrupt Enable Register	IER	RW
UART I/O Base Address + 02h	Interrupt Status Register	ISR	RO
UART I/O Base Address + 02h	FIFO Control Register	FCR	WO
UART I/O Base Address + 03h	Line Control Register	LCR	RW
UART I/O Base Address + 04h	Modem Control Register	MCR	RW
UART I/O Base Address + 05h	Line Status Register	LSR	RO
UART I/O Base Address + 06h	Modem Status Register	MSR	RO
UART I/O Base Address + 07h	Special Function register	SFR	RW
Addit	ional Standard Registers (Required	LCR[7] = 1)	
UART I/O Base Address + 00h	Division Latch Low	DLL	RW
UART I/O Base Address + 01h	Division Latch High	DLH	RW
UART I/O Base Address + 02h	Sample Clock Register	SCR	RW

#### Table 7-2 Registers in I/O Mode

#### 7.1.1. RECEIVE HOLDING REGISTER – OFFSET 00h

BIT	FUNCTION	TYPE	DESCRIPTION
7:0	Rx Holding	RO	Data received
			Reset to 00h.

#### 7.1.2. TRANSMIT HOLDING REGISTER – OFFSET 00h

BIT	FUNCTION	TYPE	DESCRIPTION
7:0	Tx Holding	WO	Data to transmit
			Reset to 00h.

#### 7.1.3. INTERRUPT ENABLE REGISTER – OFFSET 01h

BIT	FUNCTION	TYPE	DESCRIPTION
0	Rx Data Available	RW	0b: Disable the Receive Data Ready Interrupt
	Interrupt		1b: Enable the Receive Data Ready Interrupt
			Reset to 0b.
1	Tx Empty Interrupt	RW	0b: Disable the Transmit Holding Register Empty Interrupt
			1b: Enable the Transmit Holding Register Empty Interrupt
			Reset to 0b.
	D.G. M.		
2	Rx Status Interrupt	RW	0b: Disable the Receive Line Status Interrupt
			1b: Enable the Receive Line Status Interrupt
			Reset to 0b.
3	Modem Status	RW	0b: Disable the Modem Status Register Interrupt
	Interrupt		1b: Enable the Modem Status Register Interrupt
			Reset to 0b.
4	Xoff/Special	RW	0b: Disable the Software Flow Control Interrupt
	character interrupt		1b: Enable the Software Flow Control Interrupt
			Reset to 0b.





BIT	FUNCTION	TYPE	DESCRIPTION
5	RTS Interrupt	RW	0b: Disable RTS/DTR Interrupt
			1b: Enable RTS/DTR Interrupt
			Reset to 0b.
6	CTS Interrupt	RW	0b: Disable CTS/DSR interrupt
			1b: Enable CTS/DSR interrupt
			Reset to 0b.
7	Reserved	RW	

#### 7.1.4. INTERRUPT STATUS REGISTER – OFFSET 02h

BIT	FUNCTION	TYPE	DESCRIPTION
7:0	Interrupt Status	RO	0b: An interrupt is pending 1b: No interrupt pending
			Reset to C1h.

Priority	Interru	pt Status		Interrupt Source					
Level	BIT-7	BIT-6	BIT-5	BIT-4	BIT-3	BIT-2	BIT-1	BIT-0	
1	1	1	0	0	0	1	1	0	Rx data error
2	1	1	0	0	0	1	0	0	Rx data available
3	1	1	0	0	1	1	0	0	Rx time-out
4	1	1	0	0	0	0	1	0	Tx FIFO empty
5	1	1	0	0	0	0	0	0	Modem status change
6	1	1	0	1	0	0	0	0	Xoff or special
									character detected
7	1	1	1	0	0	0	0	0	CTS or RTS state
									changed
Х	1	1	0	0	0	0	0	1	No interrupt pending

#### 7.1.5. FIFO CONTROL REGISTER – OFFSET 02h

BIT	FUNCTION	TYPE	DESCRIPTION			
0	FIFO Mode Enable	WO	0b: Disable the FIFO mode			
			1b: Enable the FIFO mode			
			Reset to 0b.			
1	Rx FIFO Flush	WO	0b: No action			
			1b: Reset the receive FIFO, self-	-clear after resetting the FIFO		
			Reset to 0b.			
2	Tx FIFO Flush	WO	0b: No action			
			1b: Reset the transmit FIFO, self	f-clear after resetting the FIFO		
			Reset to 0b.			
3	Reserved	WO	Reset to 0b.			
5:4	Tx Trigger Level	WO	In the Enhanced Mode.			
			00b: 16			
			000: 16 01b: 32			
			10b: 64			
			11b: 112			
			110. 112			
			Reset to 00b.			
7:6	Rx Trigger Level	WO	In the Non-Enhanced mode	In the Enhanced mode		
			00b: 1	00b: 15		
			01b: 4	01b: 31		
			10b: 8	10b: 63		
			11b: 14	11b: 111		
			Reset to 00b.			

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#### 7.1.6. LINE CONTROL REGISTER – OFFSET 03h

BIT	FUNCTION	TYPE	DESCRIPT	ΓΙΟΝ			
1:0	Data Length	RW	00b: 5-bit d				
			01b: 6-bit d				
			10b: 7-bit d				
			11b: 8-bit da	ata length			
			Reset to 11b	).			
2	Stop-Bit Length	RW			- ·		
			Bit 2 value	e	Data leng	th	Stop bit length
			0		5,6,7,8		1
			1		5		1.5
			1		6,7,8		2
			Reset to 0b.				
5:3	Parity Type	RW					
			Bit 5	Bit 4	Bit 3	Parity se	
			X	Х	0	No parit	
			0	0	1	Odd par	
			0	1	1	Even pa	rity
			1	0	1	Mark	
			1	1	1	Space	
			Reset to 000	)b.			
6	Transmission	RW	0b: No trans	smit break	c condition		
	Break					o a space f	for alerting the remote
			receiver	of a line	break condi	tion.	, i i i i i i i i i i i i i i i i i i i
			Reset to 0b.				
7	Divisor Latch	RW	0b: Data reg				
	Enable		1b: Divisor	latch regi	sters are sel	ected	
			<b>D</b>				
			Reset to 0b.				

#### 7.1.7. MODEM CONTROL REGISTER – OFFSET 04h

BIT	FUNCTION	TYPE	DESCRIPTION
0	DTR Pin Control	RW	
0	DTR PIII Collutoi	ĸw	0b: Forces DTR output high
			1b: Forces DTR output low
			Reset to 0b.
1	RTS Pin Control	RW	0b: Forces RTS output high
			1b: Forces RTS output low
			_
			Reset to 0b.
2	Output 1	RW	When the Internal Loopback Mode is enabled by setting Modem
-			Control Register Bit[4], output of the Output1 is routed to RI.
			control register Dit( ), output of the output is found to real
			Reset to 0b.
3	Output 2	RW	When the Internal Loopback Mode is enabled by setting Modem
5	Output 2	K W	1 5 6
			Control Register Bit[4], output of the Output2 is routed to DCD.
			<b>D</b>
			Reset to 0b.
4	Internal Loopback	RW	0b: Disables Internal Loopback Mode
	Mode	1	1b: Enables Internal Loopback Mode
		1	
		1	Reset to 0b.





BIT	FUNCTION	TYPE	DESCRIPTION			
5	AFE	RW	Autoflow Control Enable. When the AFE is enabled, autoflow control is enabled. When it is disabled, the diagnostic mode is enabled. In the diagnostic mode, transmitted data is immediately received. When AFE is set to "1", MCR Bit 1 is used to enable and disable the auto-RTS.			
			MCR Bit 5 MCR Bit 1 Configuration (AFE) (RTS)			
			1 1 Auto-RTS and auto-CTS are enabled (autoflow control enabled).			
			1 0 Only auto-CTS is enabled.			
			0 x Auto-RTS and auto-CTS are disabled.			
			Reset to 0b.			
6	Reserved		Reset to 0b.			
7	Enhanced Transmission	RW	<ul> <li>Ob: Insert 1, 1.5 or 2 stop-bits between two transmitted characters.</li> <li>Ib: Insert 0.5 stop-bits between two transmitted characters.</li> <li>Note: Enabling feature may result in certain compatibility issues.</li> <li>This feature is only recommended when using two Pericom UART devices.</li> </ul>			
			Reset to 0b.			

#### 7.1.8. LINE STATUS REGISTER – OFFSET 05h

FUNCTION	TYPE	DESCRIPTION
Rx Data Available	RO	0b: No data in the receive FIFO
		1b: Data in the receive FIFO
		Reset to 0b.
Rx FIFO Overrun	RO	0b: No overrun error
		1b: Overrun error
	DO	Reset to 0b.
Rx Parity Error	ĸŎ	0b: No parity error
		1b: Parity error
		Reset to 0b.
Rx Frame Error	RO	0b: No framing error
		1b: Framing error
		-
		Reset to 0b.
Rx Break Error	RO	0b: No break condition
		1b: Break condition
		Reset to 0b.
Tx Empty	RO	0b: Tx Holding Register is not empty.
		1b: Tx Holding Register is empty.
		Reset to 0b.
Tx Complete	RO	0b: Tx Shift Register is not empty.
in complete		1b: Tx Shift Register is empty.
		Reset to 0b.
	Rx Data Available Rx FIFO Overrun Rx Parity Error Rx Frame Error	Rx Data AvailableRORx FIFO OverrunRORx FIFO OverrunRORx Parity ErrorRORx Frame ErrorRORx Break ErrorROTx EmptyRO





BIT	FUNCTION	TYPE	DESCRIPTION
7	Rx Data Error	RO	0b: No Rx FIFO error
			1b: Rx FIFO error
			Reset to 0b.

#### 7.1.9. MODEM STATUS REGISTER – OFFSET 06h

BIT	FUNCTION	TYPE	DESCRIPTION
0	Delta CTS	RO	0b: No change in CTS input.
			1b: Indicates the CTS input has changed state.
			This bit is read-clear.
			Reset to 0b.
1	Delta DSR	RO	0b: No change in DSR input.
			1b: Indicates the DSR input has changed state.
			This bit is read-clear.
			Reset to 0b.
2	Trailing RI Edge	RO	0b: No change in RI input
			1b: Indicates the RI input has changed state from the logic 0 to
			the logic 1.
			This bit is read-clear.
			Reset to 0b.
3	Delta DCD	RO	0b: No change in DCD input
			1b: Indicates the DCD input has changed state.
			This bit is read-clear.
			Reset to 0b.
4	CTS	RO	0b: The CTS input state is the logic 0
			1b: The CTS input state is the logic 1
			Reset to 0b.
5	DSR	RO	0b: The DSR input state is the logic 0
			1b: The DSR input state is the logic 1
			Reset to 0b.
6	RI	RO	The input state of RI pin
			Reset to 0b.
7	DCD	RO	The input state of DCD pin
			Reset to 0b.

#### 7.1.10. SPECIAL FUNCTION REGISTER – OFFSET 07h

BIT	FUNCTION	TYPE	DESCRIPTION
0	Force Transmission	RW	Forces transmitter to always to transmit data.
			1b: Enabled
			0b: Disabled
			Reset to 0b.
1	Auto DSR and	RW	Auto DSR and DTR flow control enable
	DTR Flow Control		
			1b: Enables DSR and DTR auto flow control
			0b: Disables DSR and DTR auto flow control
			Reset to 0b.
2	Reserved	RO	Reset to 0b.
3	Reserved	RO	Reset to 0b.
4	Reserved	RW	Reset to 0b.

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BIT	FUNCTION	TYPE	DESCRIPTION
5	950 Mode	RW	1b: Enables 950 mode
			0b: Non-950 mode
			Reset to 0b.
6	RFD / LSR	RW	1b: OFFSET 15 bit[7:0] acts as the Line Status Register Counter
	Counter Select		0b: OFFSET 15 bit[7:0] acts as the Receive FIFO Data Counter
			Reset to 0b.
7	TFD / SCR Select	RW	1b: OFFSET 16 bit[7:0] acts as the Transmit FIFO Data Counter
			0b: OFFSET 16 bit[7:0] acts as the Sample Clock Register
			Reset to 0b.
7:6	Reserved	RW	Reset to 00b.

#### 7.1.11. DIVISOR LATCH LOW REGISTER – OFFSET 00h, LCR[7] = 1

BIT	FUNCTION	TYPE	DESCRIPTION
7:0	Divisor Low	RW	Lower-part of the divisor register
			Reset to 00h.

#### 7.1.12. DIVISOR LATCH HIGH REGISTER – OFFSET 01h, LCR[7] = 1

BIT	FUNCTION	TYPE	DESCRIPTION
7:0	Divisor High	RW	Higher-part of the divisor register
			Reset to 00h.

#### 7.1.13. SAMPLE CLOCK REGISTER – OFFSET 02h, LCR[7] = 1

BIT	FUNCTION	TYPE	DESCRIPTION						
3:0	Sample Clock	RW	This register determines the Sample Clock value (SC) used in the Baud Rate Generator. Please refer to 5.2.12 Baud Rate Generation for more detail						
			0000b: SC = 16 0001b: SC = 15 0010b: SC = 14 0011b: SC = 13 0100b: SC = 12	0101b: SC = 11 0110b: SC = 10 0111b: SC = 9 1000b: SC = 8 1001b: SC = 7	1010b: $SC = 6$ 1011b: $SC = 5$ 1100b: $SC = 4$ Other settings are reserved.				
			Reset to 0h.						
7:4	Reserve	R	Reset to 0h.						





### 7.2. REGISTERS IN MEMORY-MAPPING MODE

Each UART channel has a dedicated 512-byte register block in Memory mode. The register block can be accessed by the UART Memory Base Address, which is obtained by adding the UART Register Offset to the content of the Base Address Register 1 (BAR1). The following diagram shows the arrangement of individual UART register blocks.

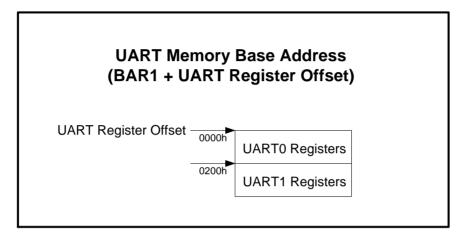


Figure 7-2 UART Register Block Arrangement in Memory Mode

Table 7-3 UART Base Address in Memory Mode

UART	UART I/O Base Address
UART0	BAR1 + 0000h
UART1	BAR1 + 0200h





Each register in the UART Register Block can be access by adding an offset to the UART Memory Base Address. The following table lists the arrangement of the registers in the UART Register Block in memory mode.

Table 7-4 Memory-Map Mode			
Offset	Register Name	Mnemonic	Register Type
UART Memory Base Address + 00h	Receive Holding Register	RHR	RO
UART Memory Base Address + 00h	Transmit Holding Register	THR	WO
UART Memory Base Address + 01h	Interrupt Enable Register	IER	RW
UART Memory Base Address + 02h	Interrupt Status Register	ISR	RO
UART Memory Base Address + 02h	FIFO Control Register	FCR	WO
UART Memory Base Address + 04h	Line Control Register	LCR	RW
UART Memory Base Address + 04h	Modem Control Register	MCR	RW
UART Memory Base Address + 05h	Line Status Register	LSR	RO
UART Memory Base Address + 06h	Modem Status Register	MSR	RO
UART Memory Base Address + 07h	Special Function Register	SFR	RW
UART Memory Base Address + 08h	Divisor Latch Low	DLL	WO
UART Memory Base Address + 09h	Divisor Latch High	DLH	WO
		n	
UART Memory Base Address + 0Ah	Enhanced Function Register	EFR	RW
UART Memory Base Address + 0Bh	XON 1 Character/Special	XON1	RW
	Character 1		
UART Memory Base Address + 0Ch	XON 2 Character/Special	XON2	RW
	Character 2		
UART Memory Base Address + 0Dh	XOFF 1 Character/Special	XOFF1	RW
	Character 3	MOTES	DIV
UART Memory Base Address + 0Eh	XOFF 2 Character/Special	XOFF2	RW
	Character 3	4.60	DUI
UART Memory Base Address + 0Fh	ACR Register	ASR	RW
UART Memory Base Address + 10h	Transmitter Interrupt Trigger Level	TTL	RW
UART Memory Base Address + 11h	Receiver Interrupt Trigger Level	RTL	RW
UART Memory Base Address + 12h	Automatic Flow control lower trigger level	FCL	RW
UART Memory Base Address + 13h	Automatic Flow control lower higher level	FCH	RW
UART Memory Base Address + 14h	Baud rate Prescale	CPR	RW
UART Memory Base Address + 15h	Receive FIFO Data Counter /	RFD/LSR	RO
	Line Status Register Counter	Counter	
UART Memory Base Address + 16h	Transmit FIFO Data Counter /	TFD	RW
5	Sample Clock Register	Counter /	
		SCR	
UART Memory Base Address + 17h	Global Register of LSR	GLSR	RW
UART Memory Base Address + 100h	UART0 FIFO DATA Register.	FIFO_D	RW
~17Fh	Use this register to map FIFO		
	data content.		
UART Memory Base Address + 180h	UART0 FIFO DATA LSR	FIFO_LSR	RW
~1FFh	Register. Use this register to map		
	FIFO data relative LSR content.		

#### ... ....

#### 7.2.1. RECEIVE HOLDING REGISTER – OFFSET 00h

BIT	FUNCTION	TYPE	DESCRIPTION
7:0	Rx Holding	RO	When data are read from the Receive Holding Register (RHR), they are removed from the top of the receiver's associated
			FIFOs, which holds a queue of data received by the receiver.
			Data read from the RHR when the FIFOs are empty are invalid. The Line Status Register (LSR) indicates the full or empty status
			of the FIFOs.
			Reset to 00h.

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#### 7.2.2. TRANSMIT HOLDING REGISTER – OFFSET 00h

BIT	FUNCTION	TYPE	DESCRIPTION
7:0	Tx Holding	WO	<ul> <li>When data are written to the Transmit Holding Register (THR), they are written to the bottom of the transmitter's associated FIFOs, which holds a queue of data to be transmitted by the transmitter.</li> <li>Data written to the THR when the FIFOs are full are lost. The Line Status Register (LSR) indicates the full or empty status of the FIFOs.</li> </ul>
			Reset to 00h.

#### 7.2.3. INTERRUPT ENABLE REGISTER – OFFSET 01h

BIT	FUNCTION	TYPE	DESCRIPTION
0	Rx Data Available Interrupt	RW	0b: Disable the Receive Data Ready Interrupt 1b: Enable the Receive Data Ready Interrupt
			Reset to 0b.
1	Tx Empty Interrupt	RW	0b: Disable the Transmit Holding Register Empty Interrupt 1b: Enable the Transmit Holding Register Empty Interrupt
			Reset to 0b.
2	Rx Error Status	RW	0b: Disable the Receive Line Status Interrupt
			1b: Enable the Receive Line Status Interrupt
			Reset to 0b.
3	Modem Status	RW	0b: Disable the Modem Status Register Interrupt
	Interrupt		1b: Enable the Modem Status Register Interrupt
			Reset to 0b.
4	Xoff/Special	RW	0b: Disable the Software Flow Control Interrupt
	character interrupt		1b: Enable the Software Flow Control Interrupt
			Reset to 0b.
5	RTS Interrupt	RW	0b: Disable RTS/DTR Interrupt
			1b: Enable RTS/DTR Interrupt
			Reset to 0b.
6	CTS Interrupt	RW	0b: Disable CTS/DSR interrupt
			1b: Enable CTS/DSR interrupt
			Reset to 0b.
7	Reserved	RW	Reset to 0b.

#### 7.2.4. INTERRUPT STATUS REGISTER – OFFSET 02h

BIT	FUNCTION	TYPE	DESCRIPTION
7:0	Interrupt Status	RO	0b: An interrupt is pending
			1b: No interrupt pending
			Reset to C1h.

Priority	Interru	pt Status	Interrupt Source						
Level	BIT-7	BIT-6	BIT-5	BIT-4	BIT-3	BIT-2	BIT-1	BIT-0	
1	1	1	0	0	0	1	1	0	Rx data error
2	1	1	0	0	0	1	0	0	Rx data available
3	1	1	0	0	1	1	0	0	Rx time-out
4	1	1	0	0	0	0	1	0	Tx FIFO empty
5	1	1	0	0	0	0	0	0	Modem status change

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6	1	1	0	1	0	0	0	0	Xoff or special
									character detected
7	1	1	1	0	0	0	0	0	CTS or RTS state
									changed
Х	1	1	0	0	0	0	0	1	No interrupt pending

#### 7.2.5. FIFO CONTROL REGISTER – OFFSET 02h

BIT	FUNCTION	TYPE	DESCRIPTION					
0	FIFO Mode Enable	WO	0b: Disable the FIFO mode					
			1b: Enable the FIFO mode					
			Reset to 0b.					
1	Rx FIFO Flush	WO	0b: No action					
			1b: Reset the receive FIFO, sel	f-clear after resetting the FIFO				
			Reset to 0b.					
2	Tx FIFO Flush	WO	0b: No action					
			1b: Reset the transmit FIFO, se	elf-clear after resetting the FIFO				
			Reset to 0b.					
3	Reserved	WO	Reset to 0b					
5:4	Tx Trigger Level	WO	In the Enhanced Mode:					
511	in ingger bever							
			00b: 16					
			01b: 32					
			10b: 64					
			11b: 112					
			Reset to 00b.					
7:6	Rx Trigger Level	WO	In the Non-Enhanced mode	In the Enhanced mode				
			00b: 1	00b: 15				
			01b: 4	01b: 31				
			10b: 8 10b: 63					
			11b: 14	11b: 111				
			Reset to 00b.					

#### 7.2.6. LINE CONTROL REGISTER – OFFSET 03h

BIT	FUNCTION	TYPE	DESCRI	PTION						
1:0	Data Length	RW	00b: 5-bit data length							
			01b: 6-bit data length							
			10b: 7-bit	data length	ı					
			11b: 8-bit	data length	ı					
			Reset to 00b.							
2	Stop-Bit Length	RW								
			Bit 2 val	ue	Data len	gth	Stop bit length			
			0		5,6,7,8		1			
			1		5		1.5			
			1		6,7,8		2			
			Reset to 0	b.						
5:3	Parity Type	RW								
			Bit 5	Bit 4	Bit 3	Parity s	election			
			Х	Х	0	No pari	ty			
			0	0	1	Odd par	rity			
			0	1	1	Even pa	rity			
			1	0	1	Mark				
			1	1	1	Space				
			Reset to 0	00b.						





BIT	FUNCTION	TYPE	DESCRIPTION
6	Transmission	RW	0b: No transmit break condition
	Break		1b: Force the transmitter output to a space for alerting the remote receiver of a line break condition.
			Reset to 0b.
7	Divisor Latch	RW	0b: Data registers are selected
	Enable		1b: Divisor latch registers are selected
			Reset to 0b.

### 7.2.7. MODEM CONTROL REGISTER – OFFSET 04h

BIT	FUNCTION	ТҮРЕ	DESCRIPTION	
0	DTR Pin Control	RW	0b: Forces DTR output	high
			1b: Forces DTR output	
			Reset to 0b.	
1	RTS Pin Control	RW	0b: Forces RTS output l	
			1b: Forces RTS output 1	ow
-		DIV	Reset to 0b.	
2	Output 1	RW		back Mode is enabled by setting Modem output of the Output1 is routed to RI.
			Reset to 0b.	
3	Output 2	RW		back Mode is enabled by setting Modem output of the Output2 is routed to DCD.
4	T. 17 1 1	DIV	Reset to 0b.	1 1 1 1 1
4	Internal Loopback Mode	RW	0b: Disables Internal Lo 1b: Enables Internal Lo	
			Reset to 0b.	
5	AFE	RW		le. When the AFE is enabled, autoflow n it is disabled, the diagnostic mode is
				ic mode, transmitted data is immediately
			When AFE is set to "1" the auto-RTS.	, MCR Bit 1 is used to enable and disable
			MCR Bit 5 MCR 1 (AFE) (RTS)	Bit 1 Configuration
			1 1	Auto-RTS and auto-CTS are enabled (autoflow control
				enabled).
			1 0	Only auto-CTS is enabled.
			0 x	Auto-RTS and auto-CTS are disabled.
			Reset to 0b.	
6	Reserved		Reset to 0b.	
7	Enhanced	RW		p-bits between two transmitted
	Transmission		characters. 1b: Insert 0.5 stop-bits l	between two transmitted characters.
			Note: Enabling feature	may result in certain compatibility issues.
				ommended when using two Pericom
			Reset to 0b.	





#### 7.2.8. LINE STATUS REGISTER – OFFSET 05h

BIT	FUNCTION	TYPE	DESCRIPTION
0	Rx Data Available	RO	0b: No data in the receive FIFO
			1b: Data in the receive FIFO
			Reset to 0b.
1	Rx FIFO Overrun	RO	0b: No overrun error
			1b: Overrun error
-			Reset to 0b.
2	Rx Parity Error	RO	0b: No parity error
			1b: Parity error
2		DO	Reset to 0b.
3	Rx Frame Error	RO	0b: No framing error
			1b: Framing error
			Reset to 0b.
4	Rx Break Error	RO	Ob: No break condition
•	The Brown Enfor		1b: Break condition
			Reset to 0b.
5	Tx Empty	RO	0b: Tx Holding Register is not empty.
			1b: Tx Holding Register is empty.
			Reset to 0b.
6	Tx Complete	RO	0b: Tx Shift Register is not empty.
			1b: Tx Shift Register is empty.
_			Reset to 0b.
7	Rx Data Error	RO	0b: No Rx FIFO error
			1b: Rx FIFO error
			Reset to 0b.

#### 7.2.9. MODEM STATUS REGISTER – OFFSET 06h

DIT	DINCTION		DEGODIPEION
BIT	FUNCTION	TYPE	DESCRIPTION
0	Delta CTS	RO	0b: No change in CTS input.
			1b: Indicates the CTS input has changed state.
			This bit is read-clear.
			Reset to 0b.
1	Delta DSR	RO	0b: No change in DSR input.
		_	1b: Indicates the DSR input has changed state.
			This bit is read-clear.
			Reset to 0b.
2	Delta RI	RO	0b: No change in RI input
			1b: Indicates the RI input has changed state from the logic 0 to
			the logic 1.
			This bit is read-clear.
			Reset to 0b.
3	Delta DCD	RO	0b: No change in DCD input
			1b: Indicates the DCD input has changed state.
			This bit is read-clear.
			Reset to 0b.

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BIT	FUNCTION	TYPE	DESCRIPTION
4	CTS	RO	0b: The CTS input state is the logic 0
			1b: The CTS input state is the logic 1
			Reset to 0b.
5	DSR	RO	0b: The DSR input state is the logic 0
			1b: The DSR input state is the logic 1
			Reset to 0b.
6	RI	RO	The input state of RI pin
			Reset to 0b.
7	DCD	RO	The input state of DCD pin
			Reset to 0b.

#### 7.2.10. SPECIAL FUNCTION REGISTER – OFFSET 07h

BIT	FUNCTION	TYPE	DESCRIPTION
0	Force Transmission	RW	Forces transmitter to always to transmit data.
			1b: Enabled 0b: Disabled
			Reset to 0b.
1	Auto DSR and DTR Flow Control	RW	Auto DSR and DTR flow control enable
			1b: Enables DSR and DTR auto flow control
			0b: Disables DSR and DTR auto flow control
			Reset to 0b.
2	Reserved	RO	Reset to 0b.
3	Reserved	RO	Reset to 0b.
4	Reserved	RW	Reset to 0b.
5	950 Mode	RW	1b: Enables 950 mode
			0b: Non-950 mode
			Reset to 0b.
6	RFD / LSR	RW	1b: OFFSET 15 bit[7:0] acts as the Line Status Register Counter
	Counter Select		0b: OFFSET 15 bit[7:0] acts as the Receive FIFO Data Counter
			Reset to 0b.
7	TFD / SCR Select	RW	1b: OFFSET 16 bit[7:0] acts as the Transmit FIFO Data Counter
			0b: OFFSET 16 bit[7:0] acts as the Sample Clock Register
			Reset to 0b.

#### 7.2.11. DIVISOR LATCH LOW REGISTER – OFFSET 08h

BIT	FUNCTION	TYPE	DESCRIPTION
7:0	Divisor Low	RW	Lower-part of the divisor register
			D
			Reset to 00h.

#### 7.2.12. DIVISOR LATCH HIGH REGISTER – OFFSET 09h

BIT	FUNCTION	TYPE	DESCRIPTION
7:0	Divisor High	RW	Higher-part of the divisor register
			Reset to 00h.





#### 7.2.13. ENHANCED FUNCTION REGISTER - OFFSET 0Ah

BIT	FUNCTION	TYPE	DESCRIPTION
1:0	In-Band Receive Flow Control Mode	RW	<ul> <li>When in-band receive flow control is enabled, the UART compares the received data with the programmed XOFF character(s). When this occurs, the UART will disable transmission as soon as any current character transmission is complete. The UART then compares the received data with the programmed XON character(s). When a match occurs, the UART will re-enable transmission (see section 7.11.6).</li> <li>00b: In-band receive flow control is disabled.</li> <li>01b: Single character in-band receive flow control enabled, recognising XON2 as the XON character and XOFF2 as the XOFF character.</li> <li>10b: Single character in-band receive flow control enabled, recognising XON1 as the XON character and XOFF1 and the XOFF character.</li> <li>11b: The behavior of the receive flow control is dependent on the configuration of EFR[3:2]. Single character in-band receive</li> </ul>
			flow control is enabled, accepting XON1 or XON2 as valid XON characters and XOFF1 or XOFF2 as valid XOFF characters when EFR[3:2] = "01" or "10". EFR[1:0] should not be set to "11" when EFR[3:2] is '00'.
3:2	In-Band Transmit Flow Control Mode	RW	Reset to 00b.         When in-band transmit flow control is enabled, XON/XOFF         character are inserted into the data stream whenever the         RFL passes the upper trigger level and falls below the lower         trigger level respectively. For automatic in-band flow control, bit         4 of EFR must be set. The combinations of software transmit         flow control can then be selected by programming EFR[3:2] as         follows.         00b:       In-band transmit flow control is disabled logic.         01b:       Single character in-band transmit flow control enabled,         using XON2 as the XON character and XOFF2 as the         XOFF character.         10b:       Single character in-band transmit flow control enabled,         using XON1 as the XON character and XOFF1 as the         XOFF character.         11b:       The value EFR[3:2] = "11" is reserved for future use and         should not be used
4	Enhanced Mode	RW	Reset to 00b.         0b:       Non-Enhanced mode.         1b:       Enhanced mode. Enables the Enhanced Mode functions. If use addition function except 16550 mode.         Reset to 0b.       Reset to 0b.
5	Special Character Detection Enable	RW	<ul> <li>Ob: Special character detection is disabled.</li> <li>Ob: Special character detection is disabled.</li> <li>Ib: While in Enhanced mode (EFR[4]=1), the UART compares the incoming receiver data with the XOFF1 or XOFF2 value and interrupt will be asserted.</li> <li>If In-Band Flow Control is enabled, this bit must be set to '1'.</li> <li>Reset to 0b.</li> </ul>
6	Automatic RTS Flow Control Enable	RW	<ul> <li>0b: RTS flow control is disabled.</li> <li>1b: RTS flow control is enabled in Enhanced mode (i.e. EFR[4] = 1), where the RTS# pin will be forced inactive high if the RFL reaches the upper flow control threshold. This will be released when the RFL drops below the lower threshold. 650 and 950-mode drivers should use different threshold level.</li> </ul>
			Reset to 0b.

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BIT	FUNCTION	TYPE	DESCRIPTION
7	Automatic CTS	RW	0b: CTS flow control is disabled (default).
	Flow Control		1b: CTS flow control is enabled in Enhanced mode (i.e. EFR[4]
	Enable		= 1), where the data transmission is prevented whenever the CTS# pin is held inactive high. 650 and 950-mode drivers should use different threshold level.
			Reset to 0b.

#### 7.2.14. XON SPECIAL CHARACTER 1 – OFFSET 0Bh

BIT	FUNCTION	TYPE	DESCRIPTION
7:0	XON1	RW	Xon character 1.
			Reset to 00h.

#### 7.2.15. XON SPECIAL CHARACTER 2 – OFFSET 0Ch

BIT	FUNCTION	TYPE	DESCRIPTION
7:0	XON2	RW	Xon character 2.
			Reset to 00h.

#### 7.2.16. XOFF SPECIAL CHARACTER 1 – OFFSET 0Dh

[	BIT	FUNCTION	TYPE	DESCRIPTION
	7:0	XOFF1	RW	Xoff character 1.
				Reset to 00h.

#### 7.2.17. XOFF SPECIAL CHARACTER 2 – OFFSET 0Eh

BIT	FUNCTION	TYPE	DESCRIPTION
7:0	XOFF2	RW	Xoff character 2.
			Reset to 00h.

#### 7.2.18. ADVANCE CONTROL REGISTER – OFFSET 0Fh

BIT	FUNCTION	TYPE	DESCRIPTION
0	Transmitter	RO	Indicates current transmitter terminate condition. If transmitter is
	Terminate		disabled by remote terminate, the condition can be shown by this
	Condition		bit.
			1b: Disabled by remote terminate.
			0b: The transmitter can transmit data normally.
			Reset to 0b.
1	Remote TX Disable	RO	Remote TX Disable.
			<ul><li>1b: If transmitter has sent XOFF message or RTS message, then DTR is inactive, and then it is enabled.</li><li>0b: otherwise</li></ul>
			Reset to 0b.





BIT	FUNCTION	TYPE	DESCRIPTION
2	Xon/Xoff Detect	RO	<ul> <li>When receiving a XON/XOFF character from a remote transmitter, this bit is set to '1'. Otherwise, this bit is set to '0'. The bit is read-clear.</li> <li>If the Xoff/Special Character Interrupt is enabled, the Xoff Detect status is also reflected in the Interrupt Status Register (Priority Level 6).</li> <li>1b: Event true</li> <li>0b: Event false</li> <li>Reset to 0b.</li> </ul>
3	Special Character Detect	RO	When detecting the special characters from a remote transmitter, this bit is set to '1'. Otherwise, this bit is set to '0'. The bit is read-clear. If the Xoff/Special Character Interrupt is enabled, the status is also reflected in the Interrupt Status Register (Priority Level 6). 1b: Event true 0b: Event false Reset to 0b.
7:4	Reserved	RO	Reset to 0000b.

#### 7.2.19. TRANSMIT INTERRUPT TRIGGER LEVEL - OFFSET 10h

BIT	FUNCTION	TYPE	DESCRIPTION
7:0	TTL	RW	Transmitter Interrupt Trigger Level.
			Depart to 00h
			Reset to 00h.

#### 7.2.20. RECEIVE INTERRUPT TRIGGER LEVEL – OFFSET 11h

BIT	FUNCTION	TYPE	DESCRIPTION
7:0	RTL	RW	Receiver Interrupt Trigger Level.
			Reset to 00h.

#### 7.2.21. FLOW CONTROL LOW TRIGGER LEVEL – OFFSET 12h

BIT	FUNCTION	TYPE	DESCRIPTION
7:0	FCL	RW	Automatic Flow Control Low Trigger Level.
			Reset to 00h.

#### 7.2.22. FLOW CONTROL HIGH TRIGGER LEVEL – OFFSET 13h

BIT	FUNCTION	TYPE	DESCRIPTION
7:0	FCH	RW	Automatic Flow Control High Trigger Level.
			Reset to 00h.

#### 7.2.23. CLOCK PRESCALE REGISTER – OFFSET 14h

BIT	FUNCTION	TYPE	DESCRIPTION
3:0	CPRN	RW	N number in calculating the Prescaler, which is used to generate the Baud Rate. Reset to 0000b.

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BIT	FUNCTION	TYPE	DESCRIPTION
7:4	CPRM	RW	M number in calculating the Prescaler, which is used to generate the Baud Rate. It is recommended that the value of the CPRM be set to "0000", "0001" or "0010". Reset to 0000b.

#### 7.2.24. RECEIVE FIFO DATA COUNTER – OFFSET 15h, SFR[6] = 0

The function of this register is selected by the Special Function Register (Offset 07h) bit 6. When SFR[6] is set to '1', this register functions as the Receive FIFO Data Counter. Otherwise, it functions as the Line Status Register Counter.

BIT	FUNCTION	TYPE	DESCRIPTION
7:0	Receive FIFO Data Counter	RO	The Receive FIFO Data Counter indicates the amount of data in the Receive FIFO.
	Counter		ule Receive FIFO.
			Reset to 00h.

#### 7.2.25. LINE STATUS REGISTER COUNTER – OFFSET 15h, SFR[6] = 1

BIT	FUNCTION	TYPE	DESCRIPTION
7:0	Line Status	RO	The Line Status Register Counter indicates the amount of data in
	Register Counter		the LSR.
			Reset to 00h.

#### 7.2.26. TRANSMIT FIFO DATA COUNTER – OFFSET 16h, SFR[7] = 1

The function of this register is selected by the Special Function Register (Offset 07h) bit 7. When SFR[7] is set to '1', this register functions as the Transmit FIFO Data Counter. Otherwise, it functions as the Sample Clock Register.

BIT	FUNCTION	TYPE	DESCRIPTION
7:0	Transmit FIFO Data Counter	RO	The Transmit FIFO Data Counter indicates the amount of data in the Transmit FIFO. Reset to 00h.

#### 7.2.27. SAMPLE CLOCK REGISTER – OFFSET 16h, SFR[7] = 0

BIT	FUNCTION	TYPE	DESCRIPTION					
3:0	Sample Clock	RW	This register determin	This register determines the Sample Clock value (SC) used in				
			the Baud Rate Genera	the Baud Rate Generator. Please refer to 5.2.12 Baud Rate				
			Generation for more of	Generation for more detail				
			0000b: SC = 16	0101b: $SC = 11$	1010b: SC = 6			
			0001b: SC = 15	0110b: $SC = 10$	1011b: SC = 5			
			0010b: SC = 14	0111b: $SC = 9$	1100b: $SC = 4$			
			0011b: SC = 13	1000b: SC = 8	Other settings are			
			0100b: $SC = 12$	1001b: SC = 7	reserved.			
			Reset to 0h.					
7:4	Reserved	RO	Reset to 0h.					





#### 7.2.28. GLOBAL LINE STATUS REGISTER – OFFSET 17h

BIT	FUNCTION	TYPE	DESCRIPTION
0	RX Data Available	RO	0b: No data in the receive FIFO
			1b: Data in the receive FIFO
			Reset to 0b.
1	RX FIFO Overrun	RO	0b: No overrun error
			1b: Overrun error
			Reset to 0b.
2	RX Parity Error	RO	0b: No parity error
			1b: Parity error
			Reset to 0b.
3	RX Frame Error	RO	0b: No framing error
			1b: Framing error
			Reset to 0b.
4	RX Break Error	RO	0b: No break condition
-	KAY BICak Ellor	RO	1b: Break condition
			Reset to 0b.
5	TX Empty	RO	0b: Tx Holding Register is not empty.
			1b: Tx Holding Register is empty.
	TTY OLIV	20	Reset to 0b.
6	TX Complete	RO	0b: Tx Shift Register is not empty.
			1b: Tx Shift Register is empty.
			Reset to 0b.
7	RX Data Error	RO	0b: No Rx FIFO error
		-	1b: Rx FIFO error
			Reset to 0b.

#### 7.2.29. RECEIVE FIFO DATA REGISTERS – OFFSET 100h ~ 17Fh

BIT	FUNCTION	TYPE	DESCRIPTION
7:0	Receive FIFO Data	RO	This register is used to map RX FIFO data content.
			Reset to 00h.

#### 7.2.30. TRANSMIT FIFO DATA REGISTERS – OFFSET 100h ~ 17Fh

BIT	FUNCTION	TYPE	DESCRIPTION
7:0	Transmit FIFO	WO	This register is used to map TX FIFO to memory space.
	Data		
			Reset to 00h.

#### 7.2.31. LINE STATUS FIFO REGISTERS –OFFSET 180h ~ 1FFh

BIT	FUNCTION	TYPE	DESCRIPTION
7:0	Line Status FIFO	RO	This register is used to map FIFO data relative LSR content.
			Reset to 00h.





### 8. EEPROM INTERFACE

The EEPROM interface consists of five pins: SR\_DI (EEPROM data input), SR\_DO (EEPROM data output), SR\_CS (EEPROM chip select), SR\_CLK\_O (EEPROM clock output), and SR\_ORG (EEPROM organization). The device may control a 93C56 or compatible parts using 2K bits. The EEPROM is used to initialize a number of registers before enumeration. This is accomplished at start-up when RTS[0] is de-asserted, at which time the data from the EEPROM is loaded. The EEPROM interface is organized into a 16-bit base, and the device supplies a 7-bit EEPROM word address.

### 8.1. AUTO MODE EERPOM ACCESS

The device may access the EEPROM in a WORD or BYTE format, which is decided by the SR\_ORG# at start-up. If SR\_ORG# is asserted at start-up, EEPROM is accessed using the WORD format. Otherwise, Byte format is used.

### 8.2. EEPROM MODE AT RESET

During a reset, the device will automatically load the information/data from the EEPROM if the automatic load condition is met. The first offset in the EEPROM contains a signature. If the signature is recognized, and if RTS[0] is de-asserted, the autoload initiates right after the reset.

EEPROM ADDRESS	PCIE REGISTER OFFSET	DEFAULT Value	DESCRIPTION
00h		A868h	Check Code
02h	Offset 00h bit[15:0]	12D8h	Vendor ID
04h	Offset 00h bit[31:16]	7952h	Device ID
06h	Offset 2Ch bit[15:0]	0000h	Subsytem Vendor ID
08h	Offset 2Ch bit[31:16]	0000h	Subsytem ID
0Ah	Bit[0] - Offset 80h bit[21]	0b	Device Specific Initialization: When set, the DSI is
			required.
	Bit[3:1] - Offset 80h bit[24:22]	111b	Aux. Current: When set, the I/O bridge needs 375
			mA in D3 state.
	Bit[4] - Offset 80h bit[25]	1b	<b>D1 Support:</b> When set, this bridge supports D1
			Power Management state.
	Bit[5] - Offset 80h bit[26]	1b	<b>D2 Support:</b> When set, this bridge supports D2
			Power Management state.
	Bit[10:6] - Offset 80h bit[31:27]	01000b	<b>PME Support:</b> When set, the PME supports D1 and
			D2 Power Management states.
	Bit[11] - Offset 84h bit[3]	1b	No Soft Reset: When set, the device does not
			trigger the Internal Reset Command during the
			transition from D3hot to D0 power state.
	Bit[13:12] - Offset A8h bit[14:13]	00b	XPIP CSR0
0Ch	Offset B0h bit[15:0]	0000h	Replay Time-out Counter
0Eh	Offset B0h bit [31:16]	0000h	Acknowledge Latency Timer
10h	Bit[1:0] - Offset ECh bit[11:10]	11b	ASPM Capability Support: When set, this bridge
			supports L0s and L1 entry
	Bit[4:2] - Offset ECh bit[14:12]	011b	Exit L0s Latency Timer
	Bit[7:5] - Offset ECh bit[17:15]	000b	Exit L1 Latency Timer
12h	Offset B4h bit[15:0]	0000h	UART Transmitter Drive Enable:
			RS232/422/485-2W/485-4W Selection for UART 0
			to 3

### 8.3. EEPROM SPACE ADDRESS MAP AND DESCRIPTION





EEPROM ADDRESS	PCIE REGISTER OFFSET	DEFAULT Value	DESCRIPTION
14h	Offset B4h bit[31:16]	0000h	UART Transmitter Drive Enable:
			RS232/422/485-2W/485-4W Selection for UART 4
			to 7
16h	Bit[1:0] - Offset B8h bit[17:16]	01b	PM Control Parameter: Determines whether this
			bridge enters L1 or not when D3 condition occurs.
	Bit[3:2] - Offset B8h bit[19:18]	00b	PM Control Parameter: Determines the delay
			counter value when entering L1
	Bit[5:4] - Offset B8h bit[21:20]	00b	PM Control Parameter: Determines whether this
			bridge asserts L0s/L1 handshake protocol
18h	Bit[13:0] - Offset C8h bit[13:0]	0200h	PHY Parameter
1Ah	Bit[0] - Offset C4h bit[15]	1b	Role Based Error Report Enable: Indicates
			implement the role-base error reporting
	Bit[15:8] - Offset 34h bit[7:0]	80h	Capability List Pointer: Points to a linked list of
			new capabilities implemented by the device
1Ch	[7:0] - Offset 08h bit[7:0]	00h	Revision ID: Indicates revision number of device
40h		12D8h	Check Code

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## 9. ELECTRICAL SPECIFICATION

### 9.1. ABSOLUTE MAXIMUM RATINGS

#### **Table 9-1 Absolute Maximum Ratings**

(Above which the useful life may be impaired. For user guidelines, not tested.)

-65°C to 150°C
-0.3v to 2.1v
-0.3v to 3.8v
-0.3v to 2.1v

Note:

Stresses greater than those listed under MAXIMUM RATINGS may cause permanent damage to the device. This is a stress rating only and functional operation of the device at these or any conditions above those indicated in the operational sections of this specification is not implied. Exposure to absolute maximum rating conditions for extended periods of time may affect reliability.

### 9.2. DC SPECIFICATIONS

#### Table 9-2 DC Electrical Characteristics

Symbol	Min.	Тур.	Max.	
VDDA	1.6v	1.8v	2.0v	
VDDC	1.6v	1.8v	2.0v	
VDDCAUX	1.6v	1.8v	2.0v	
VTT	1.6v	1.8v	2.0v	
VDDR	3.0v	3.3v	3.6v	
VIL			0.8v	
VIH	2.0v			
VOL			0.4v	
VOH	2.6v			

VDDA: analog power supply for PCI Express Interface VDDC: digital power supply for the core VTT: termination power supply for PCI Express Interface VDDCAUX: auxiliary power supply VDDR: digital power supply for the I/O VIH: I/O input high voltage VIL: I/O input low voltage VOL: I/O output low voltage VOH: I/O output High voltage

The typical power consumption of PI7C9X7952 is about 0.7 watt.

### 9.3. AC SPECIFICATIONS

#### Table 9-3 Transmitter Characteristics

Symbol	Description	Min	Typical	Max.	Unit			
Voltage Param	eters							
V <sub>TX-DIFF</sub> <sup>a</sup>	Output voltage compliance @ typical swin	Output voltage compliance @ typical swing						
	V <sub>TX-DIFFp</sub> (peak-to-peak, single ended)	400	500	600	mV			
	V <sub>TX-DIFFpp</sub> (peak-to-peak, differential)	800	1000	1200	mV			
V <sub>SW</sub>	Supported TX output voltage range (pp,	700 <sup>b</sup>		1400 <sup>c</sup>	mV			
	differential)							





Symbol	Description	Min	Typical	Max.	Unit
V <sub>OL</sub>	Low-level output voltage		V <sub>TT</sub> - 1.5 *V <sub>TX-DIFFp</sub>		V
V <sub>OH</sub>	High-level output voltage		V <sub>TT</sub> - 0.5V <sub>TX-DIFFp</sub>		V
V <sub>TX-CM-AC</sub>	Transmit common-mode voltage in L0	0.50	V <sub>TT</sub> - V <sub>TX-DIFFp</sub>	1.45	V
V <sub>TX-CM-HiZ</sub>	Transmit common-mode voltage in L0s (TX) & L1		V <sub>TX-CM-AC</sub>		V
V <sub>TX-DE-RATIO</sub>	De-emphasized differential output voltage	0		-7.96	dB
V <sub>TX-IDLE-DIFFp</sub>	Electric Idle differential peak voltage			20	mV
V <sub>TX-RCV-DETECT</sub>	Voltage change during Receive Detection		V <sub>TX-DIFFp</sub>		mV
RL <sub>TX-DIFF</sub>	Transmitter Differential Return loss	10			dB
RL <sub>TX-CM</sub>	Transmitter Common Mode Return loss	6			dB
Zose	Single-ended output impedance	40	50	60	Ω
Z <sub>TX-DIFF-DC</sub>	DC Differential TX Impedance	80	100	120	Ω
T <sub>TX-RISE, TTX-FALL</sub>	Rise / Fall time of TxP, TxN outputs	80		110 <sup>d</sup>	ps
Jitter Parameters	• • • • • •				
UI	Unit Interval	399.88	400	400.12	ps
T <sub>TX-MAX-JITTER</sub>	Transmitter total jitter (peak-to-peak)			0.30 <sup>e</sup>	ÛI
T <sub>TX-EYE</sub>	Minimum TX Eye Width (1 - T <sub>TX-MAX-JITTER</sub> )	0.70			UI
T <sub>TX-EYE-MEDIAN-to-</sub> MAX-JITTER	Maximum time between the jitter median and maximum deviation from the median			0.15	UI
Timing Paramete	rs				
L <sub>TLAT-10</sub>	Transmitter data latency (for n=10)	9		11	UI
L <sub>TLAT-20</sub>	Transmitter data latency (for n=20)	9		11	UI
L <sub>TX-SKEW</sub>	Transmitter data skew between any 2 lanes	0		2 + 200ps	UI
T <sub>TX-IDLE-SET-TO-IDLE</sub>	Maximum time to transition to a valid electrical idle after sending an Electrical Idle ordered set			8	ns
T <sub>EIExit</sub>	Time to exit Electrical Idle (L0s) state into L0		12	16	ns
T <sub>BTEn</sub>	Time from asserting BeaconTxEn to beacon being transmitted on the lane		30	80	ns

a. Measured with Vtt = 1.2V, HiDrv='0',LowDrv='0' and Dtx='0000'.

b. Minimum swing assumes LoDrv = 1, HiDrv = 0 and Dtx = 1100

c. Max swing assumes LoDrv = 0, HiDrv = 1, Dtx = 0010, VTT = 1.8V

d. As measured between 20% and 80% points. Will depend on package characteristics.

e. Measured using PCI Express Compliance Pattern

#### Table 9-4 Receiver Characteristics

Symbol	Description	Min	Typical	Max.	Unit
Voltage Parameters					
V <sub>RX-DIFFp-p</sub>	Differential input voltage	170		1200	mV
	(peak-to-peak)				
V <sub>RX-IDLE-DET-DIFFp-p</sub>	Differential input threshold voltage	65		175	mV
	(peak-to-peak) to assert				
	TxIdleDetect output				
V <sub>RX-CM-AC</sub>	Receiver common-mode voltage for		0	150	mV
	AC-coupling				
T <sub>RX-RISE, TRX-FALL</sub>	Rise time / Fall time of RxP, RxN			160	Ps
	inputs				
Z <sub>RX-DIFF-DC</sub>	Differential input impedance (DC)	80	100	120	Ω
Z <sub>RX-COM-DC</sub>	Single-ended input impedance	40	50	60	Ω
Z <sub>RX-COM-INITIAL-DC</sub>	Initial input common mode	5	50	60	Ω
	impedance (DC)				
Z <sub>RX</sub> -COM-HIGH-IMP-DC	Powered down input common mode	200k			Ω
	impedance (DC)				
RL <sub>RX-DIFF</sub>	Receiver Differential Return Loss <sup>a</sup>	10			dB
RL <sub>RX-CM</sub>	Receiver Common Mode Return	6			dB
	Loss <sup>b</sup>				



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Symbol	Description	Min	Typical	Max.	Unit
Jitter Parameters	·	•		•	
T <sub>RX-MAX-JITTER</sub>	Receiver total jitter tolerance			0.65	UI
T <sub>RX-EYE</sub>	Minimum Receiver Eye Width	0.35			UI
$T_{\text{RX-EYE-MEDIAN-to-MAX-JITTER}}$	Maximum time between jitter median and max deviation from median			0.325	UI
Timing Parameters	·				
LRLAT-10	Receiver data latency for n=10	28		29	bits
LRLAT-20	Receiver data latency for n=20	49		60	bits
TRX-SKEW	Receiver data skew between any 2 lanes	0		1°	bits
TBDDly	Beacon-Activity on channel to detection of Beacon <sup>d</sup>			200	us
TRX-IDLE_ENTER	Delay from detection of Electrical Idle condition on the channel to assertion of TxIdleDetect output		10	20	ns
TRX-IDLE_EXIT	Delay from detection of L0s to L0 transition to deassertion of TxIdleDetect output		5	10	ns

a. Over a frequency range of 50 MHz to 1.25 GHz. b. Over a frequency range of 50 MHz to 1.25 GHz.

c. Assuming synchronized bit streams at the respective receiver inputs.

d. This is a function of beacon frequency





### **10. CLOCK SCHEME**

The PI7C9X7952 requires 100MHz differential clock inputs through CLKINP and CLKINN Pins as shown in the following table.

#### **Table 10-1 Input Clock Requirements**

Symbol	Description		Min	Typical	Max.	Unit
ClkIn <sub>FREQ</sub>	Reference input clock range		-	100	-	MHz
ClkIn <sub>DC</sub>	Duty cycle of input clock		40	50	60	%
$T_R, T_F$	Rise/Fall time of input clock		-	-	0.2	<b>RCUI</b> <sup>a</sup>
V <sub>SW</sub>	Differential input voltage swing	(zero-to-peak)	0.4		0.8	V

a. RCUI (Reference Clock Unit Interval) refers to the reference clock period



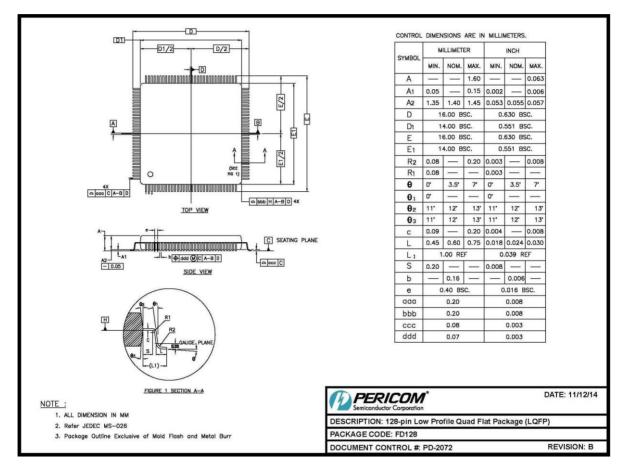
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## **11. PACKAGE INFORMATION**

The package of PI7C9X7952 is a 14mm x 14mm LQFP (128 Pin) package. The following are the package information and mechanical dimension:

#### Figure 11-1 Package Outline Drawing





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### **12. Order Information**

Part Number	Temperature Range	Package	Pb-Free & Green
PI7C9X7952 FDEX	-40°C to 85°C	128-pin LQFP	Yes
	(Industrial Temperature)	14mm x 14mm	

