

### Related products

- See TSV631, TSV632, TSV634 series for lower minimum supply voltage (1.5 V)
- See LMV821, LMV822, LMV824 series for higher gain bandwidth products (5.5 MHz)

### Applications

- Battery powered applications
- Portable devices
- Automotive signal conditioning
- Active filtering
- Medical instrumentation

### Description

The TSV52x and TSV52xA series of operational amplifiers offer low voltage operation and rail-to-rail input and output. The TSV521 device is the single version, the TSV522 device the dual version, and the TSV524 device the quad version, with pinouts compatible with industry standards.

The TSV52x and TSV52xA series offer an outstanding speed/power consumption ratio, 1.15 MHz gain bandwidth product while consuming only 45  $\mu$ A at 5 V. The devices are housed in the smallest industrial packages.

These features make the TSV52x, TSV52xA family ideal for sensor interfaces, battery supplied and portable applications. The wide temperature range and high ESD tolerance facilitate their use in harsh automotive applications.

### Features

- Gain bandwidth product: 1.15 MHz typ. at 5 V
- Low power consumption: 45  $\mu$ A typ. at 5 V
- Rail-to-rail input and output
- Low input bias current: 1 pA typ.
- Supply voltage: 2.7 to 5.5 V
- Low offset voltage: 800  $\mu$ V max.
- Unity gain stable on 100 pF capacitor
- Automotive grade

### Benefits

- Increased lifetime in battery powered applications
- Easy interfacing with high impedance sensors

**Table 1. Device summary**

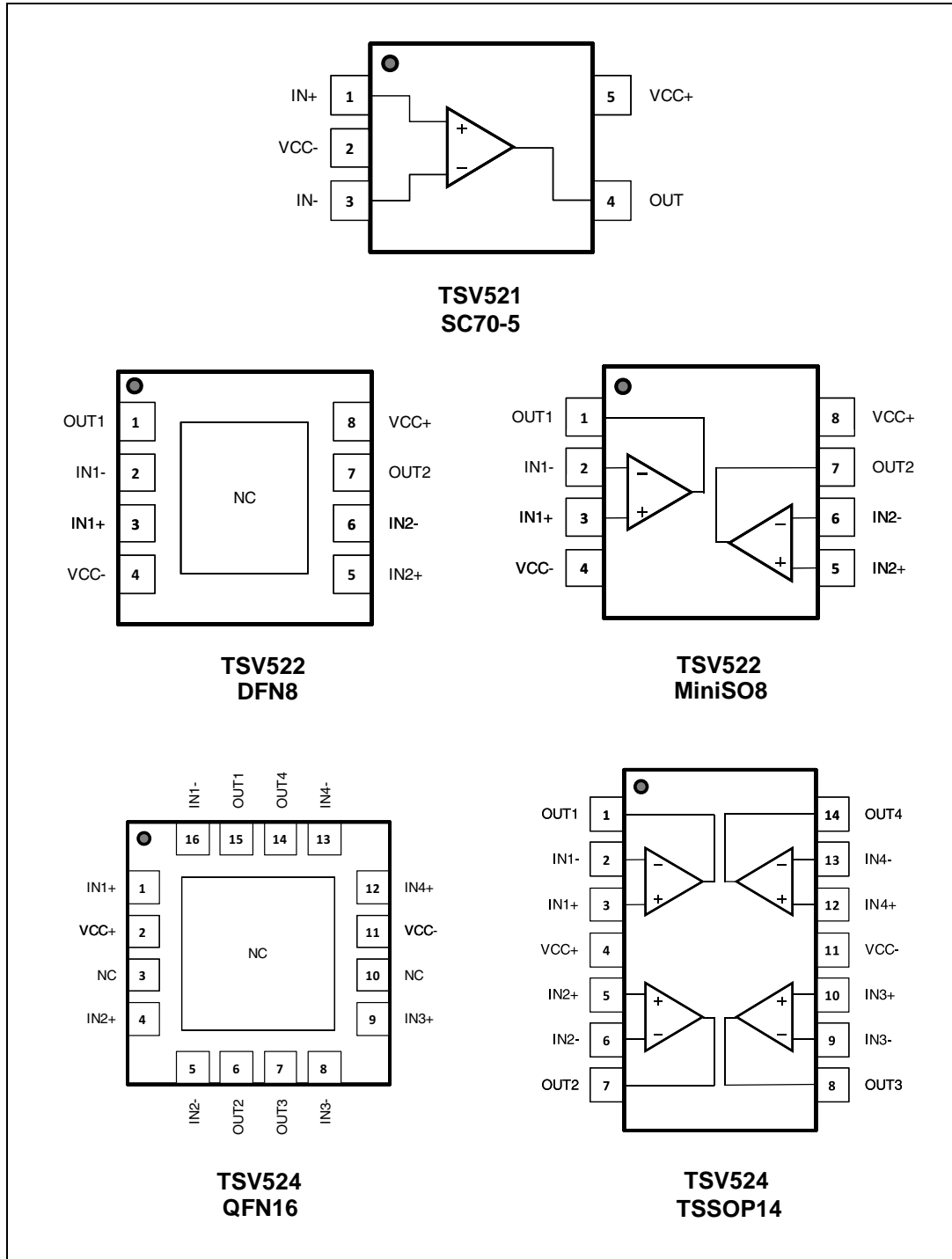
	Standard $V_{IO}$	Enhanced $V_{IO}$
Single	TSV521	TSV521A
Dual	TSV522	TSV522A
Quad	TSV524	TSV524A

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# 1 Package pin connections

Figure 1. Pin connections for each package (top view)



1. The exposed pads of the DFN8 (2x2) and QFN16 (3x3) can be connected to VCC- or left floating.

## 2 Absolute maximum ratings and operating conditions

**Table 2. Absolute maximum ratings (AMR)**

Symbol	Parameter	Value	Unit
$V_{CC}$	Supply voltage <sup>(1)</sup>	6	V
$V_{id}$	Differential input voltage <sup>(2)</sup>	$\pm V_{CC}$	
$V_{in}$	Input voltage <sup>(3)</sup>	$V_{CC-} - 0.2$ to $V_{CC+} + 0.2$	
$I_{in}$	Input current <sup>(4)</sup>	10	mA
$T_{stg}$	Storage temperature	-65 to +150	°C
$R_{thja}$	Thermal resistance junction-to-ambient <sup>(5)(6)</sup>		°C/W
	SC70-5	205	
	DFN8 2x2	57	
	QFN16 3x3	45	
	MiniSO8	190	
	TSSOP14	100	
$T_j$	Maximum junction temperature	150	°C
ESD	HBM: human body model <sup>(7)</sup>	4	kV
	MM: machine model <sup>(8)</sup>	300	V
	CDM: charged device model <sup>(9)</sup> (all packages except SC70-5 and DFN8)	1.5	kV
	CDM: charged device model (SC70-5 and DFN8) <sup>(9)</sup>	1.3	
	Latch-up immunity	200	mA

1. All voltage values, except differential voltages are with respect to network ground terminal.
2. Differential voltages are the non inverting input terminal with respect to the inverting input terminal.
3.  $V_{CC-} - V_{in}$  must not exceed 6 V,  $V_{in}$  must not exceed 6 V.
4. Input current must be limited by a resistor in series with the inputs.
5. Short-circuits can cause excessive heating and destructive dissipation.
6.  $R_{th}$  are typical values.
7. Human body model: 100 pF discharged through a 1.5 k $\Omega$  resistor between two pins of the device, done for all couples of pin combinations with other pins floating.
8. Machine model: a 200 pF cap is charged to the specified voltage, then discharged directly between two pins of the device with no external series resistor (internal resistor < 5  $\Omega$ ), done for all couples of pin combinations with other pins floating.
9. Charged device model: all pins plus package are charged together to the specified voltage and then discharged directly to ground.

**Table 3. Operating conditions**

Symbol	Parameter	Value	Unit
$V_{CC}$	Supply voltage	2.7 to 5.5	V
$V_{icm}$	Common-mode input voltage range	$V_{CC-} - 0.1$ to $V_{CC+} + 0.1$	
$T_{oper}$	Operating free air temperature range	-40 to +125	°C

### 3 Electrical characteristics

Table 4. Electrical characteristics at  $V_{CC+} = +2.7\text{ V}$  with  $V_{CC-} = 0\text{ V}$ ,  $V_{icm} = V_{CC}/2$ ,  $T = 25\text{ }^{\circ}\text{C}$ , and  $R_L = 10\text{ k}\Omega$  connected to  $V_{CC}/2$  (unless otherwise specified)

Symbol	Parameter	Conditions	Min.	Typ.	Max.	Unit
<b>DC performance</b>						
$V_{io}$	Offset voltage	TSV52xA, $T = 25\text{ }^{\circ}\text{C}$			800	$\mu\text{V}$
		TSV52xA, $-40\text{ }^{\circ}\text{C} < T < 125\text{ }^{\circ}\text{C}$			2600	
		TSV52x, $T = 25\text{ }^{\circ}\text{C}$			1.5	$\text{mV}$
		TSV52x, $-40\text{ }^{\circ}\text{C} < T < 125\text{ }^{\circ}\text{C}$			3.3	
$\Delta V_{io}/\Delta T$	Input offset voltage drift	$-40\text{ }^{\circ}\text{C} < T < 125\text{ }^{\circ}\text{C}^{(1)}$		3	18	$\mu\text{V}/^{\circ}\text{C}$
$I_{io}$	Input offset current ( $V_{out} = V_{CC}/2$ )	$T = 25\text{ }^{\circ}\text{C}$		1	$10^{(3)}$	$\text{pA}$
		$-40\text{ }^{\circ}\text{C} < T < 125\text{ }^{\circ}\text{C}$		1	$100^{(3)}$	
$I_{ib}$	Input bias current ( $V_{out} = V_{CC}/2$ )	$T = 25\text{ }^{\circ}\text{C}$		1	$10^{(3)}$	
		$-40\text{ }^{\circ}\text{C} < T < 125\text{ }^{\circ}\text{C}$		1	$100^{(3)}$	
CMR	Common-mode rejection ratio $20 \log(\Delta V_{ic}/\Delta V_{io})$ $V_{ic} = -0.1\text{ V to } V_{CC} + 0.1\text{ V}$ , $V_{out} = V_{CC}/2$ , $R_L = 1\text{ M}\Omega$	$T = 25\text{ }^{\circ}\text{C}$	50	72		$\text{dB}$
		$-40\text{ }^{\circ}\text{C} < T < 125\text{ }^{\circ}\text{C}$	46			
$A_{vd}$	Large signal voltage gain $V_{out} = 0.5\text{ V to } (V_{CC} - 0.5\text{ V})$ , $R_L = 1\text{ M}\Omega$	$T = 25\text{ }^{\circ}\text{C}$	90	105		
		$-40\text{ }^{\circ}\text{C} < T < 125\text{ }^{\circ}\text{C}$	60			
$V_{OH}$	High level output voltage	$T = 25\text{ }^{\circ}\text{C}$ $-40\text{ }^{\circ}\text{C} < T < 125\text{ }^{\circ}\text{C}$		3	35 50	$\text{mV}$
$V_{OL}$	Low level output voltage	$T = 25\text{ }^{\circ}\text{C}$ $-40\text{ }^{\circ}\text{C} < T < 125\text{ }^{\circ}\text{C}$		6	35 50	
$I_{out}$	$I_{sink}$	$V_{out} = V_{CC}$ , $T = 25\text{ }^{\circ}\text{C}$	12	22		$\text{mA}$
		$V_{out} = V_{CC}$ , $-40\text{ }^{\circ}\text{C} < T < 125\text{ }^{\circ}\text{C}$	8			
	$I_{source}$	$V_{out} = 0\text{ V}$ , $T = 25\text{ }^{\circ}\text{C}$	12	18		
		$V_{out} = 0\text{ V}$ , $-40\text{ }^{\circ}\text{C} < T < 125\text{ }^{\circ}\text{C}$	8			
$I_{CC}$	Supply current (per channel) $V_{out} = V_{CC}/2$ , $R_L > 1\text{ M}\Omega$	$T = 25\text{ }^{\circ}\text{C}$		30	51	$\mu\text{A}$
		$-40\text{ }^{\circ}\text{C} < T < 125\text{ }^{\circ}\text{C}$		30	51	
<b>AC performance</b>						
GBP	Gain bandwidth product	$R_L = 10\text{ k}\Omega$ , $C_L = 100\text{ pF}$	0.62	1		$\text{MHz}$
$F_u$	Unity gain frequency			900		$\text{kHz}$
$\Phi_m$	Phase margin			55		degrees
$G_m$	Gain margin			7		$\text{dB}$
SR	Slew rate	$R_L = 10\text{ k}\Omega$ , $C_L = 100\text{ pF}$ , $V_{out} = 0.5\text{ V to } V_{CC} - 0.5\text{ V}$		0.74		$\text{V}/\mu\text{s}$

**Table 4. Electrical characteristics at  $V_{CC+} = +2.7\text{ V}$  with  $V_{CC-} = 0\text{ V}$ ,  $V_{icm} = V_{CC}/2$ ,  $T = 25\text{ }^{\circ}\text{C}$ , and  $R_L = 10\text{ k}\Omega$  connected to  $V_{CC}/2$  (unless otherwise specified) (continued)**

Symbol	Parameter	Conditions	Min.	Typ.	Max.	Unit
$e_n$	Equivalent input noise voltage	$f = 1\text{ kHz}$ $f = 10\text{ kHz}$		61 43		$\frac{\text{nV}}{\sqrt{\text{Hz}}}$
THD+N	Total harmonic distortion + noise	Follower configuration, $f_{in} = 1\text{ kHz}$ , $R_L = 100\text{ k}\Omega$ , $V_{icm} = V_{CC}/2$ , $BW = 22\text{ kHz}$ , $V_{out} = 1\text{ V}_{pp}$		0.003		%

**Table 5. Electrical characteristics at  $V_{CC+} = +3.3\text{ V}$  with  $V_{CC-} = 0\text{ V}$ ,  $V_{icm} = V_{CC}/2$ ,  $T = 25\text{ }^{\circ}\text{C}$ , and  $R_L = 10\text{ k}\Omega$  connected to  $V_{CC}/2$  (unless otherwise specified)**

Symbol	Parameter	Conditions	Min.	Typ.	Max.	Unit
<b>DC performance</b>						
$V_{io}$	Offset voltage	TSV52xA, $T = 25\text{ }^{\circ}\text{C}$			600	$\mu\text{V}$
		TSV52xA, $-40\text{ }^{\circ}\text{C} < T < 125\text{ }^{\circ}\text{C}$			2400	
		TSV52x, $T = 25\text{ }^{\circ}\text{C}$			1.3	mV
		TSV52x, $-40\text{ }^{\circ}\text{C} < T < 125\text{ }^{\circ}\text{C}$			3.1	
$\Delta V_{io}/\Delta T$	Input offset voltage drift	$-40\text{ }^{\circ}\text{C} < T < 125\text{ }^{\circ}\text{C}^{(1)}$		3	18	$\mu\text{V}/^{\circ}\text{C}$
$\Delta V_{io}$	Long term input offset voltage drift	$T = 25\text{ }^{\circ}\text{C}^{(2)}$		0.3		$\frac{\mu\text{V}}{\sqrt{\text{month}}}$
$I_{io}$	Input offset current ( $V_{out} = V_{CC}/2$ )	$T = 25\text{ }^{\circ}\text{C}$		1	$10^{(3)}$	pA
		$-40\text{ }^{\circ}\text{C} < T < 125\text{ }^{\circ}\text{C}$		1	$100^{(3)}$	
$I_{ib}$	Input bias current ( $V_{out} = V_{CC}/2$ )	$T = 25\text{ }^{\circ}\text{C}$		1	$10^{(3)}$	
		$-40\text{ }^{\circ}\text{C} < T < 125\text{ }^{\circ}\text{C}$		1	$100^{(3)}$	
CMR	Common-mode rejection ratio $20 \log(\Delta V_{ic}/\Delta V_{io})$ $V_{ic} = -0.1\text{ V to } V_{CC} + 0.1\text{ V}$ , $V_{out} = V_{CC}/2$ , $R_L = 1\text{ M}\Omega$	$T = 25\text{ }^{\circ}\text{C}$	51	73		dB
		$-40\text{ }^{\circ}\text{C} < T < 125\text{ }^{\circ}\text{C}$	47			
$A_{vd}$	Large signal voltage gain $V_{out} = 0.5\text{ V to } (V_{CC} - 0.5\text{ V})$ , $R_L = 1\text{ M}\Omega$	$T = 25\text{ }^{\circ}\text{C}$	91	106		
		$-40\text{ }^{\circ}\text{C} < T < 125\text{ }^{\circ}\text{C}$	63			
$V_{OH}$	High level output voltage	$T = 25\text{ }^{\circ}\text{C}$ $-40\text{ }^{\circ}\text{C} < T < 125\text{ }^{\circ}\text{C}$		3	35 50	mV
$V_{OL}$	Low level output voltage	$T = 25\text{ }^{\circ}\text{C}$ $-40\text{ }^{\circ}\text{C} < T < 125\text{ }^{\circ}\text{C}$		7	35 50	
$I_{out}$	$I_{sink}$	$V_{out} = V_{CC}$ , $T = 25\text{ }^{\circ}\text{C}$	20	31		mA
		$V_{out} = V_{CC}$ , $-40\text{ }^{\circ}\text{C} < T < 125\text{ }^{\circ}\text{C}$	17			
	$I_{source}$	$V_{out} = 0\text{ V}$ , $T = 25\text{ }^{\circ}\text{C}$	19	27		
		$V_{out} = 0\text{ V}$ , $-40\text{ }^{\circ}\text{C} < T < 125\text{ }^{\circ}\text{C}$	17			
$I_{CC}$	Supply current (per channel) $V_{out} = V_{CC}/2$ , $R_L > 1\text{ M}\Omega$	$T = 25\text{ }^{\circ}\text{C}$		32	55	$\mu\text{A}$
		$-40\text{ }^{\circ}\text{C} < T < 125\text{ }^{\circ}\text{C}$		32	55	

**Table 5. Electrical characteristics at  $V_{CC+} = +3.3\text{ V}$  with  $V_{CC-} = 0\text{ V}$ ,  $V_{icm} = V_{CC}/2$ ,  $T = 25\text{ }^{\circ}\text{C}$ , and  $R_L = 10\text{ k}\Omega$  connected to  $V_{CC}/2$  (unless otherwise specified) (continued)**

Symbol	Parameter	Conditions	Min.	Typ.	Max.	Unit
<b>AC performance</b>						
GBP	Gain bandwidth product	$R_L = 10\text{ k}\Omega$ , $C_L = 100\text{ pF}$	0.64	1		MHz
$F_u$	Unity gain frequency			900		kHz
$\Phi_m$	Phase margin			55		degrees
$G_m$	Gain margin			7		dB
SR	Slew rate	$R_L = 10\text{ k}\Omega$ , $C_L = 100\text{ pF}$ , $V_{out} = 0.5\text{ V}$ to $V_{CC} - 0.5\text{ V}$		0.75		V/ $\mu\text{s}$
$e_n$	Equivalent input noise voltage	$f = 1\text{ kHz}$ $f = 10\text{ kHz}$		60 42		$\frac{\text{nV}}{\sqrt{\text{Hz}}}$
THD+N	Total harmonic distortion + noise	Follower configuration, $f_{in} = 1\text{ kHz}$ , $R_L = 100\text{ k}\Omega$ , $V_{icm} = V_{CC}/2$ , $BW = 22\text{ kHz}$ , $V_{out} = 1\text{ V}_{pp}$		0.003		%

**Table 6. Electrical characteristics at  $V_{CC+} = +5\text{ V}$  with  $V_{CC-} = 0\text{ V}$ ,  $V_{icm} = V_{CC}/2$ ,  $T = 25\text{ }^{\circ}\text{C}$ , and  $R_L = 10\text{ k}\Omega$  connected to  $V_{CC}/2$  (unless otherwise specified)**

Symbol	Parameter	Conditions	Min.	Typ.	Max.	Unit
<b>DC performance</b>						
$V_{io}$	Offset voltage	TSV52xA, $T = 25\text{ }^{\circ}\text{C}$			600	$\mu\text{V}$
		TSV52xA, $-40\text{ }^{\circ}\text{C} < T < 125\text{ }^{\circ}\text{C}$			2400	
		TSV52x, $T = 25\text{ }^{\circ}\text{C}$			1	mV
		TSV52x, $-40\text{ }^{\circ}\text{C} < T < 125\text{ }^{\circ}\text{C}$			2.8	
$\Delta V_{io}/\Delta T$	Input offset voltage drift	$-40\text{ }^{\circ}\text{C} < T < 125\text{ }^{\circ}\text{C}^{(1)}$		3	18	$\mu\text{V}/^{\circ}\text{C}$
$\Delta V_{io}$	Long term input offset voltage drift	$T = 25\text{ }^{\circ}\text{C}^{(2)}$		0.7		$\frac{\mu\text{V}}{\sqrt{\text{month}}}$
$I_{io}$	Input offset current ( $V_{out} = V_{CC}/2$ )	$T = 25\text{ }^{\circ}\text{C}$		1	$10^{(3)}$	pA
		$-40\text{ }^{\circ}\text{C} < T < 125\text{ }^{\circ}\text{C}$		1	$100^{(3)}$	
$I_{ib}$	Input bias current ( $V_{out} = V_{CC}/2$ )	$T = 25\text{ }^{\circ}\text{C}$		1	$10^{(3)}$	
		$-40\text{ }^{\circ}\text{C} < T < 125\text{ }^{\circ}\text{C}$		1	$100^{(3)}$	
CMR1	Common-mode rejection ratio $20\log(\Delta V_{ic}/\Delta V_{io})$ $V_{ic} = -0.1\text{ V}$ to $V_{CC} + 0.1\text{ V}$ , $V_{out} = V_{CC}/2$ , $R_L = 1\text{ M}\Omega$	$T = 25\text{ }^{\circ}\text{C}$	54	76		dB
		$-40\text{ }^{\circ}\text{C} < T < 125\text{ }^{\circ}\text{C}$	50			
CMR2	Common-mode rejection ratio $20\log(\Delta V_{ic}/\Delta V_{io})$ $V_{ic} = 1\text{ V}$ to $V_{CC} - 1\text{ V}$ , $V_{out} = V_{CC}/2$ , $R_L = 1\text{ M}\Omega$	$T = 25\text{ }^{\circ}\text{C}$	63	84		
		$-40\text{ }^{\circ}\text{C} < T < 125\text{ }^{\circ}\text{C}$	58			

**Table 6. Electrical characteristics at  $V_{CC+} = +5\text{ V}$  with  $V_{CC-} = 0\text{ V}$ ,  $V_{icm} = V_{CC}/2$ ,  $T = 25\text{ }^\circ\text{C}$ , and  $R_L = 10\text{ k}\Omega$  connected to  $V_{CC}/2$  (unless otherwise specified) (continued)**

Symbol	Parameter	Conditions	Min.	Typ.	Max.	Unit
SVR	Supply voltage rejection ratio $20 \log (\Delta V_{CC}/\Delta V_{io})$ $V_{CC} = 2.7\text{ V to } 5.5\text{ V}$ , $V_{out} = V_{CC}/2$	$T = 25\text{ }^\circ\text{C}$	65	87		dB
		$-40\text{ }^\circ\text{C} < T < 125\text{ }^\circ\text{C}$	60			
$A_{vd}$	Large signal voltage gain $V_{out} = 0.5\text{ V to } (V_{CC} - 0.5\text{ V})$ , $R_L = 1\text{ M}\Omega$	$T = 25\text{ }^\circ\text{C}$	94	109		
		$-40\text{ }^\circ\text{C} < T < 125\text{ }^\circ\text{C}$	68			
$V_{OH}$	High level output voltage	$T = 25\text{ }^\circ\text{C}$ $-40\text{ }^\circ\text{C} < T < 125\text{ }^\circ\text{C}$		5	35 50	mV
$V_{OL}$	Low level output voltage	$T = 25\text{ }^\circ\text{C}$ $-40\text{ }^\circ\text{C} < T < 125\text{ }^\circ\text{C}$		9	35 50	
$I_{out}$	$I_{sink}$	$V_{out} = V_{CC}$ , $T = 25\text{ }^\circ\text{C}$	36	55		mA
		$V_{out} = V_{CC}$ , $-40\text{ }^\circ\text{C} < T < 125\text{ }^\circ\text{C}$	27			
	$I_{source}$	$V_{out} = 0\text{ V}$ , $T = 25\text{ }^\circ\text{C}$	36	55		
		$V_{out} = 0\text{ V}$ , $-40\text{ }^\circ\text{C} < T < 125\text{ }^\circ\text{C}$	27			
$I_{CC}$	Supply current (per channel) $V_{out} = V_{CC}/2$ , $R_L > 1\text{ M}\Omega$	$T = 25\text{ }^\circ\text{C}$		45	60	$\mu\text{A}$
		$-40\text{ }^\circ\text{C} < T < 125\text{ }^\circ\text{C}$		45	60	
<b>AC performance</b>						
GBP	Gain bandwidth product	$R_L = 10\text{ k}\Omega$ , $C_L = 100\text{ pF}$	0.73	1.15		MHz
$F_u$	Unity gain frequency	$R_L = 10\text{ k}\Omega$ , $C_L = 100\text{ pF}$		900		kHz
$\Phi_m$	Phase margin	$R_L = 10\text{ k}\Omega$ , $C_L = 100\text{ pF}$		55		degrees
$G_m$	Gain margin	$R_L = 10\text{ k}\Omega$ , $C_L = 100\text{ pF}$		7		dB
SR	Slew rate	$R_L = 10\text{ k}\Omega$ , $C_L = 100\text{ pF}$ , $V_{out} = 0.5\text{ V to } V_{CC} - 0.5\text{ V}$		0.89		$\text{V}/\mu\text{s}$
$\int e_n$	Low-frequency peak-to-peak input noise	Bandwidth: $f = 0.1\text{ to } 10\text{ Hz}$		14		$\mu\text{V}_{pp}$
$e_n$	Equivalent input noise voltage	$f = 1\text{ kHz}$ $f = 10\text{ kHz}$		57 39		$\frac{\text{nV}}{\sqrt{\text{Hz}}}$
THD+N	Total harmonic distortion + noise	Follower configuration, $f_{in} = 1\text{ kHz}$ , $R_L = 100\text{ k}\Omega$ , $V_{icm} = V_{CC}/2$ , $BW = 22\text{ kHz}$ , $V_{out} = 1\text{ V}_{pp}$		0.002		%

1. See [Section 4.6: Input offset voltage drift over temperature](#).
2. Typical value is based on the  $V_{io}$  drift observed after 1000 h at 125 °C extrapolated to 25 °C using the Arrhenius law and assuming an activation energy of 0.7 eV. The operational amplifier is aged in follower mode configuration.
3. Guaranteed by design.



Figure 2. Supply current vs. supply voltage at  $V_{icm} = V_{CC}/2$

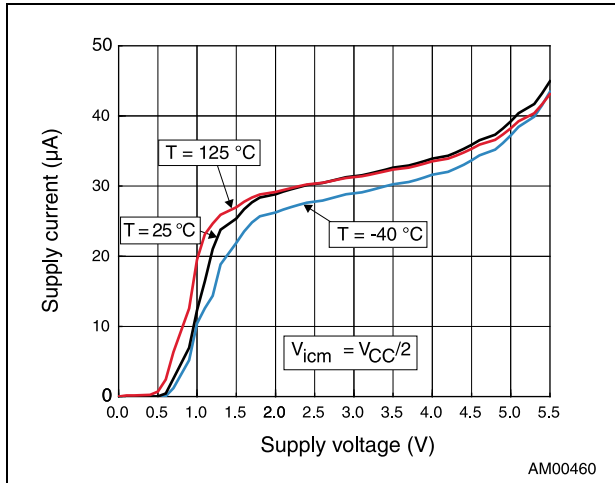


Figure 3. Input offset voltage distribution at  $V_{CC} = 5 V, V_{icm} = 2.5 V$

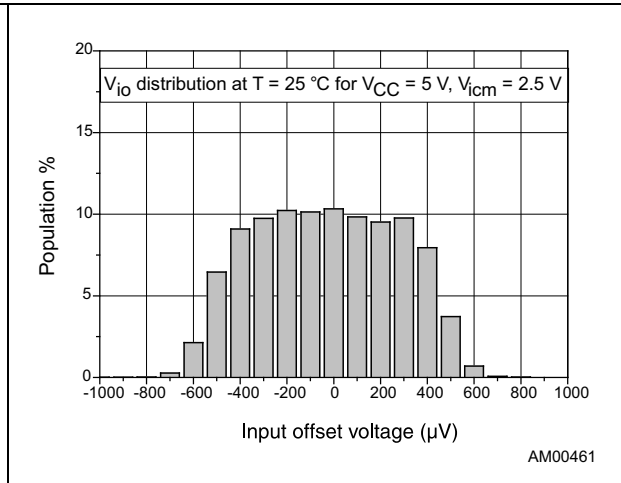


Figure 4. Input offset voltage temperature coefficient distribution

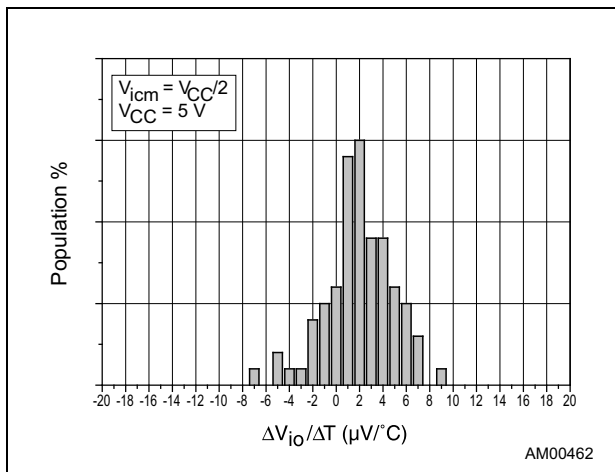


Figure 5. Input offset voltage vs. input Common-mode voltage at  $V_{CC} = 5 V$

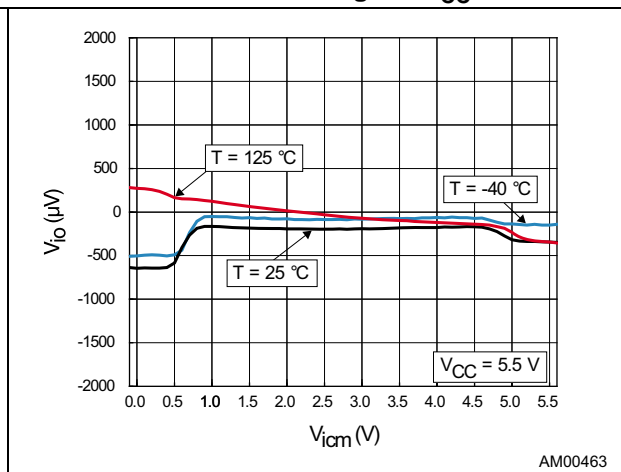


Figure 6. Input offset voltage vs. temperature at  $V_{CC} = 5 V$

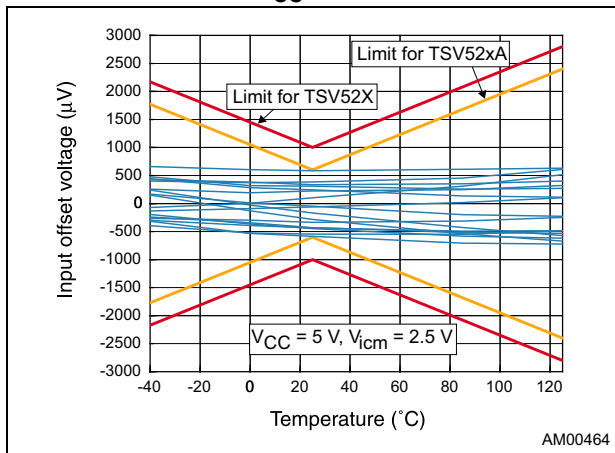


Figure 7. Output current vs. output voltage at  $V_{CC} = 2.7 V$

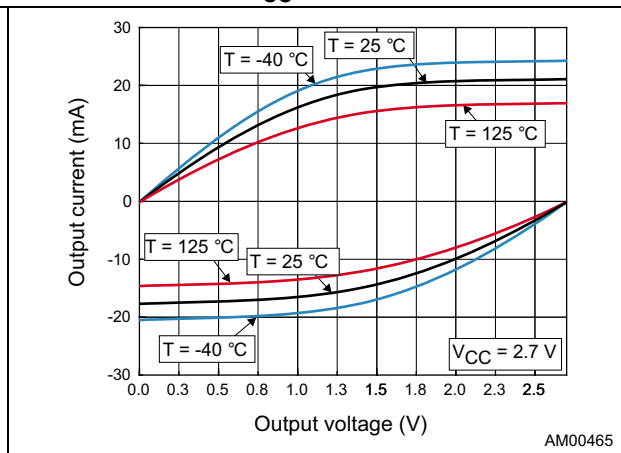


Figure 8. Output current vs. output voltage at  $V_{CC} = 5.5\text{ V}$

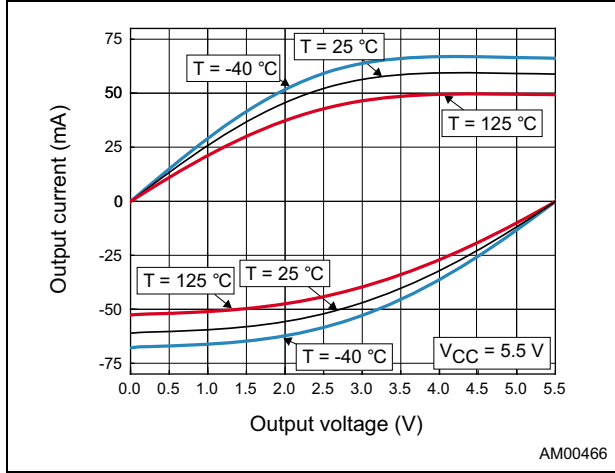


Figure 9. Bode diagram at  $V_{CC} = 2.7\text{ V}$ ,  $R_L = 10\text{ k}\Omega$

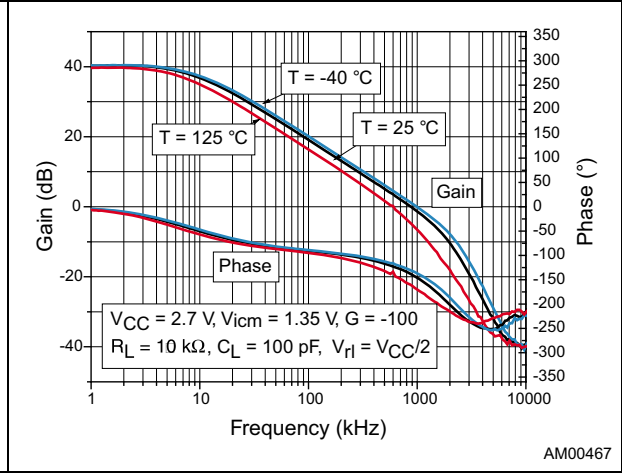


Figure 10. Bode diagram at  $V_{CC} = 2.7\text{ V}$ ,  $R_L = 2\text{ k}\Omega$

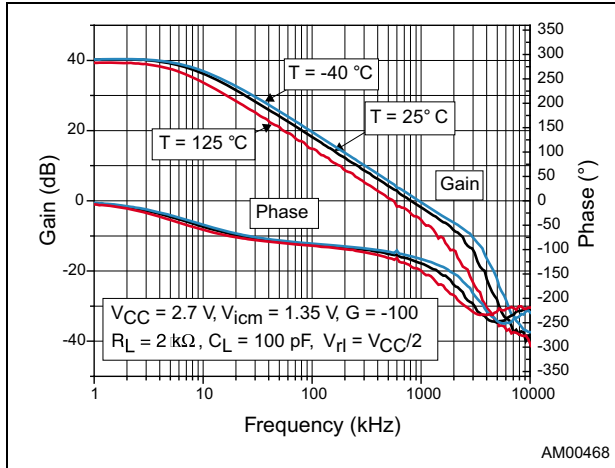


Figure 11. Bode diagram at  $V_{CC} = 5.5\text{ V}$ ,  $R_L = 10\text{ k}\Omega$

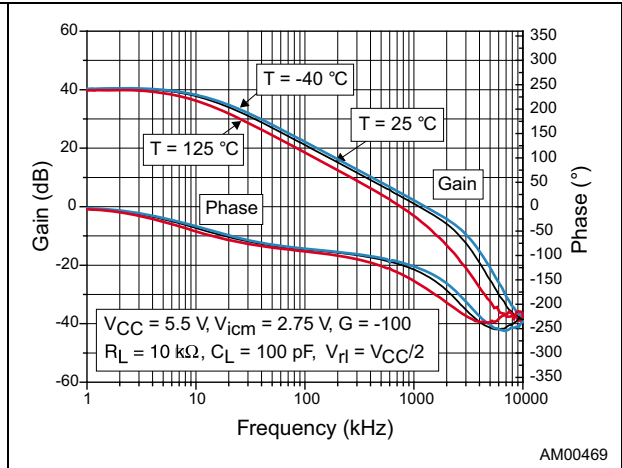


Figure 12. Bode diagram at  $V_{CC} = 5.5\text{ V}$ ,  $R_L = 2\text{ k}\Omega$

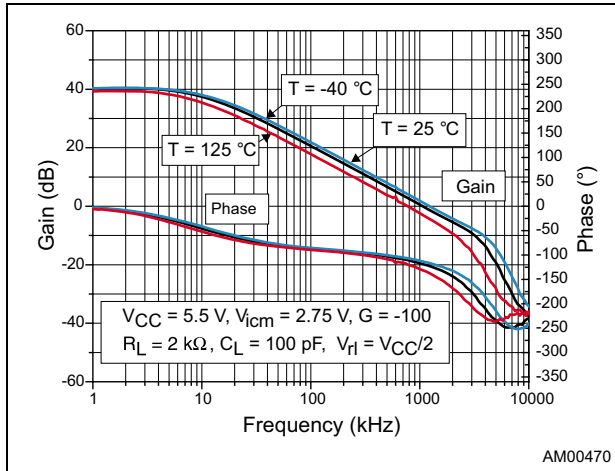


Figure 13. Noise vs. frequency

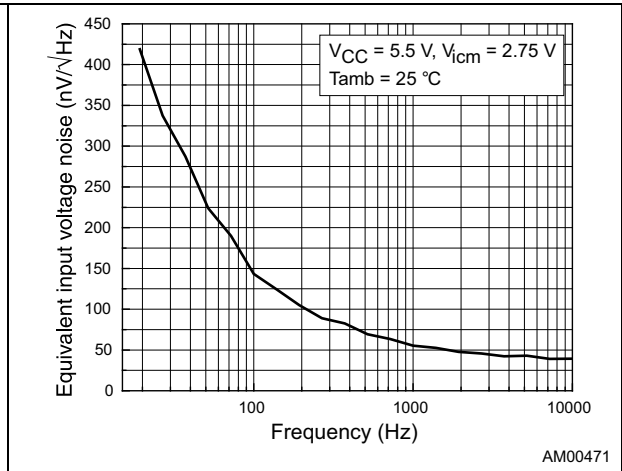


Figure 14. Positive slew rate vs. supply voltage Figure 15. Negative slew rate vs. supply voltage

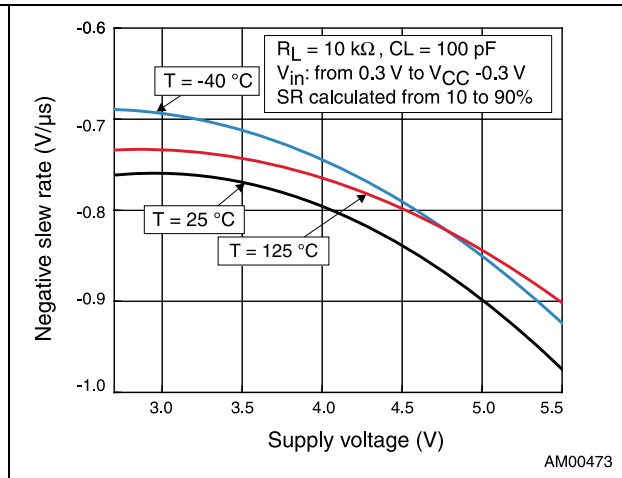
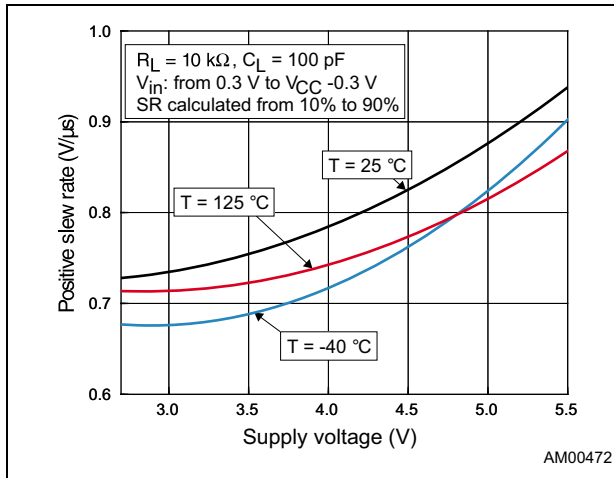


Figure 16. THD+N vs. frequency at V<sub>CC</sub> = 2.7 V

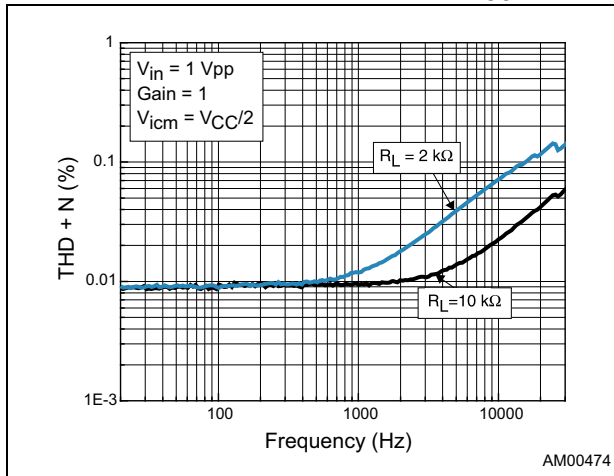


Figure 17. THD+N vs. frequency at V<sub>CC</sub> = 5.5 V

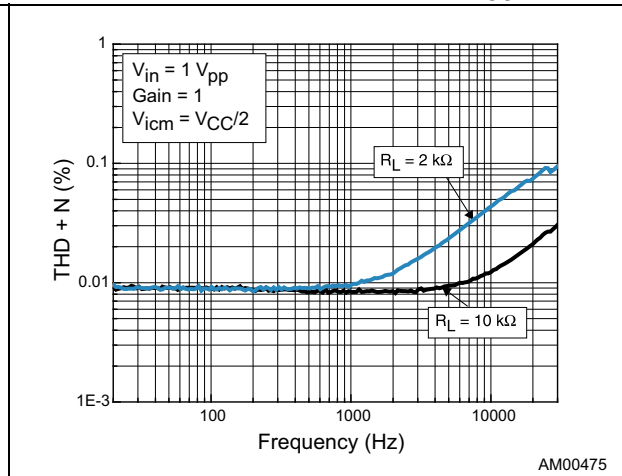


Figure 18. THD+N vs. output voltage at V<sub>CC</sub> = 2.7 V

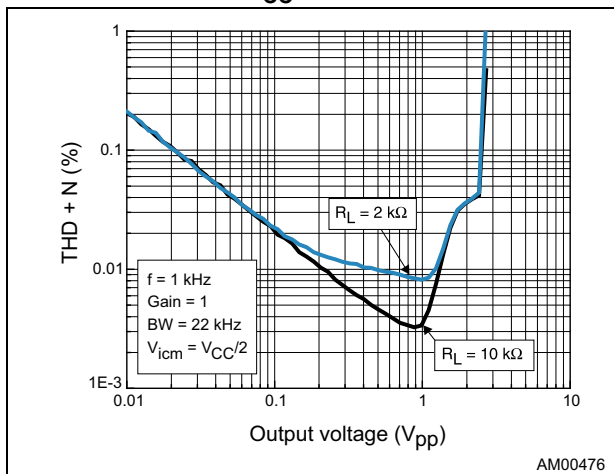


Figure 19. THD+N vs. output voltage at V<sub>CC</sub> = 5.5 V

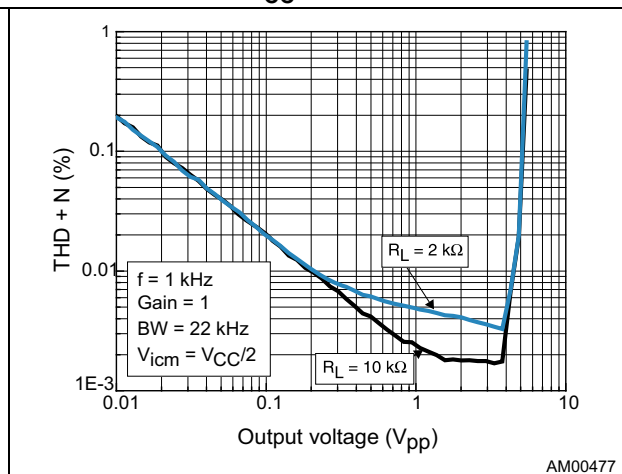


Figure 20. Output impedance versus frequency in closed-loop configuration

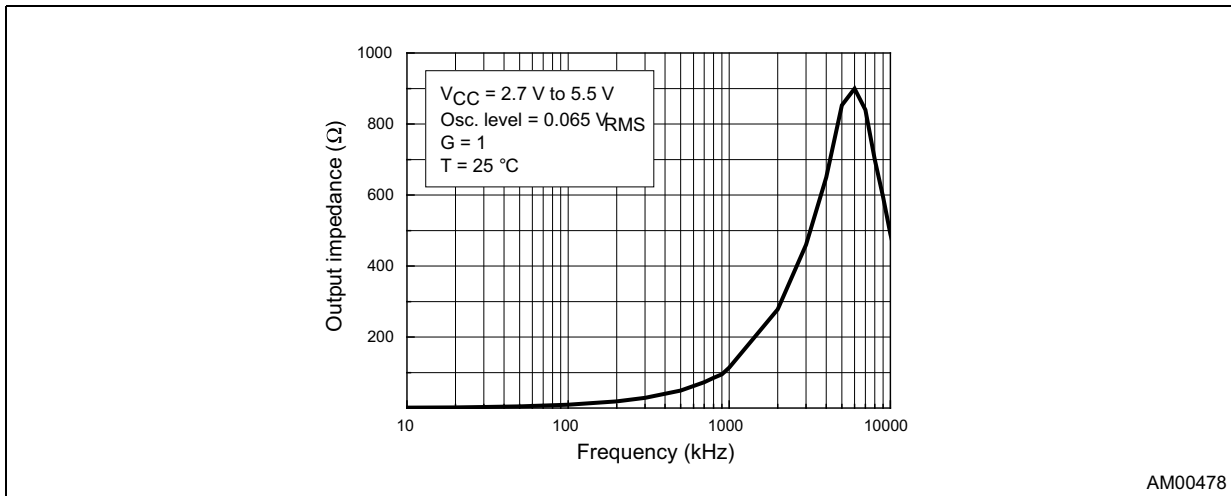


Figure 21. Response to a 100 mV input step for gain = 1 at  $V_{CC} = 5.5\text{ V}$  rising edge

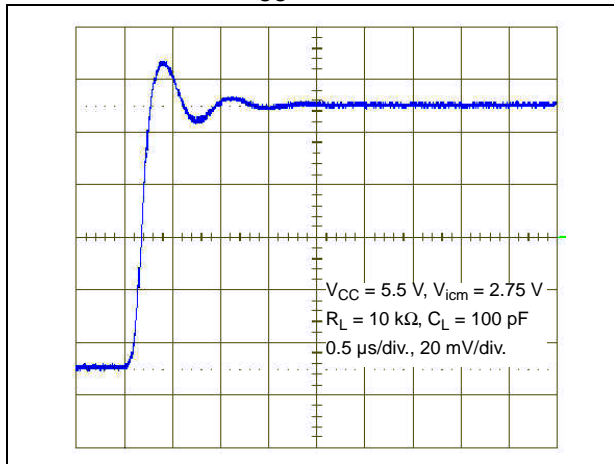


Figure 22. Response to a 100 mV input step for gain = 1 at  $V_{CC} = 5.5\text{ V}$  falling edge

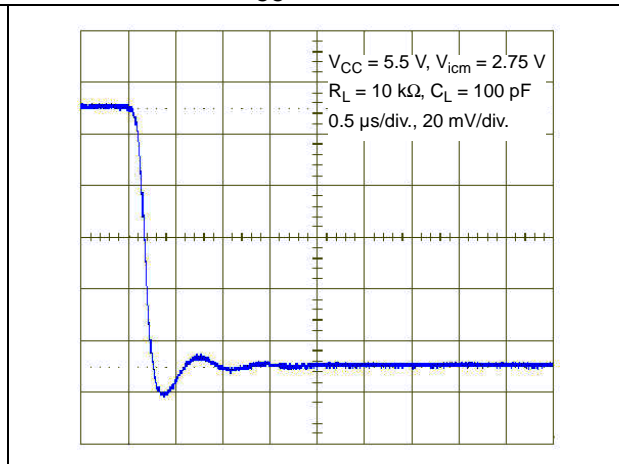


Figure 23. PSRR vs. frequency at  $V_{CC} = 2.7\text{ V}$

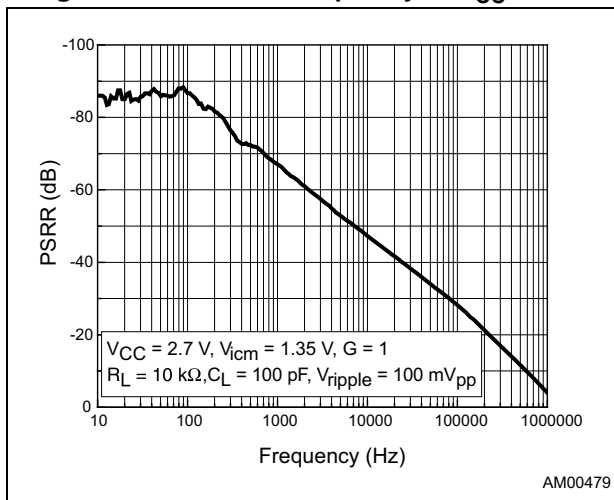
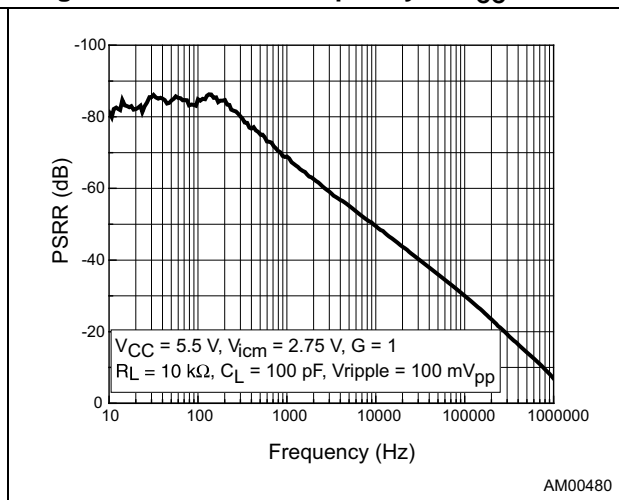


Figure 24. PSRR vs. frequency at  $V_{CC} = 5.5\text{ V}$



## 4 Application information

### 4.1 Operating voltages

The amplifiers of the TSV52x, TSV52xA series can operate from 2.7 V to 5.5 V. Their parameters are fully specified for 2.7 V, 3.3 V and 5 V power supplies. However, the parameters are very stable in the full  $V_{CC}$  range and several characterization curves show the TSV52x, TSV52xA device characteristics at 2.7 V. Additionally, the main specifications are guaranteed in extended temperature ranges from -40 to +125 °C.

### 4.2 Common-mode voltage range

The TSV52x, TSV52xA devices are built with two complementary PMOS and NMOS input differential pairs. The devices have a rail-to-rail input and the input Common-mode range is extended from  $V_{CC-} - 0.1$  V to  $V_{CC+} + 0.1$  V.

The N channel pair is active for input voltage close to the positive rail typically ( $V_{CC+} - 0.7$  V) to 100 mv above the positive rail.

The P channel pair is active for input voltage close to the negative rail typically 100 mV below the negative rail to  $V_{CC-} + 0.7$  V.

And between  $V_{CC-} + 0.7$  V and  $V_{CC+} - 0.7$  V the both N and P pairs are active.

When the both pairs work together it allows to increase the speed of the TSV52x, TSV52xA devices. This architecture improves the merit factor of the whole device. In the transition region, the performance of CMR, SVR,  $V_{io}$  (Figure 25 and Figure 26) and THD is slightly degraded.

Figure 25. Input offset voltage vs. input common-mode at  $V_{CC} = 2.7$  V

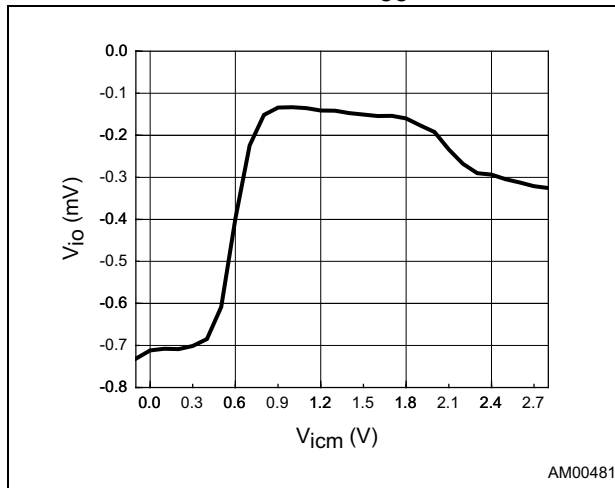
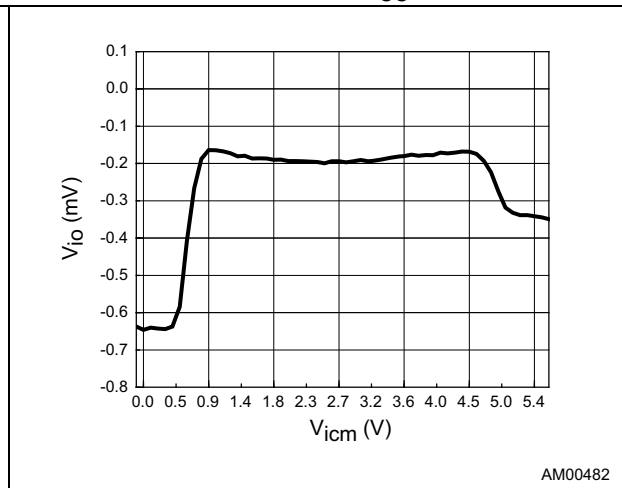


Figure 26. Input offset voltage vs. input common-mode at  $V_{CC} = 5.5$  V



### 4.3 Rail-to-rail input

The TSV52x, TSV52xA series are guaranteed without phase reversal as shown in [Figure 28](#).

It is extremely important that the current flowing in the input pin does not exceed 10 mA. In order to limit this current, a serial resistor can be added on the  $V_{in}$  path.

Figure 27. Phase reversal test schematic

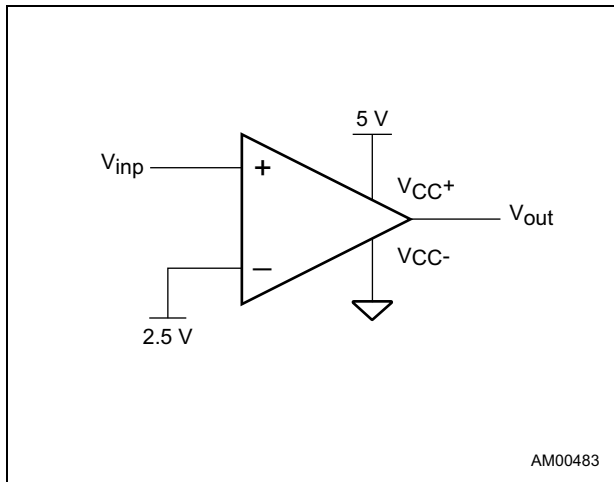
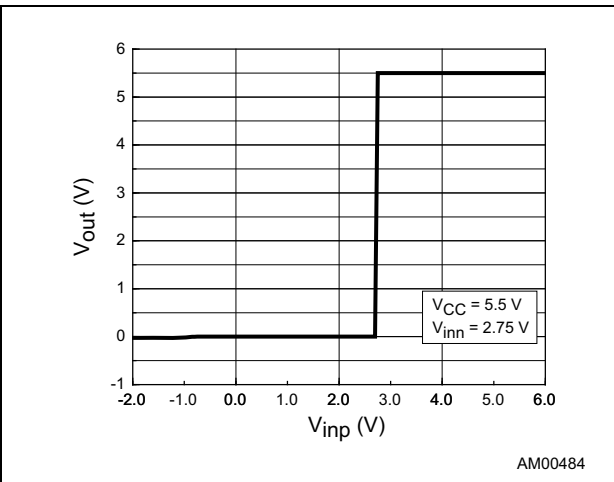


Figure 28. No phase reversal



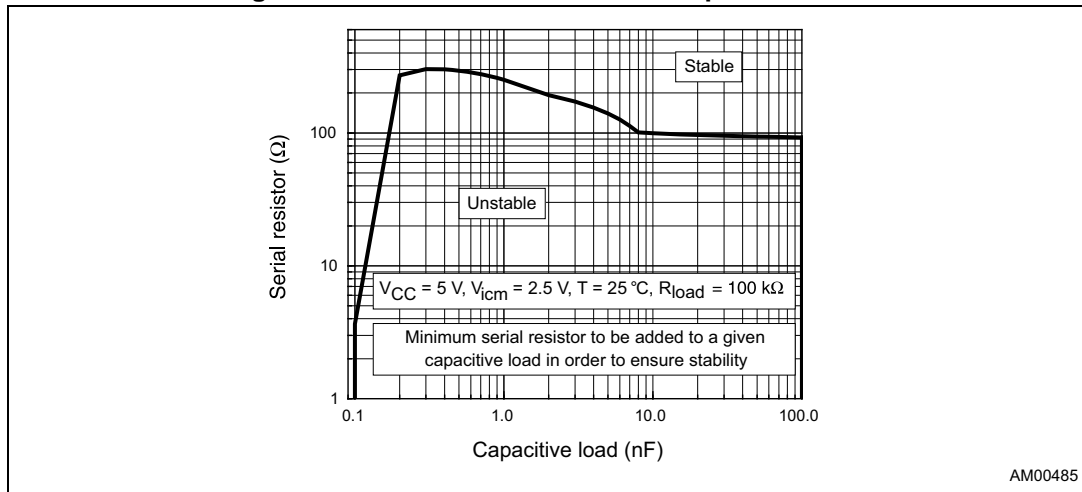
### 4.4 Rail-to-rail output

The operational amplifier output levels can go close to the rails: 35 mV maximum above and below the rail when connected to a 10 kΩ resistive load to  $V_{CC}/2$ .

### 4.5 Driving resistive and capacitive loads

To drive high capacitive loads, adding an in series resistor at the output can improve the stability of the device (see [Figure 29](#) for the recommended in series value). Once the in series resistor has been selected, the stability of the circuit should be tested on the bench and simulated with simulation models. The  $R_{load}$  is placed in parallel with the capacitive load. The  $R_{load}$  and the in series resistor create a voltage divider which introduces an error proportional to the ratio  $R_s/R_{load}$ . By keeping  $R_s$  as low as possible, this error is generally negligible.

Figure 29. In series resistor versus capacitive load



### 4.6 Input offset voltage drift over temperature

The maximum input voltage drift over the temperature variation is defined as the offset variation related to offset value measured at 25 °C. The operational amplifier is one of the main circuits of the signal conditioning chain, and the amplifier input offset is a major contributor to the chain accuracy. The signal chain accuracy at 25 °C can be compensated during production at application level. The maximum input voltage drift over temperature enables the system designer to anticipate the effect of temperature variations.

The maximum input voltage drift over temperature is computed using [Equation 1](#).

#### Equation 1

$$\frac{\Delta V_{io}}{\Delta T} = \max \left| \frac{V_{io}(T) - V_{io}(25^\circ\text{C})}{T - 25^\circ\text{C}} \right|$$

with  $T = -40\text{ }^\circ\text{C}$  and  $125\text{ }^\circ\text{C}$ .

The datasheet maximum value is guaranteed by a measurement on a representative sample size ensuring a  $C_{pk}$  (process capability index) greater than 1.33.

## 4.7 Long term input offset voltage drift

To evaluate product reliability, two types of stress acceleration are used:

- Voltage acceleration, by changing the applied voltage
- Temperature acceleration, by changing the die temperature (below the maximum junction temperature allowed by the technology) with the ambient temperature.

The voltage acceleration has been defined based on JEDEC results, and is defined using [Equation 2](#).

### Equation 2

$$A_{FV} = e^{\beta \cdot (V_S - V_U)}$$

Where:

$A_{FV}$  is the voltage acceleration factor

$\beta$  is the voltage acceleration constant in  $1/V$ , constant technology parameter ( $\beta = 1$ )

$V_S$  is the stress voltage used for the accelerated test

$V_U$  is the voltage used for the application

The temperature acceleration is driven by the Arrhenius model, and is defined in [Equation 3](#).

### Equation 3

$$A_{FT} = e^{\frac{E_a}{k} \cdot \left( \frac{1}{T_U} - \frac{1}{T_S} \right)}$$

Where:

$A_{FT}$  is the temperature acceleration factor

$E_a$  is the activation energy of the technology based on the failure rate

$k$  is the Boltzmann constant ( $8.6173 \times 10^{-5} \text{ eV} \cdot \text{K}^{-1}$ )

$T_U$  is the temperature of the die when  $V_U$  is used (K)

$T_S$  is the temperature of the die under temperature stress (K)

The final acceleration factor,  $A_F$ , is the multiplication of the voltage acceleration factor and the temperature acceleration factor ([Equation 4](#)).

### Equation 4

$$A_F = A_{FT} \times A_{FV}$$

$A_F$  is calculated using the temperature and voltage defined in the mission profile of the product. The  $A_F$  value can then be used in [Equation 5](#) to calculate the number of months of use equivalent to 1000 hours of reliable stress duration.



**Equation 5**

$$\text{Months} = A_F \times 1000 \text{ h} \times 12 \text{ months} / (24 \text{ h} \times 365.25 \text{ days})$$

To evaluate the op-amp reliability, a follower stress condition is used where  $V_{CC}$  is defined as a function of the maximum operating voltage and the absolute maximum rating (as recommended by JEDEC rules).

The  $V_{io}$  drift (in  $\mu\text{V}$ ) of the product after 1000 h of stress is tracked with parameters at different measurement conditions (see [Equation 6](#)).

**Equation 6**

$$V_{CC} = \max V_{op} \text{ with } V_{icm} = V_{CC} / 2$$

The long term drift parameter ( $\Delta V_{io}$ ), estimating the reliability performance of the product, is obtained using the ratio of the  $V_{io}$  (input offset voltage value) drift over the square root of the calculated number of months ([Equation 7](#)).

**Equation 7**

$$\Delta V_{io} = \frac{V_{io} \text{ drift}}{\sqrt{(\text{months})}}$$

where  $V_{io}$  drift is the measured drift value in the specified test conditions after 1000 h stress duration.

**4.8 PCB layouts**

For correct operation, it is advised to add 10 nF decoupling capacitors as close as possible to the power supply pins.

**4.9 Macromodel**

Accurate macromodels of the TSV52x, TSV52xA devices are available on STMicroelectronics™ website at [www.st.com](http://www.st.com). These models are a trade-off between accuracy and complexity (that is, time simulation) of the TSV52x, TSV52xA operational amplifiers. They emulate the nominal performance of a typical device within the specified operating conditions mentioned in the datasheet. They also help to validate a design approach and to select the appropriate operational amplifier, *but they do not replace on-board measurements*.

## 5 Package information

In order to meet environmental requirements, ST offers these devices in different grades of ECOPACK® packages, depending on their level of environmental compliance. ECOPACK specifications, grade definitions and product status are available at: [www.st.com](http://www.st.com). ECOPACK is an ST trademark.

### 5.1 SC705 package information

Figure 30. SC70-5 package outline

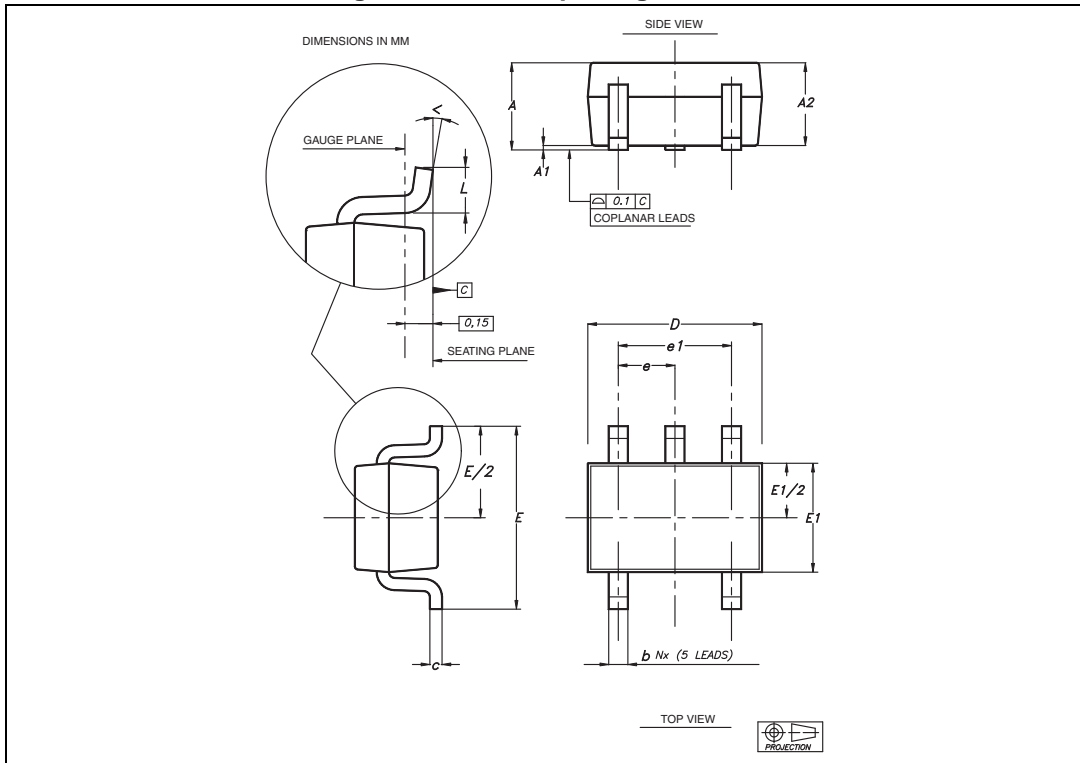


Table 7. SC70-5 package mechanical data

Ref	Dimensions					
	Millimeters			Inches		
	Min.	Typ.	Max.	Min.	Typ.	Max.
A	0.80		1.10	0.032		0.043
A1	0		0.10			0.004
A2	0.80	0.90	1.00	0.032	0.035	0.039
b	0.15		0.30	0.006		0.012
c	0.10		0.22	0.004		0.009
D	1.80	2.00	2.20	0.071	0.079	0.087
E	1.80	2.10	2.40	0.071	0.083	0.094
E1	1.15	1.25	1.35	0.045	0.049	0.053
e		0.65			0.025	
e1		1.30			0.051	
L	0.26	0.36	0.46	0.010	0.014	0.018
$\alpha$	0°		8°			

## 5.2 DFN8 2x2 package information

Figure 31. DFN8 2x2x0.6, 8 pitch, 0.5 mm package outline

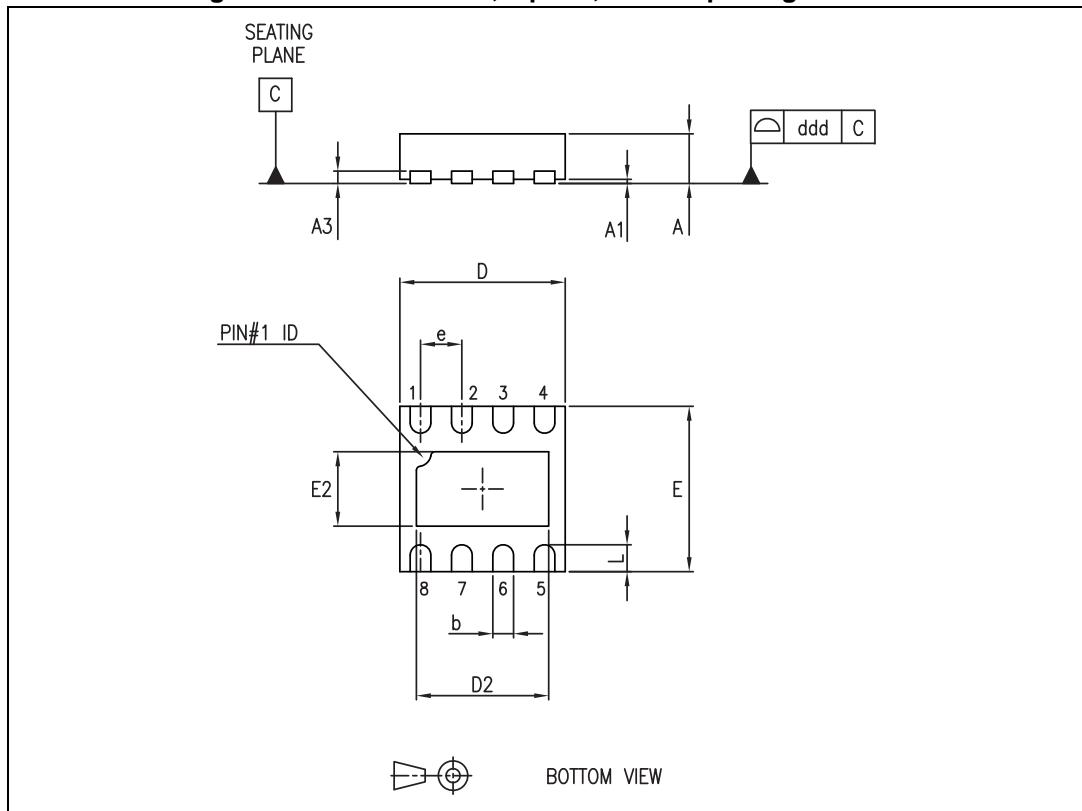
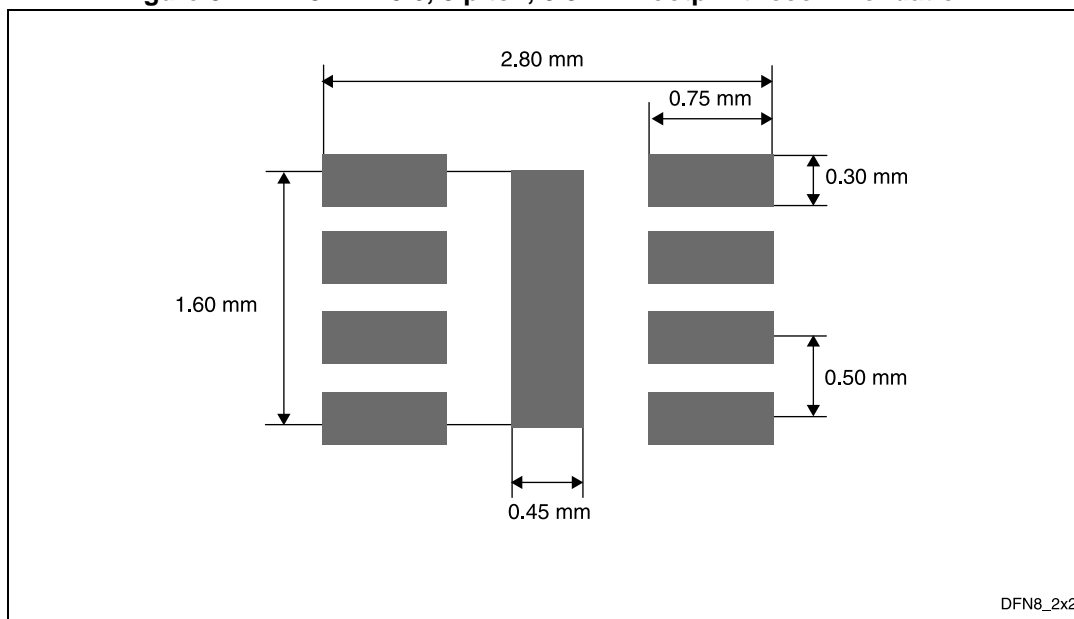


Table 8. DFN8 2x2x0.6, 8 pitch, 0.5 mm package mechanical data

Ref.	Dimensions					
	Millimeters			Inches		
	Min.	Typ.	Max.	Min.	Typ.	Max.
A	0.51	0.55	0.60	0.020	0.022	0.024
A1			0.05			0.002
A3		0.15			0.006	
b	0.18	0.25	0.30	0.007	0.010	0.012
D	1.85	2.00	2.15	0.073	0.079	0.085
D2	1.45	1.60	1.70	0.057	0.063	0.067
E	1.85	2.00	2.15	0.073	0.079	0.085
E2	0.75	0.90	1.00	0.030	0.035	0.039
e		0.50			0.020	
L			0.425			0.017
ddd			0.08			0.003

Figure 32. DFN8 2x2x0.6, 8 pitch, 0.5 mm footprint recommendation



### 5.3 MiniSO8 package information

Figure 33. MiniSO8 package outline

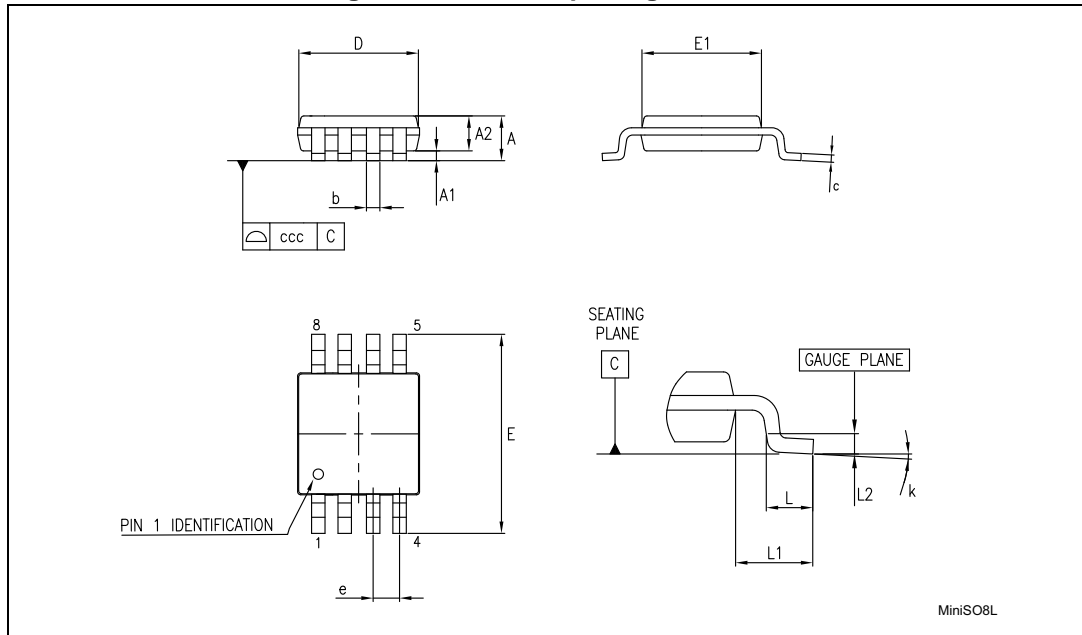


Table 9. MiniSO8 package mechanical data

Symbol	Dimensions					
	Millimeters			Inches		
	Min.	Typ.	Max.	Min.	Typ.	Max.
<b>A</b>			1.10			0.043
<b>A1</b>	0		0.15	0		0.006
<b>A2</b>	0.75	0.85	0.95	0.030	0.033	0.037
<b>b</b>	0.22		0.40	0.009		0.016
<b>c</b>	0.08		0.23	0.003		0.009
<b>D</b>	2.80	3.00	3.20	0.11	0.118	0.126
<b>E</b>	4.65	4.90	5.15	0.183	0.193	0.203
<b>E1</b>	2.80	3.00	3.10	0.11	0.118	0.122
<b>e</b>		0.65			0.026	
<b>L</b>	0.40	0.60	0.80	0.016	0.024	0.031
<b>L1</b>		0.95			0.037	
<b>L2</b>		0.25			0.010	
<b>k</b>	0°		8°	0°		8°
<b>ccc</b>			0.10			0.004

### 5.4 QFN16 3x3 package information

Figure 34. QFN16 3x3x0.9 mm, pad 1.7 package outline

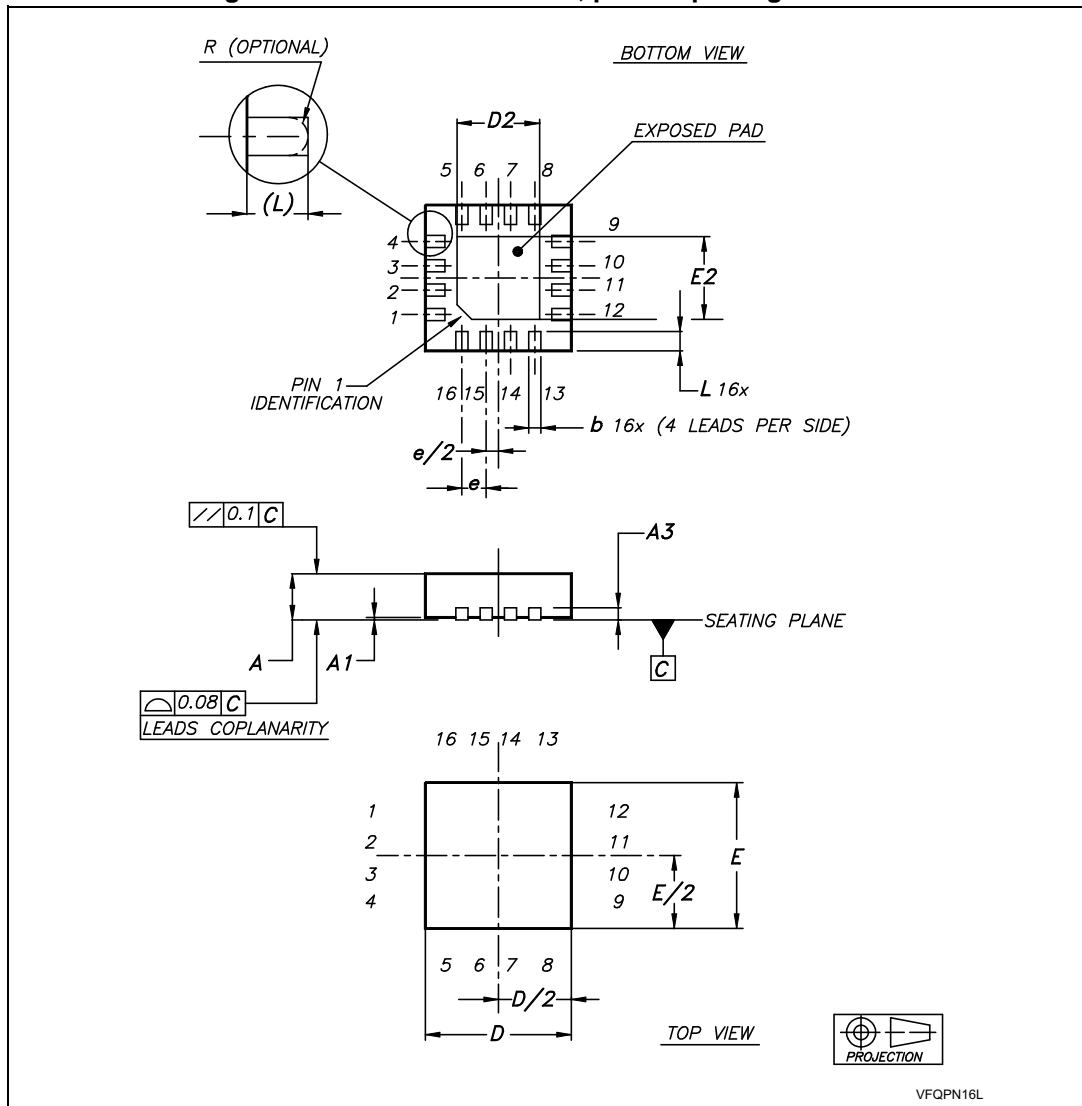
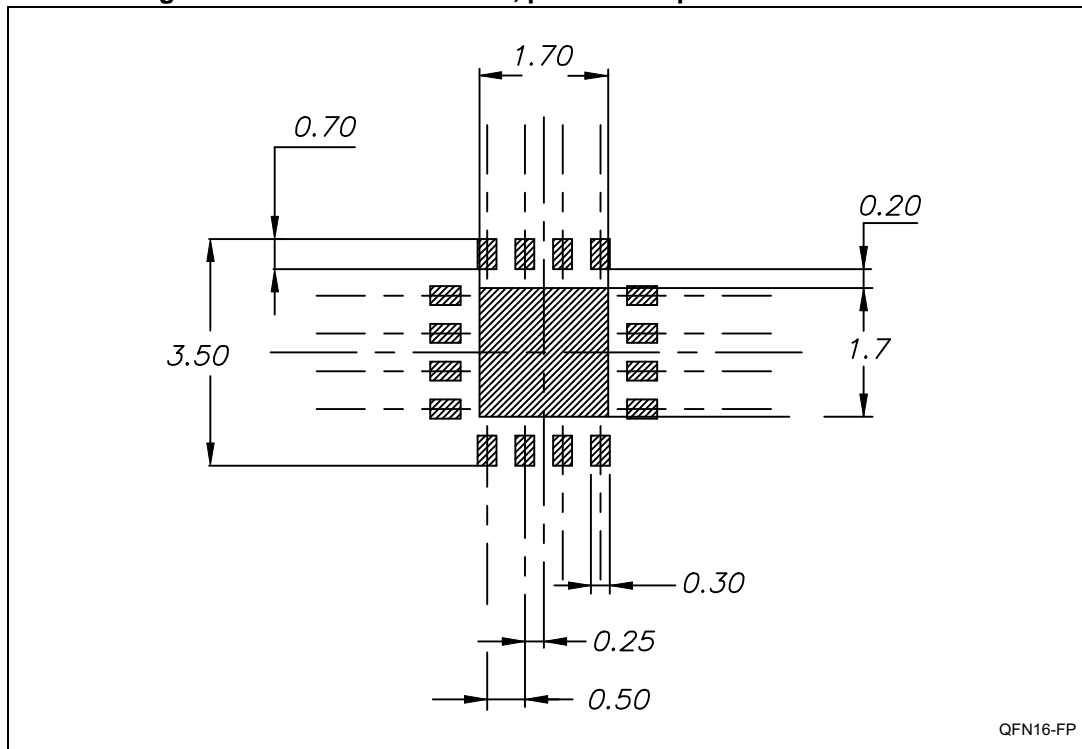


Table 10. QFN16 3x3x0.9 mm, pad 1.7 package mechanical data

Symbol	Dimensions					
	Millimeters			Inches		
	Nom.	Min.	Max.	Nom.	Min.	Max.
A	0.90	0.80	1.00	0.035	0.032	0.039
A1		0.00	0.05		0.000	0.002
A3	0.20			0.008		
b		0.18	0.30		0.007	0.012
D	3.00	2.90	3.10	0.118	0.114	0.122
D2		1.50	1.80		0.061	0.071
E	3.00	2.90	3.10	0.118	0.114	0.122
E2		1.50	1.80		0.061	0.071
e	0.50			0.020		
L		0.30	0.50		0.012	0.020

Figure 35. QFN16 3x3x0.9 mm, pad 1.7 footprint recommendation





### 5.5 TSSOP14 package information

Figure 36. TSSOP14 body 4.40 mm, lead pitch 0.65 mm package outline

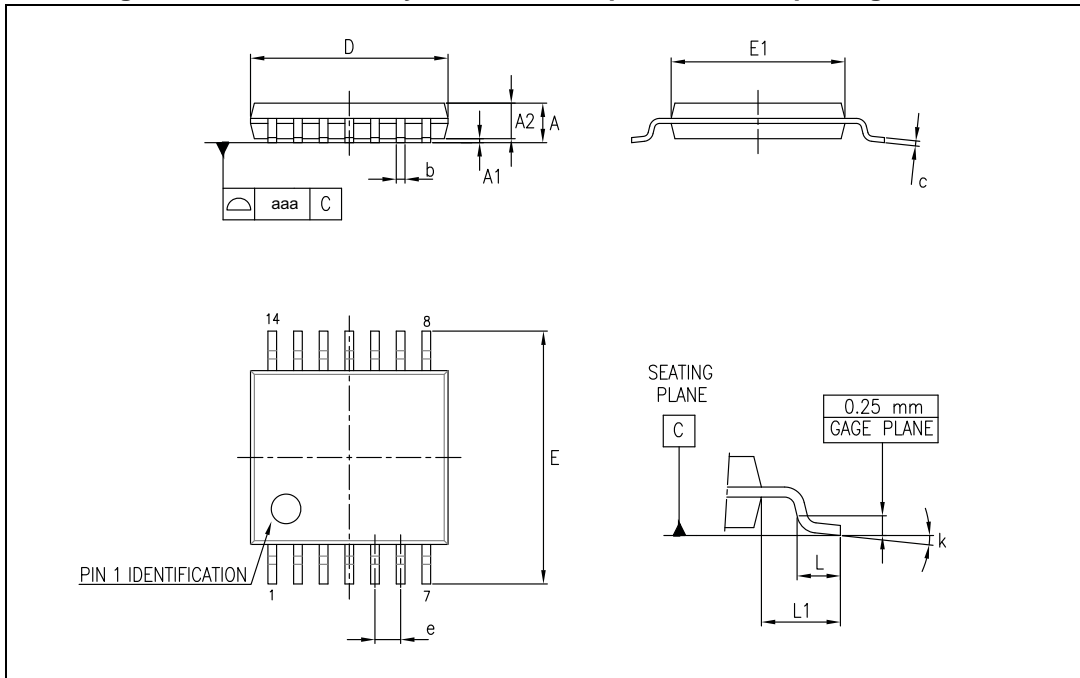


Table 11. TSSOP14 body 4.40 mm, lead pitch 0.65 mm package mechanical data

Symbol	Dimensions					
	Millimeters			Inches		
	Min.	Typ.	Max.	Min.	Typ.	Max.
A			1.20			0.047
A1	0.05		0.15	0.002	0.004	0.006
A2	0.80	1.00	1.05	0.031	0.039	0.041
b	0.19		0.30	0.007		0.012
c	0.09		0.20	0.004		0.0089
D	4.90	5.00	5.10	0.193	0.197	0.201
E	6.20	6.40	6.60	0.244	0.252	0.260
E1	4.30	4.40	4.50	0.169	0.173	0.176
e		0.65			0.0256 BSC	
L	0.45	0.60	0.75			
L1		1.00				
k	0°		8°	0°		8°
aaa			0.10	0.018	0.024	0.030

## 6 Ordering information

Table 12. Order codes

Order code	Temperature range	Package	Packing	Marking
TSV521ICT	-40 to 125 °C	SC70-5	Tape and reel	K1G
TSV522IQ2T		DFN8 2 x 2		K1G
TSV522IST		MiniSO8		K1G
TSV524IQ4T		QFN16 3 x 3		K1G
TSV524IPT		TSSOP14		TSV524
TSV522IYST	-40 to 125 °C Automotive grade <sup>(1)</sup>	MiniSO8		K1H
TSV524IYPT		TSSOP14		TSV524Y
TSV521AICT	-40 to 125 °C	SC70-5		K1K
TSV522AIQ2T		DFN8 2 x 2		K1K
TSV522AIST		MiniSO8		K1K
TSV524AIQ4T		QFN16 3 x 3		K1K
TSV524AIPT		TSSOP14		TSV524A
TSV522AIYST	-40 to 125 °C Automotive grade <sup>(1)</sup>	MiniSO8		K1L
TSV524AIYPT		TSSOP14		TSV524AY

1. Qualification and characterization according to AEC Q100 and Q003 or equivalent, advanced screening according to AEC Q001 and Q 002 or equivalent.

## 7 Revision history

Table 13. Document revision history

Date	Revision	Changes
19-Jun-2012	1	Initial release.
31-Jan-2014	2	Updated information of “ <i>Related products</i> ” “ <i>Figure 1: Pin connections for each package (top view)</i> ”: added footnote 1. “ <i>Section 4: Application information</i> ”: updated text to make it more readable “ <i>Table 12</i> ”: updated automotive footnotes.
12-Apr-2017	3	Updated <a href="#">Table 8</a> : “L” dimension changed from 0.5 mm to 0.425 mm.

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