

AR0237_iBGA80_Demo3Head

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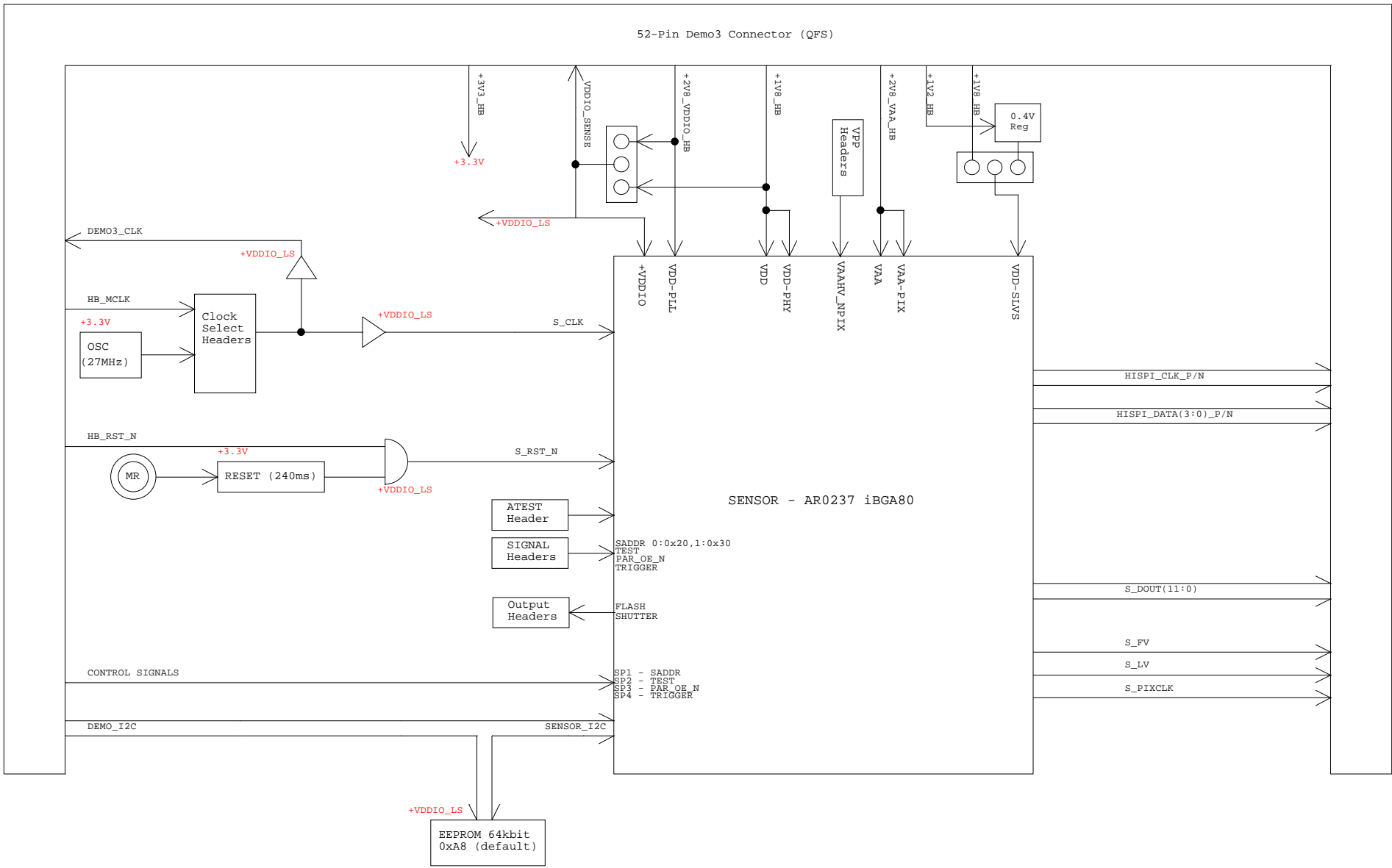
| Rev | Who | Date | Description |
|---------|--------|----------|---|
| Rev 0.0 | aralex | 06/10/15 | Initial schematic taken from AR0230 IBGA 80 demo3 HB design because the pinout is the same. Changed P3 from 2 pin header to 3 pin header Added R50, P30; Deleted R8 |
| | | 06/12/15 | Updated with the new Sensor part for AR0237 |



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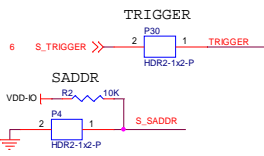
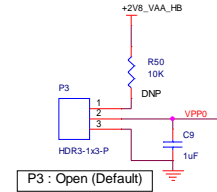
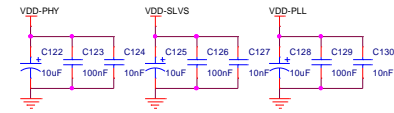
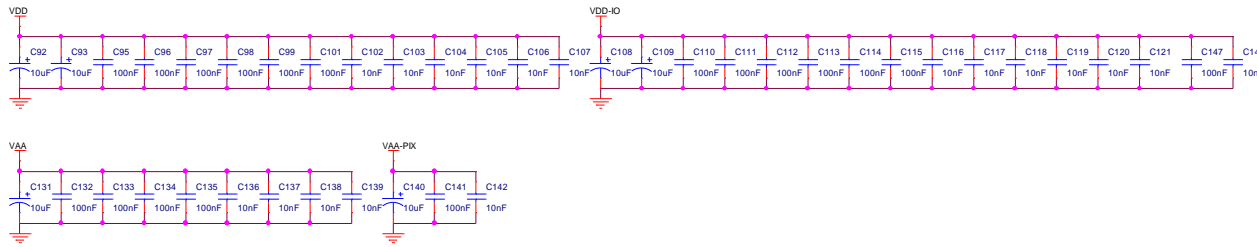
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| Title | | |
| TITLE PAGE | | |
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Block Diagram

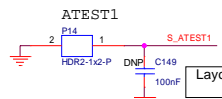
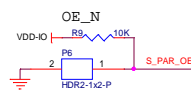
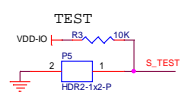


Sensor

| | |
|-----------|-------|
| +5V0 | 4 |
| +3V3 | 4,5 |
| +VDDIO_LS | 4,5,6 |
| VDD | 4 |
| VDD-ID | 4 |
| VDD-PHY | 4 |
| VDD-SLVS | 4 |
| VDD-PLL | 4 |
| VAA | 4 |
| VAA-PIX | 4 |

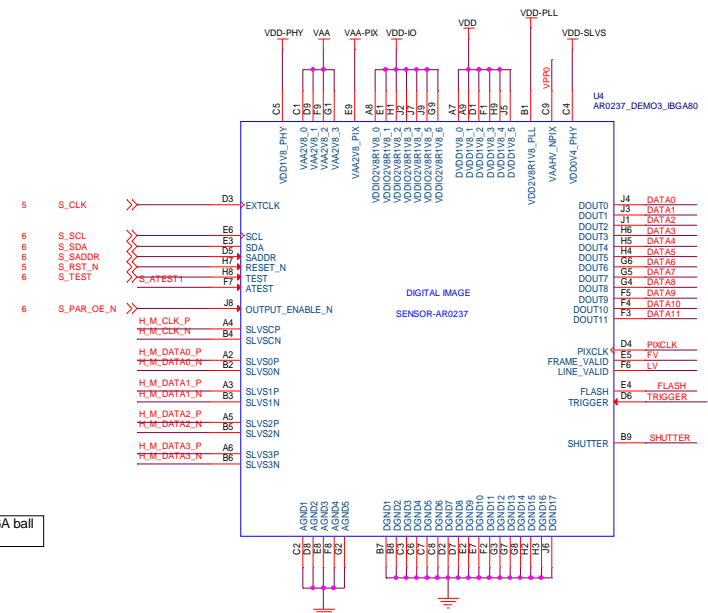
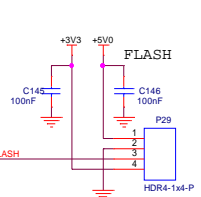


Jumper P4:
 SHORT : SADDR= 0x20
 OPEN : SADDR= 0x30

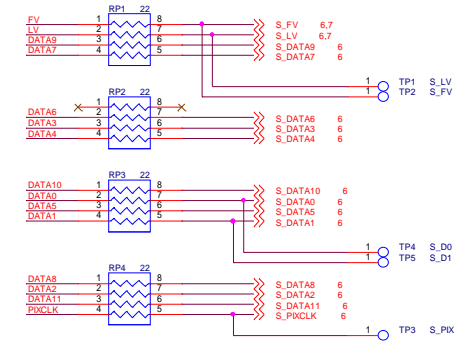
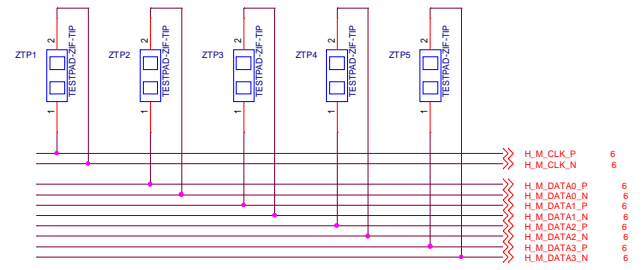


Layout Note: Place capacitor close to BGA ball of ATEST1 pin

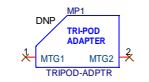
Default Jumper Settings
 P5 : SHORT (S_TEST->GND)
 P6 : SHORT (Parallel mode Default)
 P14: SHORT (ATEST1->GND)



(Note for layout: - Place these testpads near the Demo3 I/F connector at the top side of PCB)



TRIPOD MOUNT



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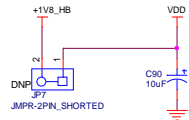
SENSOR

| | | |
|-------|------------------------|--------------|
| File | SENSOR | |
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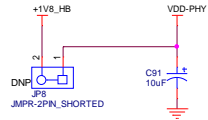
Debug Headers: Cut away the shorted trace and mount header for power debugging

Power

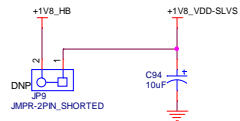
VDD 1.8V SUPPLY



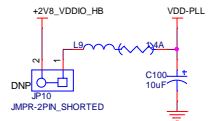
VDD-PHY 1.8V SUPPLY



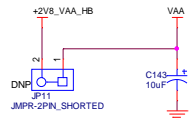
VDD-SLVS 1.8V SUPPLY



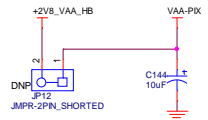
VDD-PLL 2.8V SUPPLY



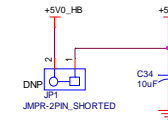
VAA 2.8V SUPPLY



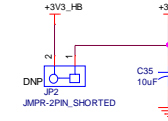
VAA-PIX 2.8V SUPPLY



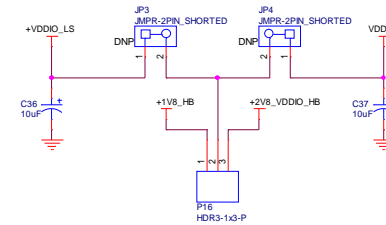
PERIPHERAL 5V SUPPLY



PERIPHERAL 3.3V SUPPLY

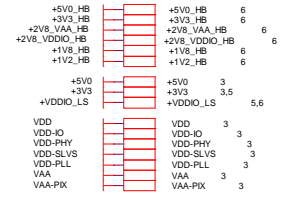
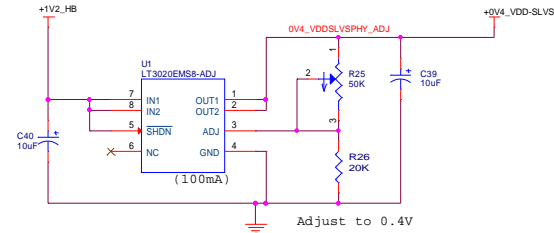


VDDIO & VDDIO_LS 1.8V/2.8V SUPPLY

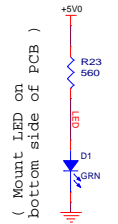


P16 Default Setting: 1-2 Short (1V8 operation)

VDD_SLVS 0.4V SUPPLY



5V LED



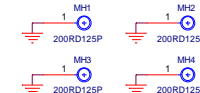
Fiducials




Ground Testpoints



Mounting Holes





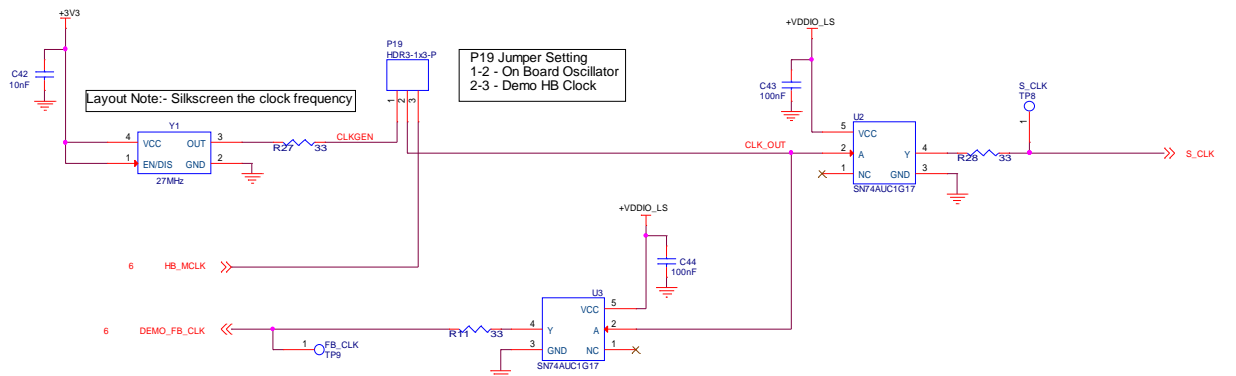
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| | |
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| POWER | |
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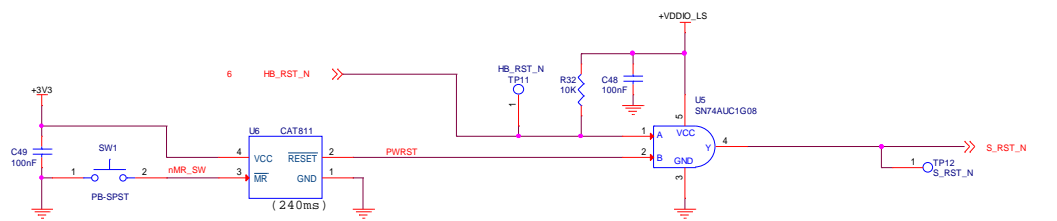
Clock and Reset

+5V0 3.4
 +3V3 3.4
 +VDDIO_LS 4.6

CLOCK CIRCUIT



RESET CIRCUIT



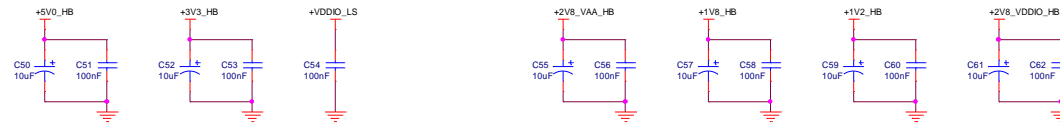
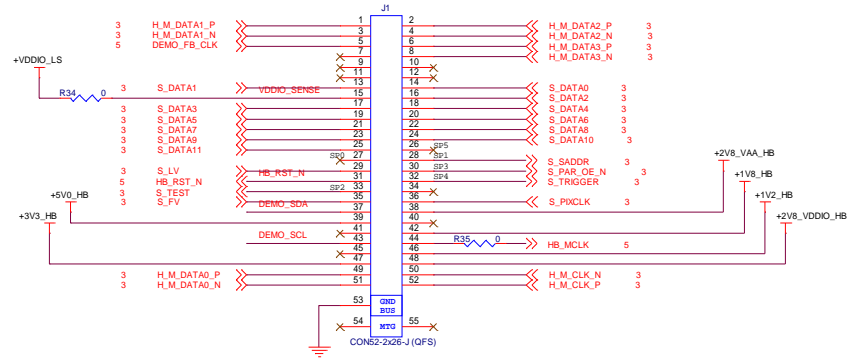
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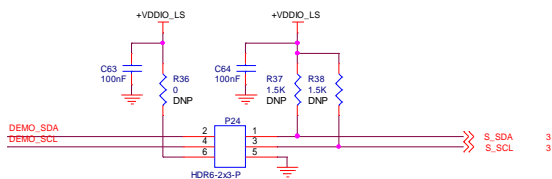
External Interface

| | | | |
|---------------|-------|---------------|-------|
| +5V0_HB | 4 | +5V0_HB | 4 |
| +3V3_HB | 4 | +3V3_HB | 4 |
| +2V8_VAA_HB | 4 | +2V8_VAA_HB | 4 |
| +2V8_VDDIO_HB | 4 | +2V8_VDDIO_HB | 4 |
| +1V8_HB | 4 | +1V8_HB | 4 |
| +1V2_HB | 4 | +1V2_HB | 4 |
| +3V3 | 3,4,5 | +3V3 | 3,4,5 |
| +VDDIO_LS | 4,5 | +VDDIO_LS | 4,5 |

DEMO3 BASEBOARD I/F

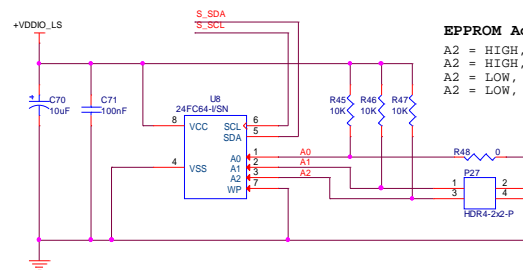


I2C DEBUG



P24 Default Setting:
 1-2 : Short : Demo and Sensor SDA connected
 3-4 : Short : Demo and Sensor SCL connected

LENS CORRECTION EEPROM



EEPROM Address Switch Settings:

A2 = HIGH, A1 = LOW, A0 = LOW; Address => 0xA8 (default)
 A2 = HIGH, A1 = HIGH, A0 = LOW; Address => 0xA9
 A2 = LOW, A1 = HIGH, A0 = LOW; Address => 0xA4
 A2 = LOW, A1 = LOW, A0 = LOW; Address => 0xA0

P27 Default Jumper Setting:
 1-2 : Short => Ground/Low
 3-4 : Open => Pull-up/High



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| EXTERNAL INTERFACE | |
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