

Ultra low power Bluetooth LE system-on-chip solution

Rev. 2.7 — 21 November 2018

Product data sheet

1. Introduction

QN902x is an ultra low power, wireless System-on-Chip (SoC) for Bluetooth Smart applications. It supports both master and slave modes. QN902x integrates a high performance 2.4 GHz RF transceiver with a 32-bit ARM Cortex-M0 MCU, flash memory, and analog and digital peripherals.

By integrating a Bluetooth LE v4.2 compliant radio, link controller and host stack, QN902x provides a single-chip solution for Bluetooth Smart applications. The 32-bit ARM Cortex-M0 MCU and on-chip memory provides additional signal processing and room to run applications for a true single-chip Bluetooth Smart solution. In addition, QN902x can be used as a network processor by connecting to an application processor via UART or SPI. It helps to add Bluetooth Smart feature to any product.

QN902x has built-in analog and digital interfaces. It enables easy connection to any analog or digital peripheral, sensor, and external application processor in network processor mode.

2. General description

QN902x is an ultra low power, high performance and highly integrated Bluetooth LE solution. It is used in Bluetooth Smart applications such as sports and fitness, human interface devices, and app-enabled smart accessories. It is specially designed for wearable electronics and can run on a small capacity battery such as a coin cell battery.

QN902x integrates a Bluetooth LE radio, controller, protocol stack and profile software on a single chip, providing a flexible and easy to use Bluetooth LE SoC solution. It also has a high performance MCU and an on-chip memory that can support users to develop a single-chip wireless MCU solution. Users can also utilize QN902x as a network processor by connecting to an application processor for more advanced applications.

Additional system features include fully integrated DC-to-DC converter and LDO, low-power sleep timer, battery monitor, general-purpose ADC, and GPIOs. These features reduce overall system cost and size. QN902x has very low power consumption in all modes. It enables long life in battery-operated systems while maintaining excellent RF performance. QN9020/1 operates with a power supply range of 2.4 V to 3.6 V. The QN9022 operates with a power supply range of 1.8 V to 3.6 V.

3. Features and benefits

- True single-chip Bluetooth LE SoC solution
 - Integrated Bluetooth LE radio
 - Complete Bluetooth LE protocol stack and application profiles



)N907x

- Supports both master and slave modes
- Supports secure connections
- Up to eight simultaneous links in master mode
- Frequency bands: 2400 MHz to 2483.5 MHz
- 1 Mbit/s on air data rate and 250 kHz deviation
- GFSK modulation format
- RF
 - –95 dBm RX sensitivity (non-DC-to-DC mode)
 - –93 dBm RX sensitivity (DC-to-DC mode)
 - TX output power from –20 dBm to +4 dBm
 - Fast and reliable RSSI and channel quality indication
 - Compatible with worldwide radio frequency regulations
 - Excellent link budget up to 99 dB
- Very low power consumption
 - Single power supply of 2.4 V to 3.6 V for QN9020/1
 - Single power supply of 1.8 V to 3.6 V for QN9022
 - Integrated DC-to-DC converter and LDO
 - 4 2 μA deep sleep mode
 - 3 μA sleep mode (32 kHz RC oscillator on)
 - 9.25 mA RX current with DC-to-DC converter
 - 8.8 mA TX current @0 dBm TX power with DC-to-DC converter
- Compact 6 mm × 6 mm HVQFN48 package for QN9020, 5 mm × 5 mm HVQFN32 package for QN9021, and 5 mm × 5 mm HVQFN40 package for QN9022
- Microcontroller
 - Integrated 32-bit ARM Cortex-M0 MCU
 - ◆ 64 kB system memory
 - 96 kB ROM
 - ◆ 128 kB on-chip flash memory with 4 kB page size for QN9020 and QN9021
 - User-controllable code protection
- High-level integration
 - ◆ 4-channel, 10-bit general-purpose ADC
 - Two general-purpose analog comparators
 - 31 GPIO pins for QN9020, 15 GPIO pins for QN9021, and 22 GPIO pins for QN9022
 - GPIO pins can be used as interrupt sources
 - Four general-purpose timers
 - ♦ 32 kHz sleep timer
 - Watchdog timer
 - Real-time clock with calibration
 - 2-channel programmable PWM
 - Two SPI/UART interfaces
 - ◆ I²C-bus master/slave interface
 - Brownout detector
 - Battery monitor
 - AES-128 security coprocessor

- 16 MHz or 32 MHz crystal oscillator
- Low power 32 kHz RC oscillator
- ◆ 32.768 kHz crystal oscillator

4. Applications

- Sports and fitness
- Healthcare and medical
- Remote control
- Smartphone accessories
- PC peripherals (mouse and keyboard)
- Wireless sensor networks

5. Profiles and services

QN902x offers a complete list of qualified profiles and services.

Table 1. Supported profiles and services

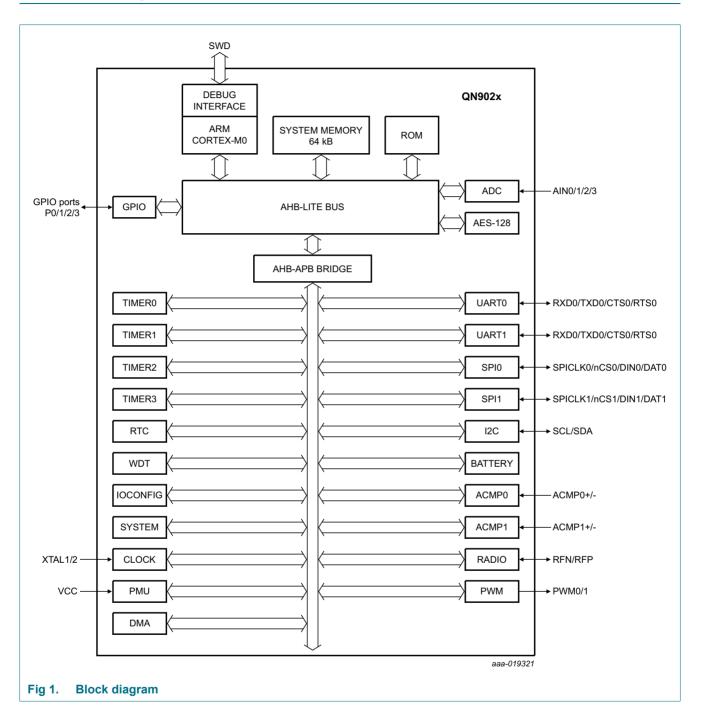
| Profiles and services | Version |
|-----------------------------------|---------|
| Device information service | 1.1 |
| Battery service | 1.0 |
| Blood pressure profile | 1.0 |
| Find me profile | 1.0 |
| Glucose profile | 1.0 |
| Heart rate profile | 1.0 |
| Health thermometer profile | 1.0 |
| HID over GATT profile | 1.0 |
| Proximity profile | 1.0 |
| Scan parameters profile | 1.0 |
| Time profile | 1.0 |
| Alert notification profile | 1.0 |
| Phone alert status profile | 1.0 |
| Cycling speed and cadence profile | 1.0 |
| Running speed and cadence profile | 1.0 |

6. Ordering information

Table 2. Ordering information

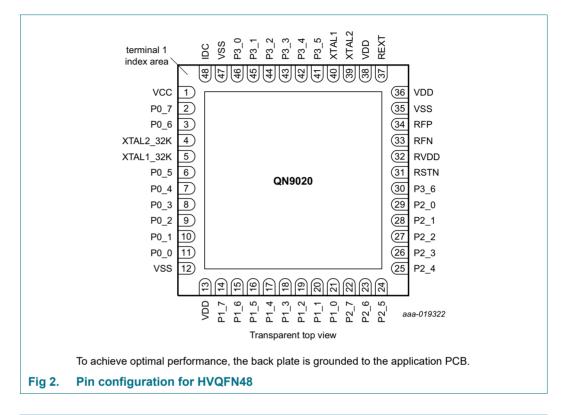
| Type number | Package | | | | | | | | |
|-------------|---------|---|-----------|--|--|--|--|--|--|
| | Name | Description | Version | | | | | | |
| QN9020 | HVQFN48 | plastic thermal enhanced very thin quad flat package; no leads; 48 terminals; body $6\times6\times0.85~\text{mm}$ | SOT778-4 | | | | | | |
| QN9021 | HVQFN32 | plastic thermal enhanced very thin quad flat package; no leads; 32 terminals; body $5\times5\times0.85~\text{mm}$ | SOT617-13 | | | | | | |
| QN9022 | HVQFN40 | plastic thermal enhanced very thin quad flat package; no leads; 40 terminals; body 5 \times 5 \times 0.85 mm | SOT1369-2 | | | | | | |

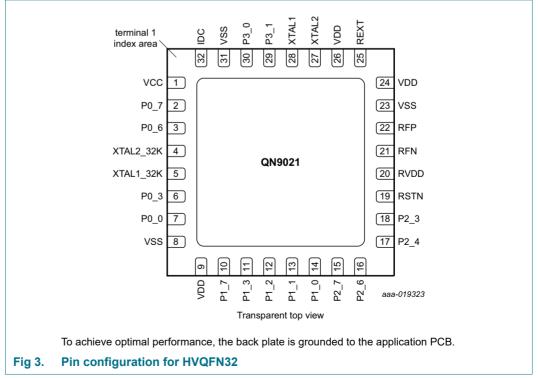
7. Block diagram



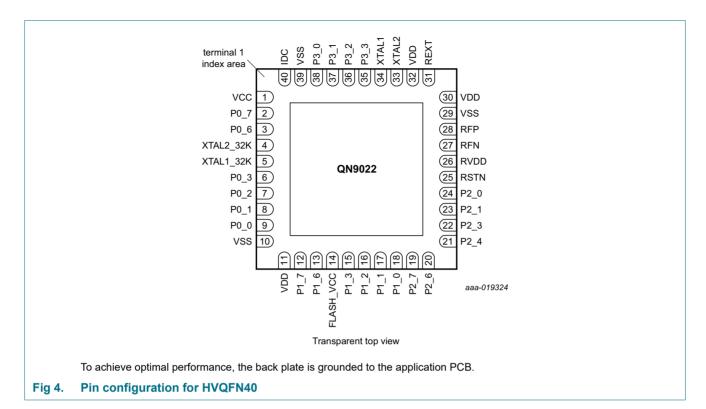
8. Pinning information

8.1 Pinning





Product data sheet



8.2 Pin description

Table 3. Pin description

I = *Input;* O = *Output; I*/O = *Input/Output;* AI = Analog *Input.*

| Symbol | Pin | | | | Туре | Description |
|-----------|-----------|--------|--------|----------|------------------------------------|---|
| | QN9020 | QN9021 | QN9022 | function | | |
| VCC | 1 | 1 | 1 | - | - | supply voltage |
| P0_7 | 2 | 2 | 2 | SWCLK | I | default to SWCLK (input with pull-up) |
| | | | | P0_7 | I/O | GPIO7 |
| | | | | AIN3 | AI | ADC input channel 3 |
| | | | ACMP1- | AI | analog comparator 1 negative input | |
| P0_6 | 0_6 3 3 3 | | 3 | SWDIO | I/O | default to SWDIO (input with pull-up) |
| | | | | P0_6 | I/O | GPIO6 |
| | | | | AIN2 | AI | ADC input channel 2 |
| | | | | ACMP1+ | AI | analog comparator 1 positive input |
| XTAL2_32K | 4 | 4 | 4 | - | - | connected to 32.768 kHz crystal or external 32 kHz clock; if RC oscillator is used, this pin is not connected |
| XTAL1_32K | 5 | 5 | 5 | - | - | connected to 32.768 kHz crystal; if RC oscillator is used, this pin is not connected |
| P0_5 | _5 6 | | - | P0_5 | I/O | GPIO5 |
| | | | | SCL | I/O | I ² C-bus clock |
| | | ADCT I | | I | ADC conversion external trigger | |
| | | | | ACMP1_O | 0 | analog comparator 1 output |

Table 3. Pin description ...continued

| Symbol | Pin | | | Alternate | Туре | Description | | |
|-----------|----------|--------|--------|-----------|--|--|--|--|
| | QN9020 | QN9021 | QN9022 | function | | | | |
| P0_4 | 7 | - | - | P0_4 | I/O | GPIO4 | | |
| | | | | CLKOUT1 | 0 | clock output 1 | | |
| | | | | RTCI | I | RTC input capture | | |
| P0_3 | 8 | 6 | 6 | P0_3 | I/O | GPIO3 | | |
| | | | | CLKOUT0 | 0 | clock output 0 | | |
| | | | | T0_ECLK | CLK I/O timer 0 external clock input or PWM output I/O GPIO2 | | | |
| P0_2 | _2 9 - 7 | | 7 | P0_2 | I/O | GPIO2 | | |
| | | | | SDA | I/O | I ² C-bus data transmit | | |
| | | | | SPICLK0 | I/O | SPI0 clock | | |
| | | | | RTS0 | 0 | UART0 RTS | | |
| P0_1 | 10 | - | 8 | P0_1 | I/O | GPIO1 | | |
| | | | | nCS0_0 | I/O | SPI0 slave select for master/slave mode | | |
| | | | | CTS0 | I | UART0 CTS | | |
| P0_0 | 11 | 7 | 9 | P0_0 | I/O | GPIO0 | | |
| | | | | TXD0 | 0 | UART0 TX data output with pull-up | | |
| | | | | DAT0 | I/O | in 4-wire mode, SPI0 output data; in 3-wire mode, data I/O | | |
| | | | | RTCI | I | RTC input capture | | |
| VSS | 12 | 8 | 10 | - | - | ground | | |
| VDD | 13 | 9 | 11 | - | - | supply voltage | | |
| P1_7 | 14 | 10 | 12 | P1_7 | I/O | GPIO15 | | |
| | | | | RXD0 | I | UART0 RX data input | | |
| | | | | DIN0 | I | SPI0 input data in 4-wire mode; invalid in 3-wire mode | | |
| | | | | T0_0 | 0 | timer 0 PWM output | | |
| P1_6 | 15 | - | 13 | P1_6 | I/O | GPIO14 | | |
| | | | | nCS0_1 | 0 | SPI0 slave select output for master mode | | |
| | | | | PWM0 | 0 | PWM0 output | | |
| | | | | T0_3 | I/O | timer 0 input capture/clock or PWM output | | |
| FLASH_VCC | - | - | 14 | - | - | power output for flash ^[1] | | |
| P1_5 | 16 | - | - | P1_5 | I/O | GPIO13 | | |
| | | | | PWM1 | 0 | PWM1 output | | |
| | | | | T1_2 | I/O | timer 1 input capture/clock or PWM output | | |
| P1_4 | 17 | - | - | P1_4 | I/O | GPIO12 | | |
| | | | | T1_3 | I/O | timer 1 input capture/clock or PWM output | | |
| P1_3 | 18 | 11 | 15 | P1_3 | I/O | GPIO11 | | |
| | | | | SPICLK1 | I/O | SPI1 clock | | |
| | | | | RTS1 | 0 | UART1 RTS | | |
| | | | | CLKOUT1 | 0 | clock output 1 | | |

Table 3.Pin description ...continued

I = Input; O = Output; I/O = Input/Output; AI = Analog Input.

| Symbol | Pin | | | Alternate | Туре | Description |
|--------|----------|--------|--------|-----------|--------|---|
| | QN9020 | QN9021 | QN9022 | function | | |
| P1_2 | 19 | 12 | 16 | P1_2 | I/O | GPIO10 |
| | | | | nCS1_0 | I/O | SPI1 slave select for master/slave mode |
| | | | | CTS1 | I | UART1 CTS |
| | 1 20 13 | | | ADCT | AI | ADC conversion external trigger |
| P1_1 | 20 | 13 | 17 | P1_1 | I/O | GPIO9 |
| | | | | DAT1 | I/O | in 4-wire mode, SPI1 output data; in 3-wire mode, data I/O |
| | | | | TXD1 | 0 | UART1 TX data |
| | | | | T1_0 | I/O | timer 1 input capture/clock or PWM output |
| P1_0 | 21 | 14 18 | | P1_0 | I/O | GPIO8 |
| | | | | DIN1 | I | SPI1 input data in 4-wire mode; invalid in 3-wire mode |
| | | | | RXD1 | I | UART1 RX data |
| | | | | T2_ECLK | I/O | timer 2 external clock input or PWM output |
| P2_7 | 22 15 | 19 | P2_7 | I/O | GPIO23 | |
| | | | | ACMP1_O | 0 | analog comparator 1 output |
| | | | | PWM0 | 0 | PWM0 output |
| | | | | T1_ECLK | I/O | timer 1 external clock input or PWM output |
| P2_6 | _6 23 16 | 16 | 16 20 | P2_6 | I/O | GPIO22, pull up to bypass ISP mode and enable fast boot function during boot process. |
| | | | | PWM1 | 0 | PWM1 output |
| | | | | T2_0 | I/O | timer 2 input capture/clock or PWM output |
| P2_5 | 24 | - | | P2_5 | I/O | GPIO21 |
| | | | | nCS1_1 | 0 | SPI1 slave select output for master mode |
| | | | | T2_2 | I/O | timer 2 input capture/clock or PWM output |
| P2_4 | 25 | 17 | 21 | P2_4 | I/O | GPIO20 |
| | | | | SCL | I/O | I ² C-bus master clock output with pull-up |
| | | | | PWM1 | 0 | PWM1 output |
| | | | | T3_ECLK | I/O | timer 3 external clock input or PWM output |
| P2_3 | 26 | 18 | 22 | P2_3 | I/O | GPIO19 |
| | | | | SDA | I/O | I ² C-bus data transmit |
| | | | | ACMP0_O | 0 | analog comparator 0 output |
| | | | | T3_0 | I/O | timer 3 input capture/clock or PWM output |
| P2_2 | 27 | - | - | P2_2 | I/O | GPIO18 |
| | | | | SPICLK1 | I/O | SPI1 clock |
| | | | | RTS1 | 0 | UART1 RTS |
| | | | | T2_3 | I/O | timer 2 input capture/clock or PWM output |

Table 3. Pin description ...continued

I = *Input*; *O* = *Output*; *I/O* = *Input/Output*; *AI* = *Analog Input*.

| Symbol | Pin | | | | Туре | Description | |
|--------|--------|--------|--------|----------|------|---|--|
| | QN9020 | QN9021 | QN9022 | function | | | |
| P2_1 | 28 | - | 23 | P2_1 | I/O | GPIO17 | |
| | | | | DAT1 | I/O | in 4-wire mode, SPI0 output data; in 3-wire mode, data I/O | |
| | | | | TXD1 | 0 | UART1 TX data output with pull-up | |
| | | | | T3_1 | I/O | timer 3 input capture/clock or PWM output | |
| P2_0 | 29 | - | 24 | P2_0 | I/O | GPIO16 | |
| | | | | DIN1 | I | SPI1 input data in 4-wire mode; invalid in 3-wire mode | |
| | | | | RXD1 | I | UART1 RX data input | |
| | | | | T3_2 | I/O | timer 3 input capture/clock or PWM output | |
| P3_6 | 30 | - | - | P3_6 | I/O | GPIO30 | |
| | | | | nCS1_0 | I/O | SPI1 slave select for master/slave mode | |
| | | | | CTS1 | I | UART1 CTS | |
| RSTN | 31 | 19 | 25 | - | - | hardware reset, active LOW | |
| RVDD | 32 | 20 | 26 | - | - | regulated PA power output | |
| RFN | 33 | 21 | 27 | - | - | differential RF port | |
| RFP | 34 | 22 | 28 | - | - | differential RF port | |
| VSS | 35 | 23 | 29 | - | - | analog ground | |
| VDD | 36 | 24 | 30 | - | - | analog power supply | |
| REXT | 37 | 25 | 31 | - | - | current reference terminal, connect 56 k $\Omega\pm$ 1 % resistor to ground | |
| VDD | 38 | 26 | 32 | - | - | analog power supply | |
| XTAL2 | 39 | 27 | 33 | - | - | connected to 16 MHz or 32 MHz crystal | |
| XTAL1 | 40 | 28 | 34 | - | - | connected to 16 MHz or 32 MHz crystal | |
| P3_5 | 41 | - | - | P3_5 | I/O | GPIO29 | |
| | | | | nCS0_0 | I/O | SPI0 slave select for master/slave mode | |
| | | | | Т0_0 | I/O | timer 0 input capture/clock or PWM output | |
| P3_4 | 42 | - | - | P3_4 | I/O | GPIO28 | |
| | | | | SPICLK0 | I/O | SPI0 clock | |
| P3_3 | 43 | - | 35 | P3_3 | I/O | GPIO27 | |
| | | | | DAT0 | I/O | in 4-wire mode, SPI0 output data; in 3-wire mode, data I/O | |
| | | | | CLKOUT0 | 0 | clock output 0 | |
| P3_2 | 44 | - | 36 | P3_2 | I/O | GPIO26 | |
| | | | | DIN0 | I | SPI0 input data in 4-wire mode; invalid in 3-wire mode | |
| | | | | ACMP0_O | 0 | analog comparator 0 output | |
| P3_1 | 45 | 29 | 37 | P3_1 | I/O | GPIO25 | |
| | | | | T0_2 | I/O | timer 0 input capture/clock or PWM output | |
| | | | | AIN1 | I | ADC input channel 1 | |
| | | | | ACMP0- | I | analog comparator 0 negative input | |

Table 3.Pin description ...continued

I = Input; O = Output; I/O = Input/Output; AI = Analog Input.

| Symbol | Pin | Pin | | | Туре | Description |
|--------|-------------|--------|--------|----------|------|--|
| | QN9020 | QN9021 | QN9022 | function | | |
| P3_0 | _0 46 30 38 | | 38 | P3_0 | I/O | GPIO24 |
| | | | | T2_1 | I/O | timer 1 input capture/clock or PWM output |
| | | | | AIN0 AI | | ADC input channel 0 |
| | | | | ACMP0+ | AI | analog comparator 0 positive input |
| VSS | 47 | 31 | 39 | - | - | ground |
| IDC | 48 | 32 | 40 | - | - | if DC-to-DC is enabled, PWM driver is used for LC filter; if DC-to-DC is disabled, this pin is not connected |

[1] Available only in QN9022.

9. Functional description

QN902x integrates an ultra low power 2.4 GHz radio, a qualified software stack and application profiles on a single chip. The integrated Power Management Unit (PMU) controls the system operation in different power states, to ensure low-power operation. The high-frequency crystal oscillator provides the reference frequency for the radio transceiver, while the low-frequency oscillators maintain timing in sleep states.

The integrated AES coprocessor supports encryption with minimal MCU usage. Minimum MCU usage helps in reducing the load on the MCU and also reduces power consumption. The embedded MCU and additional memory provides additional signal processing capability and helps to run user applications.

QN902x includes a general-purpose ADC with four external independent input channels. The ADC is utilized for power supply voltage monitoring. Digital serial interfaces (SPI/UART/I²C) are integrated to communicate with application processor or digital sensors.

The UART supports Bluetooth LE Direct Test Mode (DTM). This interface is used to control the PHY layer with commercially available Bluetooth testers, used for qualification.

I²C-bus is integrated and supports both master and slave mode. It can communicate with a digital sensor or EEPROM.

9.1 MCU subsystem

The MCU subsystem includes:

- 32-bit ARM Cortex-M0 MCU
- 64 kB system memory
- Reset generation
- · Clock and power management unit
- Nested Vectored Interrupt Controller (NVIC)
- Serial Wire Debug (SWD) interface

9.1.1 MCU

The CPU core is a 32-bit ARM Cortex-M0 MCU offering significant benefits to application development. It includes the following:

- · Simple, easy-to-use programmers model
- Highly efficient ultra low power operation
- Excellent code density
- Deterministic, high-performance interrupt handling for 32 external interrupt inputs

The processor is extensively optimized for low power and delivers exceptional power efficiency through its efficient instruction set. It provides high-end processing hardware including a single-cycle multiplier.

9.1.2 Memory organization

QN902x has an on-chip system memory of 64 kB, used for storing application program and data. It is secured with a user-configurable protection mode, to prevent unauthorized access. The MCU is 32-bit, with an address space of 4 GB. It is shared between the system memory, ROM, system registers, peripheral registers, and general-purpose memory. The address space ranges from 0x0000 0000 to 0xFFFF FFFF; see Figure 5. The system memory is secured with a user-controllable protection scheme, which prevents unauthorized access.

| RESERVED | 0xFFFFFFFF |
|----------------------|--------------------------------|
| MCU PRIVATE PERIPHER | 0xEFFFFFF ALS 0xE0000000 |
| RESERVED | |
| ADC | 0x50013FFF |
| ADC | 0x50010000 |
| RESERVED | |
| GPIO | 0x50003FFF |
| GFIO | 0x50000000 |
| RESERVED | |
| APB PERIPHERALS | 0x400EFFFF |
| APB PERIPHERALS | 0x40000000 |
| RESERVED | |
| SYSTEM MEMORY | 0x1000FFFF |
| STSTEM MEMORY | 0x10000000 |
| RESERVED | |
| ROM | 0x00017FFF |
| NOIVI | 0x00000000 |
| | aaa-019325 |

Fig 5. Memory address map

9.1.3 RESET generation

The device has four sources of reset. The following events generate a reset:

• Forcing RSTN pin to LOW

- Power-on
- Brownout
- Watchdog time-out

9.1.4 Nested Vectored Interrupt Controller (NVIC)

QN902x supports Cortex-M0 built-in Nested Vectored Interrupt Controller (NVIC) with 24 external interrupt inputs. External interrupt signals are connected to the NVIC and the NVIC prioritizes the interrupts. Software is used to set the priority of each interrupt. The NVIC and Cortex-M0 processor core are closely coupled, providing low-latency interrupt processing and efficient processing of late arriving interrupts.

9.1.5 Clock and power management

QN902x provides flexible clocking scheme to balance between performance and power. A high frequency crystal oscillator is utilized to provide reference frequency and system clock. QN902x supports 16 MHz and 32 MHz external crystal with $\pm 50 \times 10^{-6}$ accuracy. The system clock is 32 MHz or its divided versions.

Two low-speed 32 kHz oscillators are integrated. The 32.768 kHz crystal oscillator is used where accurate timing is needed, while a 32 kHz RC oscillator reduces cost and power consumption. Only one works at a time.

QN902x features ultra low power consumption with two sleep modes, SLEEP and DEEP SLEEP. After the execution of Wait For Interrupt (WFI) instruction, the MCU stops execution, enters into SLEEP mode and stops the clock immediately. Before entering into SLEEP mode, MCU should set the sleep timer correctly and make the 32 kHz clock ready. If DEEP SLEEP mode is entered, it must wait for the external interrupts to wake it up.

When an external interrupt or sleep timer time-out occurs, the Wake-up Interrupt Controller (WIC) enables the system clock. It takes 16 clock cycles to wake up the MCU and restore the states, before MCU can resume program execution to process the interrupt.

Only P0_0 to P0_7 and P1_0 to P1_7 can wake up MCU out of sleep states. The power management unit controls the power states of the whole chip and switch on/off the supply to different parts, as per the power state.

| Mode | Digital regulator | 32 kHz oscillator | Sleep timer | Description |
|------------|-------------------|-------------------|-------------|--|
| deep sleep | off | off | off | wait for external interrupt to wake it up; RAM and register content retained |
| sleep | off | on | on | wait for SLEEP TIMER time-out to wake it up; RAM and register content retained |
| idle | on | on | on | 16 MHz or 32 MHz XTAL on; MCU idle |
| active | on | on | on | radio off; MCU on |
| radio | on | on | on | radio on |

Table 4.Power matrix

9.1.6 Serial Wire Debug (SWD) interface

QN902x provides a standard SWD interface and supports up to four hardware breakpoints and two watch points.

9.2 Flash

QN9020/1 have a 128 kB flash. The flash communicates with the MCU by internal SPI interface and can be used to store code or data. The flash has the following features:

- 32 equal sectors of 4 kB each, any sector can be erased individually
- Minimum 100000 erase/program cycles
- RES command, 1-byte command code
- Low power consumption

QN9022 has an interface to connect external flash.

9.3 Digital peripherals

9.3.1 TIMER 0/1/2/3

Timer 0 and timer 1 are general-purpose 32-bit timers whereas timer 2 and timer 3 are general-purpose 16-bit timers. Both have a programmable 10-bit prescaler. The prescaler source is a system clock, 32 kHz clock or an external clock input.

The timers have the following functions:

- · Input capture function
- Compare function
- PWM output

The timers generate maskable interrupts in the event of overflow, compare and capture. They are used to trigger MCU or ADC conversions.

9.3.2 Real-Time Clock (RTC)

A 32 kHz clock runs the RTC, which provides real time with calibration. It supports the following functions:

- · Time and date configuration on the fly
- One second interrupt generation, interrupt can be enabled or disabled through software
- · Input capture function with programmable noise canceler

9.3.3 WatchDog Timer (WDT)

The WatchDog Timer (WDT) is a 16-bit timer clocked by a 32 kHz clock. It is used as a recovery method in situations where the CPU may be subjected to a software upset. The WDT resets the system when the software fails to clear the WDT within the selected time interval. The WDT is configured either as a watchdog timer or as an interval timer for general-purpose use. If WDT is configured as an interval timer, it can be used to generate interrupts at selected time intervals. The maximum time-out interval is 1.5 days.

9.3.4 Sleep timer

The sleep timer is a 32-bit timer running at 32 kHz clock rate. It is in always-on power domain, used to set the interval for system to exit sleep mode and wake up MCU.

9.3.5 PWM

The PWM provides two-channel PWM waveforms with programmable period and duty cycle. It has two 8-bit auto reload down counter and programmable 10-bit prescaler for both channels. It supports the functions mentioned below:

- Predictable PWM initial output state
- Buffered compare register and polarity register to ensure correct PWM output
- Programmable overflow interrupt generation

9.3.6 DMA

The DMA controller is used to relieve the MCU of handling data transfer operations, leading to high performance and efficiency. It has a single DMA channel to support fixed and undefined length transfer. The source address and the destination address are programmable. It can be aborted immediately in a transfer process by configuring ABORT register, and a DMA done interrupt is generated meanwhile.

9.3.7 Random number generator

QN902x integrates a random number generator for security purpose.

9.3.8 AES coprocessor

The Advanced Encryption Standard (AES) coprocessor allows encryption/decryption to be performed with minimal CPU usage. The coprocessor supports 128-bit key and DMA transfer trigger capability.

9.4 Communication interfaces

9.4.1 UART 0/1

UART 0 and UART 1 have identical functions and include the following features:

- 8-bit payload mode: 8-bit data without parity
- 9-bit payload mode: 8-bit data plus parity
- The parity in 9-bit mode is odd or even configurable
- · Configurable start bit and stop bit levels
- Configurable LSB first or MSB first data transfer
- Parity and framing error status
- Configurable hardware flow control
- Support overrun
- Flexible baud rate: 1.2/2.4/4.8/9.6/14.4/19.2/28.8/38.4/57.6/76.8/115.2/230.4 kBd

9.4.2 SPI 0/1

SPI 0 and SPI 1 have identical functions and includes the following features:

- Master/slave mode configurable
- 4-wire or 3-wire configurable
- Clock speed configurable for master mode (divided from AHB clock)
- 4 MHz maximum clock speed in slave mode when AHB clock is 32 MHz
- 16 MHz maximum clock speed in master mode when AHB clock is 32 MHz
- · Configurable clock polarity and phase
- Configurable LSB or MSB first transfer

9.4.3 I²C-bus

The l²C-bus module provides an interface between the device and l²C-bus compatible devices connected by a 2-wire serial l²C-bus. The l²C-bus module features include:

- Compliance with the I²C-bus specification v2.1
- 7-bit device addressing modes
- Standard mode up to 100 kbit/s and fast mode up to 400 kbit/s support
- · Supports master arbitration in master mode
- Supports line stretch in slave mode

9.5 Radio and analog peripherals

9.5.1 RF transceiver

QN902x radio transceiver is compliant with volume 6, part A: physical layer specification for Bluetooth LE. The transceiver requires a 32 MHz or a 16 MHz crystal to provide reference frequency. It also requires a matching network to match an antenna connected to the receiver/transmitter pins.

9.5.2 On-chip oscillators

QN902x includes three integrated oscillators:

- HFXO: Low-power high frequency crystal oscillator supporting 32 MHz or 16 MHz external crystal
- LFXO: Ultra low power 32.768 kHz crystal oscillator
- LFRCO: Ultra low power 32 kHz RC oscillator with $\pm 250 \times 10^{-6}$ frequency accuracy after calibration

The high frequency crystal oscillator (HFXO) provides the reference frequency for radio transceiver. The low frequency 32.768 kHz oscillators provide the protocol timing. The low-frequency clock can also be obtained from a 32.768 kHz external clock source. For HFXO, the external capacitance is integrated to reduce the BOM cost. Software is used to adjust the capacitance.

9.5.3 DC-to-DC converter

QN902x includes highly efficient integrated regulators to generate all the internal supply voltages from a single external supply voltage. Optional integrated DC-to-DC down-converter is used to reduce the current consumption by 30 %. It is useful for applications using battery technologies with higher nominal cell voltages.

9.5.4 General-purpose ADC

QN902x integrates a general-purpose 8-bit or 10-bit SAR ADC, with a sampling rate of up to 50 kilosample per second. It includes an analog multiplexer with up to four external input channels. Conversion results can be moved to memory through DMA.

The main features of the ADC are as follows:

- · Four single-ended input channels, or two differential channels
- · Reference voltage selectable as internal or external signal-ended
- Interrupt request generation
- DMA triggers at the end of conversions
- Window compare function
- Battery measurement capability

When using internal reference voltage, it is calibrated to achieve high resolution.

The ADC operates in the following three modes:

- Signal conversion mode
- · Continuous conversion mode
- Scan mode (automatic switching among external inputs)

9.5.5 Analog comparator

The analog comparator is used to compare the voltage of two analog inputs and has a digital output to indicate the higher input voltage. The positive input is always from the external pin. The negative input can be either one of the selectable internal references or from an external pin.

The analog comparator features low-power operation. The comparison result is used as an interrupt source to wake up the system from SLEEP mode.

9.5.6 Battery monitor

A battery monitor is integrated by connecting supply voltage (V_{DD} / 4) to the ADC input. It uses the internal regulated reference for conversion.

10. Limiting values

Table 5.

Limiting values

| Symbol | Parameter | Conditions | Min | Max | Unit |
|--------------------------------------|---------------------------------|------------------------|------|------|------|
| V _{CC} | supply voltage | V _{CC} to GND | -0.3 | +5.0 | V |
| V _{DD} | supply voltage | V _{DD} to GND | -0.3 | +5.0 | V |
| T _{stg} | storage temperature | | -55 | +150 | °C |
| V _{ESD} electrostatic disch | electrostatic discharge voltage | human body model | | | |
| | | RFN, RFP | - | 1.5 | kV |
| | | other pins | - | 2 | kV |
| | | machine model | | | |
| | | RFN, RFP | - | 100 | V |
| | | other pins | - | 200 | V |
| | | charged-device model | | | |
| | | all pins | - | 1 | kV |

11. Recommended operating conditions

| Table 6. | Operating conditions | | | | | |
|--------------------------------|----------------------|-----------------|-----|-----|-----|------|
| Symbol | Parameter | Conditions | Min | Тур | Max | Unit |
| V _{CC} supply voltage | supply voltage | relative to GND | | | | |
| | | QN9020/1 | 2.4 | 3.0 | 3.6 | V |
| | | QN9022 | 1.8 | 3.0 | 3.6 | V |
| V _{DD} supply voltage | supply voltage | relative to GND | | | | |
| | | QN9020/1 | 1.8 | 3.0 | 3.6 | V |
| | | QN9022 | 1.8 | 3.0 | 3.6 | V |
| T _{amb} | ambient temperature | | -40 | +25 | +85 | °C |

12. Characteristics

12.1 DC characteristics

Table 7. DC characteristics

Typical values are T_{amb} = 25 °C and V_{CC} / V_{DD} = 3 V.

| Symbol | Parameter | Conditions | | Min | Тур | Max | Unit |
|--------------------------|---------------------------------------|---|---------------|---------------------|------|---------------------|------|
| I _{CC} | supply current | deep sleep mode | <u>[1][2]</u> | - | 2 | - | μA |
| | | sleep mode | <u>[1][3]</u> | - | 3 | - | μA |
| | | idle mode without DC-to-DC converter | <u>[1][4]</u> | - | 0.84 | - | mA |
| | MCU @8 MHz without DC-to-DC converter | <u>[1][5]</u> | - | 1.35 | - | mA | |
| | | RX mode without DC-to-DC converter | <u>[1][6]</u> | - | 13.6 | - | mA |
| | | RX mode with DC-to-DC converter [1][7] - | - | 9.25 | - | mA | |
| | | TX mode @0 dBm TX power without DC-to-DC converter | e . | | 13.3 | - | mA |
| | | TX mode @0 dBm TX power with DC-to-DC converter | <u>[1]</u> | - | 8.8 | - | mA |
| t _{startup} | start-up time | RSTN pin remains at LOW level | | 50 | - | - | μs |
| Interface ^[8] | | | | | | | |
| V _{OH} | HIGH-level output voltage | | | $0.9\times V_{CC}$ | - | - | V |
| V _{OL} | LOW-level output voltage | | | - | - | $0.1 \times V_{CC}$ | V |
| V _{IH} | HIGH-level input voltage | | | $0.7 \times V_{CC}$ | - | - | V |
| V _{IL} | LOW-level input voltage | | | - | - | $0.3\times V_{CC}$ | V |

[1] Supply current for both analog and digital modes.

[2] Deep sleep mode: digital regulator off, no clocks, POR, RAM/register control retained.

[3] Sleep mode: digital regulator off, 32 kHz RC oscillator on, POR, sleep timer on, and RAM/register content retained.

[4] Idle: 16 MHz oscillator on, no radio or peripherals, 8 MHz system clock and MCU idle (no code execution).

[5] MCU@8 MHz: MCU running at 8 MHz RC oscillator, no radio peripherals.

[6] RX sensitivity is -95 dBm when DC-to-DC is disabled.

[7] RX sensitivity is -93 dBm when DC-to-DC is enabled.

[8] Depend on I/O conditions.

Table 8. 16/32 MHz crystal oscillator reference clock

| Symbol | Parameter | Conditions | Min | Тур | Max | Unit |
|-------------------|-------------------------------|------------|------------------------|-----|------------------------|------|
| f _{xtal} | crystal frequency | | - | 16 | - | MHz |
| | | | - | 32 | - | MHz |
| Δf_{xtal} | crystal frequency accuracy | | -50 × 10 ⁻⁶ | - | +50 × 10 ⁻⁶ | - |

| Symbol | Parameter | Conditions | Min | Тур | Max | Unit |
|----------------------|------------------------------|-------------------------------|-----|-----|-----|------|
| ESR | equivalent series resistance | | - | - | 50 | Ω |
| CL | load capacitance | | 5 | - | 9 | pF |
| t _{startup} | start-up time | 16 MHz crystal oscillator [1] | - | - | 0.7 | ms |
| | | 32 MHz crystal oscillator [1] | - | - | 0.4 | ms |

Table 8. 16/32 MHz crystal oscillator reference clock ...continued

[1] Guaranteed by design.

Table 9. 32 kHz crystal oscillator reference clock Typical values are $T_{\rm eff} = 25 \, \%$ and $V_{\rm eff} = 3 \, V$

| Symbol | Parameter | Conditions | Min | Тур | Max | Unit |
|----------------------|-------------------------------|------------|-----|------------------------|-----|------|
| f _{xtal} | crystal frequency | | - | 32.768 | - | kHz |
| Δf_{xtal} | crystal frequency accuracy | | - | 250 × 10 ⁻⁶ | - | - |
| ESR | equivalent series resistance | | - | - | 100 | kΩ |
| CL | load capacitance | | - | 12 | - | pF |
| t _{startup} | start-up time | | - | 1 | - | s |

Table 10. 32 kHz RC oscillator reference clock

Typical values are $T_{amb} = 25 \ ^{\circ}C$ and $V_{CC} / V_{DD} = 3 \ V$. Symbol Parameter Conditions Min Unit Typ Max oscillator frequency 32 kHz f_{osc} 500 × 10⁻⁶ oscillator frequency _ fosc(acc) accuracy тс temperature 0.04 %/°C coefficient $\Delta f_{osc} / \Delta V_{CC}$ oscillator frequency 3 %/V variation with supply voltage calibration time 1 t_{cal} ms

Table 11. RF receiver characteristics

Typical values are $T_{amb} = 25 \ ^{\circ}C$; $V_{CC} / V_{DD} = 3 \ V$; $f_c = 2440 \ MHz$; BER < 0.1 %.

| Symbol | Parameter | Conditions | Min | Тур | Max | Unit |
|-------------------------|-------------------------|---|-----|-----|-----|------|
| S _{RX} | RX sensitivity | high performance mode | - | -95 | - | dBm |
| | | low power mode with DC-to-DC converter | - | -93 | - | dBm |
| P _{i(max)} | maximum input power | | - | 0 | - | dBm |
| C/I | carrier-to-interference | co-channel | - | 6 | - | dB |
| | ratio | adjacent channel @ ±1 MHz | - | -1 | - | dB |
| | | alternate channel $\cong \pm 2 \text{ MHz}$ | - | -40 | - | dB |
| α_{image} | image rejection | | - | -19 | - | dB |

Table 11. RF receiver characteristics ... continued

Typical values are T_{amb} = 25 °C; V_{CC} / V_{DD} = 3 V; f_c = 2440 MHz; BER < 0.1 %.

| Symbol | Parameter | Conditions | Min | Тур | Max | Unit |
|---------------------|--|----------------------|-----|-----|-----|------|
| $\alpha_{sup(oob)}$ | u _{sup(oob)} out-of-band suppression | 30 MHz to 2000 MHz | –18 | - | - | dBm |
| | | 2003 MHz to 2399 MHz | -18 | - | - | dBm |
| | | 2484 MHz to 2997 MHz | -18 | - | - | dBm |
| | | 3 GHz to 12.75 GHz | -18 | - | - | dBm |

Table 12. RF transmitter characteristics

Typical values are T_{amb} = 25 °C; V_{CC} / V_{DD} = 3 V; f_c = 2440 MHz.

| Symbol | Parameter | Conditions | Min | Тур | Max | Unit |
|------------------------|-------------------------------|-------------------------------------|------|------|--------|------|
| f _{o(RF)} | RF output frequency | | 2400 | - | 2483.5 | MHz |
| αcs | channel separation | | - | 2 | - | MHz |
| Po | output power | TX power without DC-to-DC converter | -20 | - | +4 | dBm |
| | | TX power with DC-to-DC converter | -20 | - | +4 | dBm |
| P _{o(RF)step} | RF output power step | | - | 2 | - | dB |
| P _{o(acc)} | TX power accuracy | | -2 | - | +2 | dB |
| I _{CC(TX)} | transmitter supply current | without DC-to-DC | | | | |
| | | 4 dBm | - | 17.6 | - | mA |
| | | 0 dBm | - | 13.3 | - | mA |
| | | –4 dBm | - | 10.5 | - | mA |
| | | –8 dBm | - | 8.3 | - | mA |
| | | –20 dBm | - | 6.1 | - | mA |
| | | with DC-to-DC | | | | |
| | | 0 dBm | - | 8.8 | - | mA |
| | | –4 dBm | - | 6.9 | - | mA |
| | | –8 dBm | - | 5.9 | - | mA |
| | | –20 dBm | - | 4.3 | - | mA |

Table 13.RSSI characteristics

Typical values are T_{amb} = 25 °C and V_{CC} / V_{DD} = 3 V.

| Symbol | Parameter | Conditions | Min | Тур | Мах | Unit |
|-----------------------------|-----------------|------------|-----|-----|-----|------|
| $\alpha_{RSSI(range)}$ | RSSI range | | -90 | - | -30 | dBm |
| α _{RSSI(acc)} | RSSI accuracy | | -4 | - | +4 | dB |
| $\alpha_{\text{RSSI(res)}}$ | RSSI resolution | | - | 1 | - | dB |

Table 14. ADC characteristics

Typical values are T_{amb} = 25 °C and V_{CC} / V_{DD} = 3 V, with differential ADC input signal.

| Symbol | Parameter | Conditions | Min | Тур | Max | Unit |
|---------------------|--------------------------|-------------------------|-------------------|------|-------------------|------|
| V _{I(ADC)} | ADC input voltage | single-ended mode | 0 | - | V _{ref} | V |
| | | differential input mode | -V _{ref} | - | +V _{ref} | V |
| ENOB | effective number of bits | 10-bit | - | 9.3 | - | bits |
| S/N | signal-to-noise ratio | 10-bit | - | 59.3 | - | dB |

Table 14. ADC characteristics ... continued

Typical values are T_{amb} = 25 °C and V_{CC} / V_{DD} = 3 V, with differential ADC input signal.

| Symbol | Parameter | Conditions | Min | Тур | Max | Unit |
|-------------------------|--------------------------------|------------------|-----|-------|-----|------|
| SFDR | spurious-free dynamic range | 10-bit | - | 65.2 | - | dB |
| THD | total harmonic distortion | 10-bit | - | -63 | - | dB |
| DNL | differential non-linearity | 10-bit | -1 | +0.6 | +2 | LSB |
| INL | integral non-linearity | 10-bit | -2 | +0.88 | +3 | LSB |
| t _{c(ADC)} | ADC conversion time | 10-bit | - | 18 | - | μs |
| E _G | gain error | 10-bit | - | 4 | 10 | LSB |
| Eo | offset error | 10-bit | - | - | 2 | LSB |
| I _{CC(int)ADC} | ADC internal supply | @1 MHz ADC clock | | | | |
| | current | ADC | - | 50 | 65 | μA |
| | | buffer | - | 140 | 180 | μA |
| | | PGA | - | 90 | 120 | μA |

Table 15. Battery monitor characteristics

Typical values are $T_{amb} = 25 \ ^{\circ}C$ and $V_{CC} / V_{DD} = 3 \ V$.

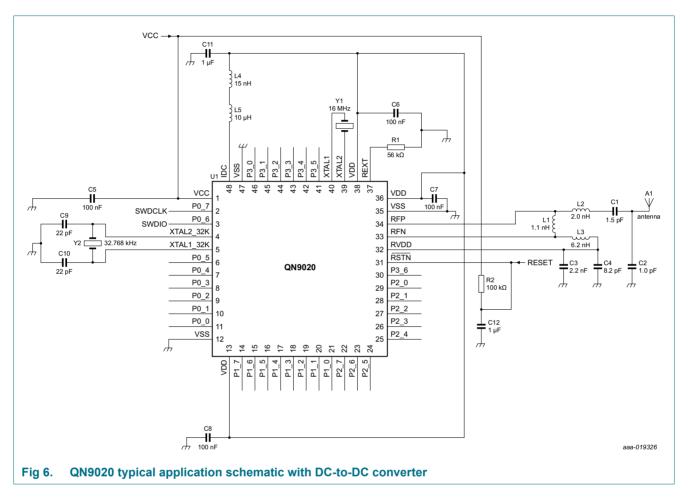
| Symbol | Parameter | Conditions | Min | Тур | Max | Unit |
|--------------------------|-----------------------------|------------|-----|-----|-----|------|
| V _{mon(bat)} | battery monitor voltage | QN9020/1 | 2.4 | - | 3.6 | V |
| | | QN9022 | 1.8 | - | 3.6 | V |
| V _{mon(bat)acc} | battery monitor accuracy | | - | 0.2 | - | mV |

Table 16. Analog comparator characteristics

Typical values are $T_{amb} = 25 \ ^{\circ}C$ and $V_{CC} / V_{DD} = 3 \ V$.

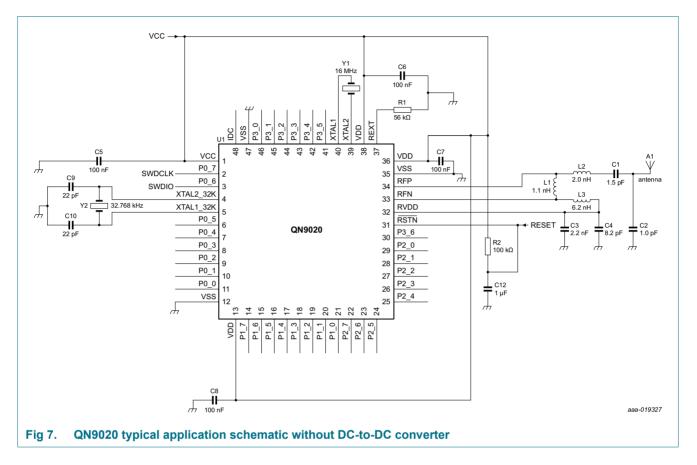
| Symbol | Parameter | Conditions | Min | Тур | Мах | Unit |
|------------------|-----------------------------------|------------|-----|-----|-----------------|------|
| Vi | input voltage | | 0 | - | V _{DD} | V |
| | analog internal supply current | | - | 0.3 | - | μA |
| V _{hys} | hysteresis | | - | 40 | - | mV |

13. Application information

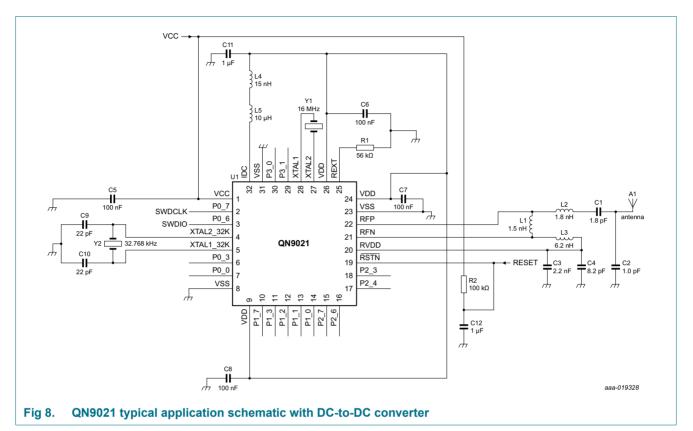


13.1 Schematic for QN9020 with DC-to-DC converter

QN902x

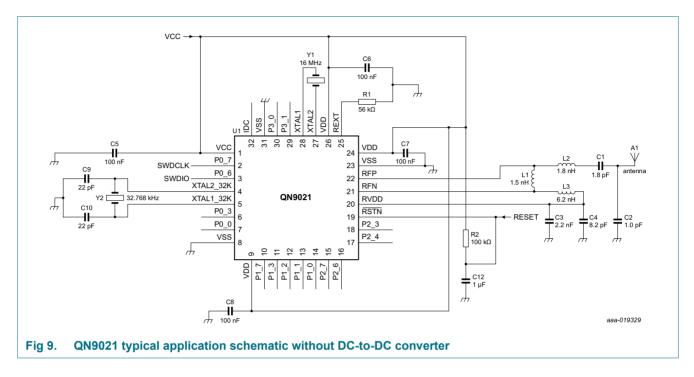


13.2 Schematic for QN9020 without DC-to-DC converter

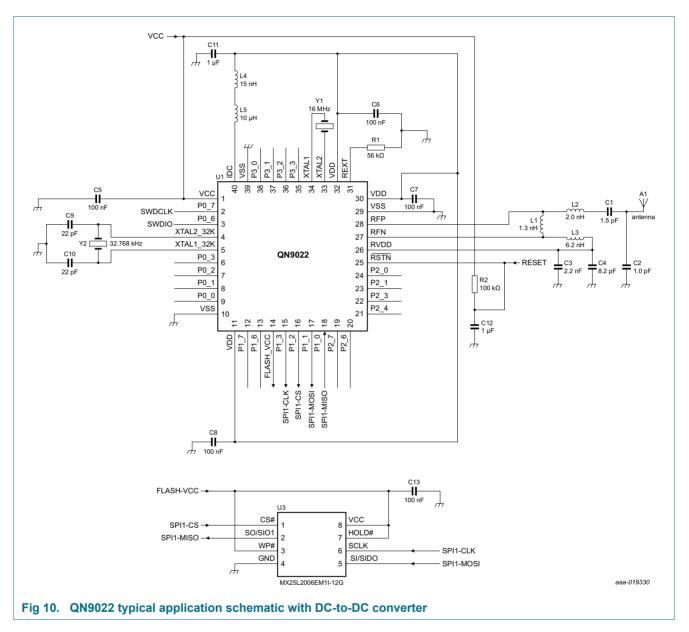


13.3 Schematic for QN9021 with DC-to-DC converter

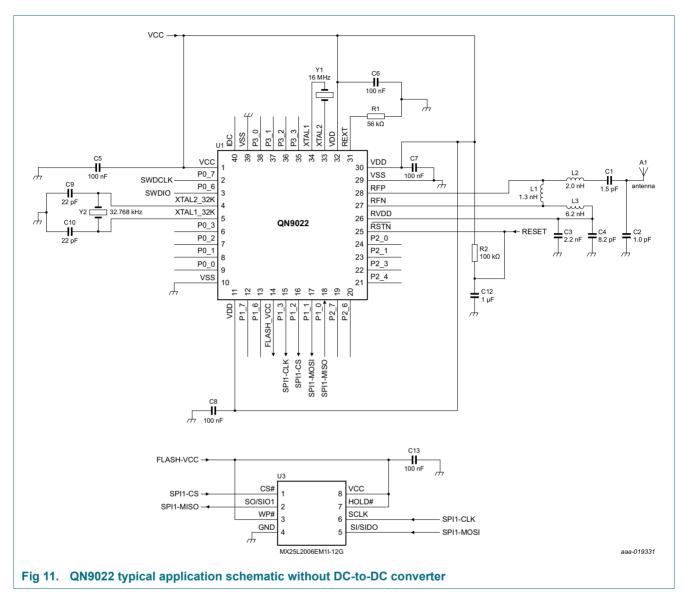
Product data sheet



13.4 Schematic for QN9021 without DC-to-DC converter



13.5 Schematic for QN9022 with DC-to-DC converter



13.6 Schematic for QN9022 without DC-to-DC converter

13.7 QN902x external component list

| Component | Description | Value |
|----------------|-------------------------------------|---|
| C1 | capacitor for RF matching network | 1.5 pF (QN9020/2), 1.8 pF (QN9021) |
| C2 | capacitor for RF matching network | 1.0 pF |
| C3 | capacitor for RF matching network | 2.2 nF |
| C4 | capacitor for RF matching network | 8.2 pF |
| C5, C6, C7, C8 | supply decoupling capacitors | 100 nF, X5R, ±10 %, 6.3 V, 0402 |
| C9, C10 | crystal loading capacitors | 22 pF, NP0, ±5 %, 25 V, 0402 |
| C11 | supply decoupling capacitor | 1 μF, NP0, ±5 %, 6.3 V, 0402 |
| C12 | capacitor used for reset | 1 μF, NP0, ±5 %, 6.3 V, 0402 |
| C13 | supply decoupling capacitor | 100 nF, X5R, ±10 %, 6.3 V, 0402 |
| L1 | inductor for RF matching network | 1.1 nH (QN9020), 1.5 nH (QN9021), 1.3 nH (QN9022) |
| L2 | inductor for RF matching network | 2.0 nH (QN9020/2), 1.8 nH (QN9021) |
| L3 | inductor for RF matching network | 6.2 nH |
| L4 | chip inductor for DC-to-DC | 15 nH |
| L5 | chip inductor for DC-to-DC | 10 μH |
| R1 | resistor used for current reference | 56 kΩ, ±1 %, 0402 |
| R2 | resistor used for reset | 100 kΩ, ±1 %, 0402 |

Table 17. External component list

14. Package outline

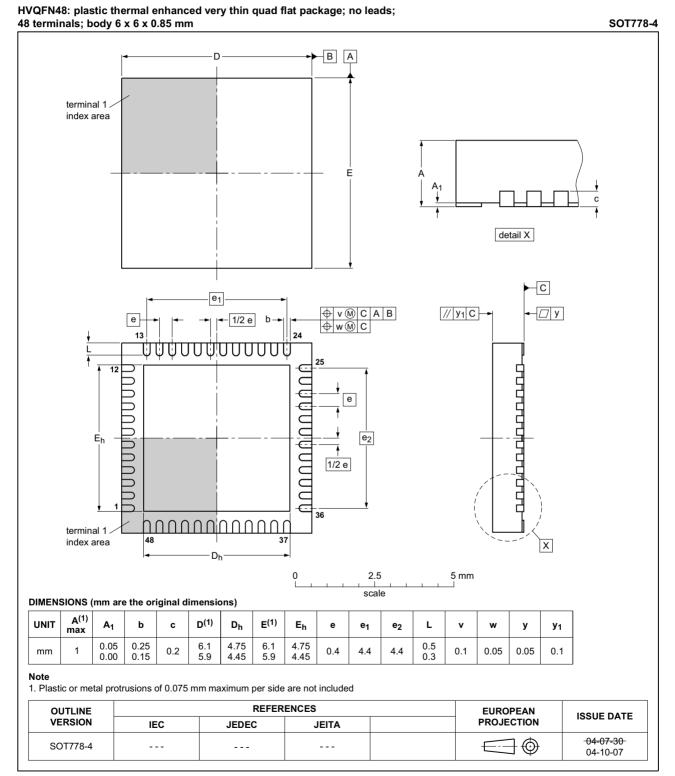
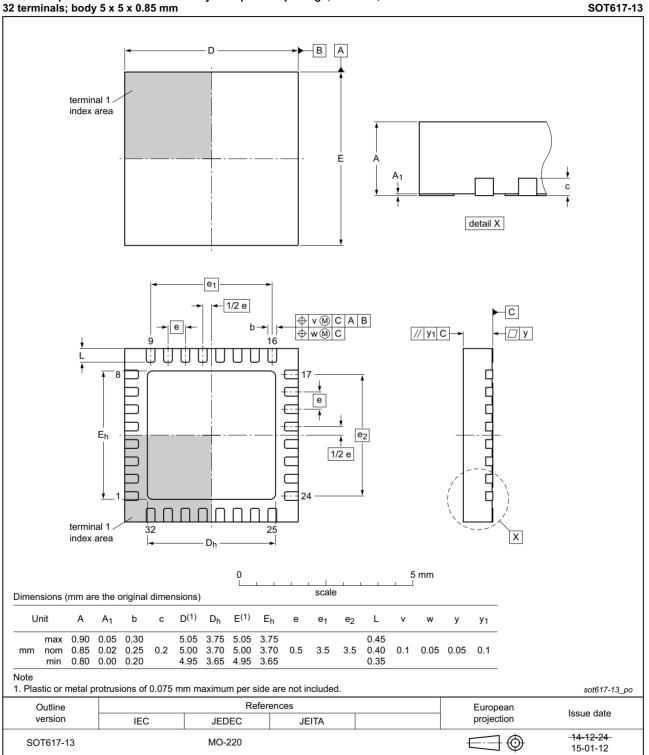


Fig 12. Package outline SOT778-4 (HVQFN48)

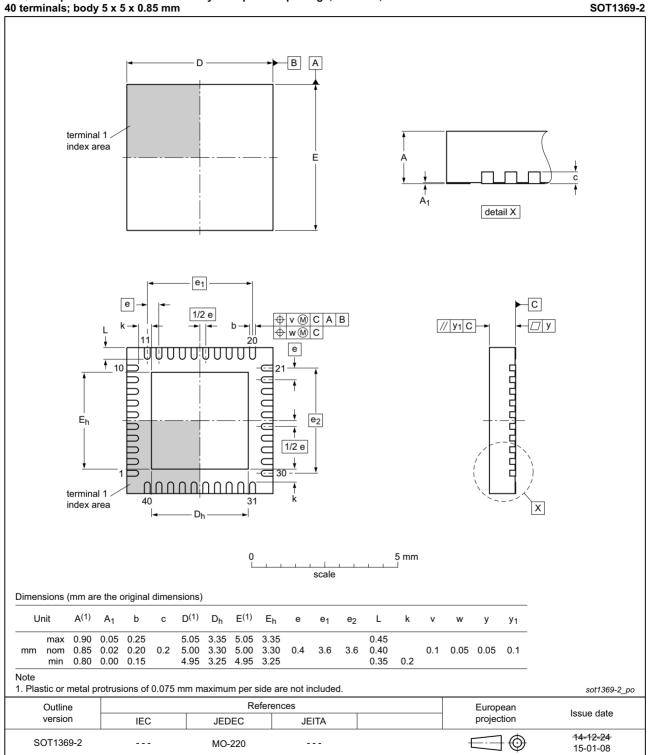
QN902x



HVQFN32: plastic thermal enhanced very thin quad flat package; no leads; 32 terminals; body 5 x 5 x 0.85 mm

Fig 13. Package outline SOT617-13 (HVQFN32)

QN902x



HVQFN40: plastic thermal enhanced very thin quad flat package; no leads; 40 terminals; body 5 x 5 x 0.85 mm

Fig 14. Package outline SOT1369-2 (HVQFN40)

15. Soldering of SMD packages

This text provides a very brief insight into a complex technology. A more in-depth account of soldering ICs can be found in Application Note *AN10365 "Surface mount reflow soldering description"*.

15.1 Introduction to soldering

Soldering is one of the most common methods through which packages are attached to Printed Circuit Boards (PCBs), to form electrical circuits. The soldered joint provides both the mechanical and the electrical connection. There is no single soldering method that is ideal for all IC packages. Wave soldering is often preferred when through-hole and Surface Mount Devices (SMDs) are mixed on one printed wiring board; however, it is not suitable for fine pitch SMDs. Reflow soldering is ideal for the small pitches and high densities that come with increased miniaturization.

15.2 Wave and reflow soldering

Wave soldering is a joining technology in which the joints are made by solder coming from a standing wave of liquid solder. The wave soldering process is suitable for the following:

- Through-hole components
- Leaded or leadless SMDs, which are glued to the surface of the printed circuit board

Not all SMDs can be wave soldered. Packages with solder balls, and some leadless packages which have solder lands underneath the body, cannot be wave soldered. Also, leaded SMDs with leads having a pitch smaller than ~0.6 mm cannot be wave soldered, due to an increased probability of bridging.

The reflow soldering process involves applying solder paste to a board, followed by component placement and exposure to a temperature profile. Leaded packages, packages with solder balls, and leadless packages are all reflow solderable.

Key characteristics in both wave and reflow soldering are:

- · Board specifications, including the board finish, solder masks and vias
- · Package footprints, including solder thieves and orientation
- · The moisture sensitivity level of the packages
- Package placement
- Inspection and repair
- Lead-free soldering versus SnPb soldering

15.3 Wave soldering

Key characteristics in wave soldering are:

- Process issues, such as application of adhesive and flux, clinching of leads, board transport, the solder wave parameters, and the time during which components are exposed to the wave
- Solder bath specifications, including temperature and impurities

220

15.4 Reflow soldering

≥ 2.5

Key characteristics in reflow soldering are:

- Lead-free versus SnPb soldering; note that a lead-free reflow process usually leads to higher minimum peak temperatures (see <u>Figure 15</u>) than a SnPb process, thus reducing the process window
- Solder paste printing issues including smearing, release, and adjusting the process window for a mix of large and small components on one board
- Reflow temperature profile; this profile includes preheat, reflow (in which the board is heated to the peak temperature) and cooling down. It is imperative that the peak temperature is high enough for the solder to make reliable solder joints (a solder paste characteristic). In addition, the peak temperature must be low enough that the packages and/or boards are not damaged. The peak temperature of the package depends on package thickness and volume and is classified in accordance with Table 18 and 19

| Package thickness (mm) | Package reflow temperature (°C |) |
|------------------------|--------------------------------|--------------|
| | Volume (mm ³) | |
| | < 350 | ≥ 350 |
| < 2.5 | 235 | 220 |

Table 18. SnPb eutectic process (from J-STD-020D)

220

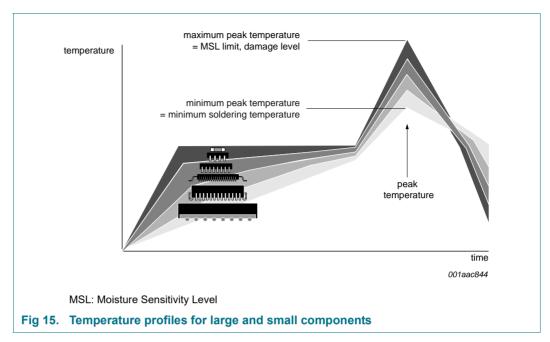
Table 19. Lead-free process (from J-STD-020D)

| Package thickness (mm) | Package reflow temp | erature (°C) | | |
|------------------------|---------------------------|--------------|--------|--|
| | Volume (mm ³) | | | |
| | < 350 | 350 to 2000 | > 2000 | |
| < 1.6 | 260 | 260 | 260 | |
| 1.6 to 2.5 | 260 | 250 | 245 | |
| > 2.5 | 250 | 245 | 245 | |

Moisture sensitivity precautions, as indicated on the packing, must be respected at all times.

Studies have shown that small packages reach higher temperatures during reflow soldering, see Figure 15.

QN902x



For further information on temperature profiles, refer to Application Note *AN10365 "Surface mount reflow soldering description"*.

16. Abbreviations

| Table 20. Abbreviations | |
|---------------------------------|---|
| Acronym | Description |
| ADC | Analog-to-Digital Converter |
| AES | Advanced Encryption Standard |
| АНВ | AMBA High-performance Bus |
| BER | Bit Error Rate |
| DTM | Direct Test Mode |
| EEPROM | Electrically Erasable Programmable Read Only Memory |
| GFSK | Gaussian Frequency-Shift Keying |
| GPIO | General Purpose Input Output |
| LDO | Low DropOut |
| LE | Low Energy |
| LSB | Least Significant Bit |
| MCU | MicroController Unit |
| MSB | Most Significant Bit |
| PGA | Programmable Gain Amplifier |
| PWM | Pulse Width Modulation |
| RF | Radio Frequency |
| RSSI | Received Signal Strength Indicator |
| RTC | Real-Time Clock |
| SAR | Successive Approximation Register |
| S/N | Signal-to-Noise ratio |
| SoC | System-on-Chip |
| SPI | Serial Peripheral Interface |
| SWD | Serial Wire Debug |
| UART | Universal Asynchronous Receiver Transmitter |

17. Revision history

| Document ID | Release date | Data sheet status | Change notice | Supersedes |
|----------------|--|--|------------------------------|----------------------------|
| QN902x v.2.7 | 20181121 | Product data sheet | | |
| Modifications | Changes the page 21 | ne maximum value of P_o in | Table 12 "RF transm | nitter characteristics" on |
| QN902x v.2.6 | 20181119 | Product data sheet | | |
| Modifications | page 6 | ne description of alternate ne description of alternate | | |
| QN902x v.2.5 | 20180418 | Product data sheet | | |
| Modifications | Added alter | nate function Fast Boot in Ta | ble 3 "Pin description" | on page 6 |
| QN902x v.2.4 | 20170116 | Product data sheet | - | QN902x v.2.3 |
| Modifications: | Minor updat | te to VDD voltage for QN9 | 020/1 <u>Table 6 "Operat</u> | ting conditions" on page 1 |
| QN902x v.2.3 | 20160905 | Product data sheet | - | QN902x v.2.2 |
| Modifications: | Minor updat | te to XTAL1 and XTAL2 in Ta | ble 3 "Pin description" | on page 6 |
| QN902x v.2.2 | 20160825 | Product data sheet | - | QN902x v.2.1 |
| Modifications: | Minor updat | te to Table 7 "DC characteris | tics" on page 18 | |
| QN902x v.2.1 | 20160414 | Product data sheet | - | QN902x v.2 |
| Modifications: | GPIO pin in Update to 1 | formation and package detainable 7 | ils for QN9020/1/2 upd | ated |
| QN902x v.2 | 20160314 | Product data sheet | - | QN902x v.1 |
| Modifications: | | about QN9022 is added to the state of the second seco | he data sheet | |
| QN902x v.1 | 20150210 | Product data sheet | - | - |

18. Legal information

18.1 Data sheet status

| Document status[1][2] | Product status ^[3] | Definition |
|--------------------------------|-------------------------------|---|
| Objective [short] data sheet | Development | This document contains data from the objective specification for product development. |
| Preliminary [short] data sheet | Qualification | This document contains data from the preliminary specification. |
| Product [short] data sheet | Production | This document contains the product specification. |

[1] Please consult the most recently issued document before initiating or completing a design.

[2] The term 'short data sheet' is explained in section "Definitions".

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